

REMARKS ON THE REGULARITY OF QUASISLITS

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Abstract. A quasislit is the image of a vertical line segment $[0, iy]$, $y > 0$, under a quasiconformal homeomorphism of the upper half-plane fixing ∞ . Quasislits correspond precisely to curves generated by the Loewner equation with a driving function in the $\text{Lip}-\frac{1}{2}$ class. It is known that a quasislit is contained in a cone depending only on its Loewner driving function $\text{Lip}-\frac{1}{2}$ seminorm, σ . In this note we use the Loewner equation to give quantitative estimates on the opening angle of this cone in the maximal range $\sigma < 4$. The estimate is shown to be sharp for small σ . As consequences, we derive explicit Hölder exponents for $\sigma < 4$ as well as estimates on winding rates. We also relate quantitatively the $\text{Lip}-\frac{1}{2}$ seminorm with the quasiconformal dilatation and discuss the optimal regularity of quasislits achievable through reparametrization.

1. Introduction

A quasicircle is the image of the unit circle under a quasiconformal homeomorphism of the complex plane. Recall that $f \in W_{\text{loc}}^{1,2}$ is a k -quasiconformal map if it is a homeomorphic solution to the Beltrami equation, $\bar{\partial}f = \mu(z)\partial f$, where μ is measurable, complex valued, and such that $k := \|\mu\|_{\infty} < 1$ with corresponding maximal dilatation $(1+k)/(1-k)$. Many equivalent characterizations of quasicircles exist, both analytic and geometric, see e.g. [3]. For a particular characterization it is quite natural to ask how the geometry of the quasicircle depends quantitatively on the given data and how the data for different characterizations are related. For example, a k -quasicircle is the image of a k -quasiconformal map and a well-known theorem of Smirnov (motivated by a conjecture of Astala) states that the dimension of such a quasicircle is at most $1+k^2$ for k small.¹

In this note we will quantify some simple geometric features of quasicircles seen from the point of view of the Loewner equation. In this case it is more convenient to consider *quasislits*, that is, the image of a line segment $\{iy: 0 \leq y \leq y_0\}$ ($y_0 \in (0, \infty]$) under a quasiconformal homeomorphism $\mathbf{H} \rightarrow \mathbf{H}$, fixing ∞ . Every quasislit has a Loewner driving function in the $\text{Lip}-\frac{1}{2}$ class (see below) and conversely, every continuous function is the Loewner driving function for a quasislit if it is in the $\text{Lip}-\frac{1}{2}$ class with small seminorm. We will primarily be interested in understanding how properties of the curve depend quantitatively on this seminorm.

1.1. Curves, the Loewner equation, quasiarcs, and $\text{Lip}-\frac{1}{2}$. A curve is an equivalence class of continuous functions $[0, 1] \rightarrow \mathbf{C}$, where two representatives are

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¹Recent work of Ivrii shows however that this bound is not sharp, see Section 6.

in the same equivalence class if and only if each one can be obtained from the other by an increasing reparametrization. That is, γ_1 and γ_2 describe the same curve if and only if there exist increasing homeomorphisms $\alpha_1, \alpha_2: [0, 1] \rightarrow [0, 1]$ such that $\gamma_1 \circ \alpha_1(t) = \gamma_2 \circ \alpha_2(t)$, $t \in [0, 1]$. We will almost always consider curves with a particular parametrization chosen and refer to this as a curve as well.

Let $\lambda_t = \lambda(t)$, $t \in [0, 1]$, be a continuous real-valued function with $\lambda_0 = 0$, and consider for $z \in \mathbf{H} = \{z: \operatorname{Im} z > 0\}$ the solution $(f_t(z))$ to the Loewner PDE

$$(1.1) \quad \partial_t f_t(z) = -f'_t(z) \frac{2}{z - \lambda_t}, \quad f_0(z) = z.$$

The family (f_t) is called a Loewner chain and for each t , $f_t: \mathbf{H} \rightarrow H_t \subset \mathbf{H}$ is a conformal map normalized ‘hydrodynamically’ at ∞ by $f_t(z) = z - 2t/z + O(1/|z|^2)$. If λ_t is sufficiently well-behaved, the limit

$$(1.2) \quad \gamma(t) = \lim_{y \downarrow 0} f_t(\lambda_t + iy)$$

exists for every $t \in [0, 1]$, defines a continuous function $t \mapsto \gamma(t)$, and the simply connected domain H_t is the unbounded connected component of $\mathbf{H} \setminus \gamma[0, t]$. In this case, we say that the Loewner chain is generated by the curve γ . Viewed differently, the driving term λ generates the (chordal) Loewner curve $\gamma = \gamma^\lambda$ which comes equipped with a particular parametrization from the Loewner equation via (1.2) called the (half-plane) capacity parametrization. This process can be reversed, and starting from, e.g., a simple curve in $\overline{\mathbf{H}}$ meeting \mathbf{R} non-tangentially at its starting point, otherwise staying in \mathbf{H} , one can parametrize by capacity and recover its driving term from the hydrodynamically normalized uniformizing conformal maps $f_t^{-1}: \mathbf{H} \setminus \gamma[0, t] \rightarrow \mathbf{H}$.

Remark. Applying $z \mapsto z^2$, and ‘completing’ the resulting curve in union with \mathbf{R}_+ by a hyperbolic geodesic from the endpoint to ∞ , we can naturally think of a Loewner curve as part of a loop in $\hat{\mathbf{C}}$ through 0 and ∞ containing \mathbf{R}_+ as a sub-arc. In fact, any simple loop in $\hat{\mathbf{C}}$ (that does not necessarily contain \mathbf{R}_+ as a sub-arc) can be described by a two-sided Loewner equation, driven by a function defined on \mathbf{R} , see Section 6 of [16].

Here we will be interested in curves corresponding to driving terms in the $\operatorname{Lip}\text{-}\frac{1}{2}$ class, that is, functions satisfying

$$\|\lambda\|_{\frac{1}{2}} := \sup_{s \neq t} \frac{|\lambda_t - \lambda_s|}{|t - s|^{\frac{1}{2}}} < \infty.$$

For $\sigma > 0$, write

$$\Lambda_\sigma = \{\lambda: [0, 1] \rightarrow \mathbf{R} \mid \|\lambda\|_{\frac{1}{2}} \leq \sigma, \lambda_0 = 0\}.$$

The fundamental observation is due to Marshall and Rohde [11]: there exists C so that if $\lambda \in \Lambda_\sigma$ with $\sigma < C$ then γ^λ is a quasislit, in particular a simple curve. Lind showed that one can take $C = 4$ and that this is sharp in the sense that for each $\sigma \geq 4$, there exists a function $\lambda \in \Lambda_\sigma$ that does not even generate a curve [8]. Conversely, if $\gamma[0, t_0]$ is a quasislit generated by λ , then λ_t , $t \in [0, t_0]$, is in $\operatorname{Lip}\text{-}\frac{1}{2}$. See [9, 10, 13] for more. For later reference we note that an equivalent description of a quasislit is as a *quasiarc* (i.e., the image of a line segment under a quasiconformal homeomorphism of \mathbf{C}) in $\overline{\mathbf{H}}$ that meets \mathbf{R} non-tangentially at its starting point and otherwise stays in \mathbf{H} .

We may now define

$$\Gamma_\sigma = \{\gamma^\lambda \mid \lambda \in \Lambda_\sigma\}, \quad \sigma < 4$$

and in what follows, we will consider quasislits $\gamma \in \Gamma_\sigma$.

1.2. Results. For $\sigma < 4$ and $t \geq 0$, define

$$\mathcal{C}_{t,\sigma} = \sup_{\gamma \in \Gamma_\sigma} \frac{|\operatorname{Re}(\gamma(t))|}{\operatorname{Im}(\gamma(t))}.$$

This quantity measures the smallest opening angle required so that a cone at 0 contains any curve in Γ_σ . Our goal is to estimate $\mathcal{C}_{t,\sigma}$ and then derive regularity information from this bound. In order to state the result, fix $\sigma < 4$ and consider the following equation

$$(1.3) \quad e^x = \frac{\sqrt{16 - \sigma^2}}{\sqrt{16x^2 - \sigma^2(x + 1)^2}}.$$

The right-hand side of (1.3) is defined for $x > \sigma/(4 - \sigma)$. It is a continuous function which is strictly decreasing from ∞ to 0 as x ranges from $\sigma/(4 - \sigma)$ to ∞ . Therefore, the equation has a unique solution, which we will denote by $p(\sigma)$. Next, define

$$(1.4) \quad L_\sigma = \frac{\sigma}{\sqrt{16 - \sigma^2}}(1 + p(\sigma))e^{p(\sigma)}.$$

We have the following.

Theorem 1.1. *The following bounds hold uniformly in $t > 0$:*

(i) *If $0 < \sigma < 4$, then*

$$\mathcal{C}_{t,\sigma} \leq L_\sigma.$$

(ii) *If $0 < \sigma < \frac{8}{\pi}$, then*

$$\mathcal{C}_{t,\sigma} \leq \frac{\pi\sigma}{\sqrt{64 - \pi^2\sigma^2}}.$$

We prove (ii) in Section 3 and (i) in Section 4.

The function L_σ has the following expansion as $\sigma \rightarrow 0$:

$$(1.5) \quad L_\sigma = \frac{1}{4} \left(1 + \frac{1}{\mathcal{W}(1)} \right) \sigma + O(\sigma^3),$$

where $\mathcal{W}(\cdot)$ is the Lambert W function, so that $L_\sigma \sim 0.69\sigma$ as $\sigma \rightarrow 0$. Comparing with (ii) we see that the estimate in (i) is not sharp, but does provide the first non-trivial and explicit bound that holds for all $\sigma < 4$. On the other hand, by choosing the driving function $\lambda_t = \sigma\sqrt{t} \in \Lambda_\sigma$ we see that for all $t > 0$

$$\mathcal{C}_{t,\sigma} \geq \tan \left(\frac{\pi}{2} \frac{\sigma}{\sqrt{16 + \sigma^2}} \right),$$

see Example 4.12 in [7]. This shows that the estimate (ii) of Theorem 1.1 is sharp for small σ , and we have

$$\mathcal{C}_{t,\sigma} = \frac{\pi}{8}\sigma + O(\sigma^3).$$

Let us discuss some consequences of Theorem 1.1. Suppose $\gamma \in \Gamma_\sigma$ with $\sigma < 4$. Then by [13], Remark 4.2, there exists $\beta_\sigma \in (0, \frac{1}{2}]$, depending only on σ , such that $\gamma(t)$, $t \in [0, 1]$, parametrized by half-plane capacity is Hölder continuous with exponent β_σ . Time 0 is special for Loewner curves in \mathbf{H} parametrized by capacity: under weak assumptions, such curves are always Hölder- $\frac{1}{2}$ at $t = 0$, see, e.g., [6]. To achieve better regularity one can restrict attention to strictly positive times (or

consider driving terms that are constant during a small time interval starting with 0). Let us fix $\varepsilon > 0$ and given a Loewner curve γ we consider its optimal Hölder exponent for the capacity parametrization

$$\alpha(\gamma) = \sup\{\alpha : \gamma \text{ parametrized by capacity is Hölder-}\alpha \text{ on } [\varepsilon, 1]\}.$$

(If γ is not Hölder continuous in the capacity parametrization, by convention $\alpha(\gamma) = 0$.) Next, define the corresponding universal exponent for the class Γ_σ by

$$\alpha(\Gamma_\sigma) = \inf\{\alpha(\gamma) : \gamma \in \Gamma_\sigma\}.$$

It is not hard to show that if $\sigma < 2$, then one has $\alpha(\Gamma_\sigma) \geq 1 - \sigma^2/4$, see, e.g., [13], but this bound is not sharp and in the range $\sigma \in [2, 4)$ no estimate except $\alpha(\Gamma_\sigma) > 0$ was as far as we are aware known prior to this paper. This is in contrast with the much rougher setting of SLE where the sharp Hölder exponents for the capacity parametrization are known [6]. In this case, the randomness helps in the analysis, see below for further discussion.

Our first corollary is a quantitative estimate on $\alpha(\Gamma_\sigma)$ for $\sigma \in [0, 4)$.

Corollary 1.2. *If $\sigma < 4$, then*

$$(1.6) \quad \alpha(\Gamma_\sigma) \geq \frac{1}{1 + L_\sigma^2},$$

where L_σ is given by (1.4).

Our second corollary improves on the regularity estimate (1.6) (and the easy one $\alpha(\Gamma_\sigma) \geq 1 - \sigma^2/4$), in the smaller range $\sigma \in (0, 8/\pi)$.

Corollary 1.3. *If $\sigma < \frac{8}{\pi}$, then*

$$\alpha(\Gamma_\sigma) \geq 1 - \frac{\pi^2 \sigma^2}{64}.$$

The proofs of these corollaries are the same, and given in Section 5.1.

Even though the cone estimate is sharp for small σ , we do not expect the exponents of Corollary 1.3 to be sharp, see Section 5.1. Here we simply remark that choosing $\lambda_t = \sigma\sqrt{1-t}$ produces a curve with a spiral at $t = 1$ and a Hölder exponent of $1 - \sigma^2/16$. Indeed, this can be seen from direct computation using the representation given in Proposition 3.3 of [9], see, e.g., [12]. So $\alpha(\Gamma_\sigma) \leq 1 - \sigma^2/16$ and Rohde and Viklund have conjectured that this is in fact sharp for $\sigma \in [0, 4)$, but we currently have no proof of a matching lower bound.

Remark. Let $D(\Gamma_\sigma)$ be the maximal Hausdorff dimension of $\gamma \in \Gamma_\sigma$. Corollary 1.3 immediately implies

$$D(\Gamma_\sigma) \leq 1 + \pi^2 \sigma^2 / 64 + O(\sigma^4)$$

as $\sigma \rightarrow 0$.

Theorem 1.1 also gives non-trivial bounds on winding rates for the curve near the tip, when σ is small, see Section 5.2.

In Section 6 we make a few simple observations about the related problem of estimating the optimal Hölder regularity for quasiflits achievable through reparametrization and the relation between the quasiconformal dilatation parameter k and the semi-norm σ .

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2. Preliminaries

In this section we recall some basic properties of the Loewner differential equation and related objects which we will need in our analysis. Recall that $g_t = f_t^{-1}$ satisfies a family of ODEs,

$$(2.1) \quad \partial_t g_t(z) = \frac{2}{g_t(z) - \lambda_t}, \quad g_0(z) = z.$$

The family (g_t) is also called a Loewner chain. We will frequently write expressions of the form $dZ_t = a(t) dF(t)$ for functions a, F , which are to be interpreted as

$$\int_{t_0}^t dZ_s = \int_{t_0}^t a(s) dF(s).$$

Throughout, we let $\sigma < 4$ and assume that γ is generated by $\lambda \in \Lambda_\sigma$ and that $(g_t)_{t \geq 0}$ is the corresponding Loewner chain. To analyze f_t , which satisfies a PDE, it is convenient to use the reverse flow. For fixed $t > 0$ and $s \in [0, t]$, let $\beta_s^t = \lambda_t - \lambda_{t-s}$. If t is understood from the context, we instead write β_s . Then the following holds.

Lemma 2.1. Fix $t > 0$ and let \hat{h}_s satisfy the equation

$$(2.2) \quad d\hat{h}_s(z) = d\beta_s^t - \frac{2}{\hat{h}_s(z)} ds, \quad \hat{h}_0(z) = z,$$

for $s \in [0, t]$ and $z \in \mathbf{H}$. Then

$$\hat{h}_t(z) = f_t(\lambda_t + z).$$

Proof. Use (2.1) to see that the family of maps \hat{h}_s , defined by $\hat{h}_s(z) := g_{t-s}(f_t(z + \lambda_t)) - \lambda_{t-s}$ for $0 \leq s \leq t$, satisfies (2.2) and $\hat{h}_t(z) = f_t(\lambda_t + z)$. \square

Remark. Note that $\hat{h}_s(z)$ depends on t : if we let \tilde{h}_s solve (2.2) with driving function λ but for $t_1 \neq t$ in the same way, then it does not hold in general that $\hat{h}_s(z) = \tilde{h}_s(z)$ for $s < \min(t, t_1)$.

If we write $\hat{h}_s(z) = X_s(z) + iY_s(z)$ for $z = x + iy \in \mathbf{H}$, then (2.2) is equivalent to the equations

$$(2.3) \quad dX_s = d\beta_s - \frac{2X_s}{X_s^2 + Y_s^2} ds, \quad X_0 = x,$$

$$(2.4) \quad dY_s = \frac{2Y_s}{X_s^2 + Y_s^2} ds, \quad Y_0 = y.$$

Next, we recall the following from [13].

Lemma 2.2. [13, Theorem 3.1 and Lemma 2.1] *Suppose $\sigma < 4$. There exists a constant $c_\sigma > 0$, depending only on σ , such that for all $0 < y \leq 1$ and $s \geq 0$,*

$$(2.5) \quad \sqrt{y^2 + c_\sigma s} \leq Y_s(iy) \leq \sqrt{y^2 + 4s}.$$

Moreover,

$$(2.6) \quad |X_s(iy)| \leq \sup_{0 \leq r \leq s} |\beta_s - \beta_r|.$$

In order to estimate $|\operatorname{Re}(\gamma(t))|/\operatorname{Im}(\gamma(t))$ we will work with the process

$$W_s(z) = \frac{X_s(z)}{Y_s(z)}$$

and note that by (1.2)

$$(2.7) \quad \frac{\operatorname{Re}(\gamma(t))}{\operatorname{Im}(\gamma(t))} = \lim_{y \rightarrow 0} W_t(iy).$$

Moreover, we can rewrite (2.3) as

$$(2.8) \quad dX_s = d\beta_s - \frac{2W_s^2}{W_s^2 + 1} \frac{1}{X_s} ds, \quad X_0 = x.$$

When estimating the Hölder exponents and the winding rates for the curves, we need to estimate $|f'_t(\lambda_t + iy)|$ and $\arg f'_t(\lambda_t + iy)$, where differentiation is with respect to the spatial variable. Since $f'_t(\lambda_t + z) = \hat{h}'_t(z)$ the following formulas for $\hat{h}'_s(z)$ will be useful. For $s \in [0, t]$,

$$(2.9) \quad \begin{aligned} |\hat{h}'_s(z)| &= \exp \left\{ \int_0^s \frac{2(X_r^2 - Y_r^2)}{(X_r^2 + Y_r^2)^2} dr \right\} = \exp \left\{ \int_0^s \frac{X_r^2 - Y_r^2}{X_r^2 + Y_r^2} d \log Y_r \right\} \\ &= \exp \left\{ \int_0^s \frac{W_r^2 - 1}{W_r^2 + 1} d \log Y_r \right\}, \end{aligned}$$

$$(2.10) \quad \begin{aligned} \arg \hat{h}'_s(z) &= -4 \int_0^s \frac{X_r Y_r}{(X_r^2 + Y_r^2)^2} dr = -2 \int_0^s \frac{X_r Y_r}{X_r^2 + Y_r^2} d \log Y_r \\ &= -2 \int_0^s \frac{W_r}{W_r^2 + 1} d \log Y_r. \end{aligned}$$

2.1. Time reparametrization. By (2.4) and (2.5), it follows that $Y_s: [0, \infty) \rightarrow [y, \infty)$ is a strictly increasing, continuous function and hence that the function $(Y_s^2 - y^2): [0, \infty) \rightarrow [0, \infty)$ is a bijection. We denote by θ_s its inverse function, that is, $Y_{\theta_s}^2 - y^2 = s$ and denote the reparametrized functions by $\tilde{X}_s = X_{\theta_s}$, $\tilde{Y}_s = Y_{\theta_s} = \sqrt{y^2 + s}$ and $\tilde{W}_s = \tilde{X}_s/\sqrt{y^2 + s}$. Then we have

$$(2.11) \quad d\tilde{X}_s = d\beta_{\theta_s} - \frac{\tilde{X}_s}{2(y^2 + s)} ds, \quad \tilde{X}_0 = x,$$

$$(2.12) \quad d\theta_s = \frac{1}{4} \left(\frac{\tilde{X}_s^2}{y^2 + s} + 1 \right) ds, \quad \theta_0 = 0.$$

The advantage of this reparametrization is that it only leaves us with one unknown: \tilde{X} . This makes it easier to compare two solutions with different driving functions and will play a crucial role in the proof of Theorem 1.1.

3. A bound in the range $0 \leq \sigma < \frac{8}{\pi}$

This section is devoted to the proof of part (ii) of Theorem 1.1, and we will prove the following result, which will imply it.

Proposition 3.1. *Let $\lambda \in \Lambda_\sigma$ with $\sigma < \frac{8}{\pi}$, fix some $t > 0$ and define $\hat{h}_s(iy) = X_s(iy) + iY_s(iy)$ as the solution to (2.2). Then, for all $s \in [0, t]$ and $y > 0$, we have*

$$(3.1) \quad |W_s(iy)| = \left| \frac{X_s(iy)}{Y_s(iy)} \right| \leq \frac{\pi\sigma}{\sqrt{64 - \pi^2\sigma^2}}.$$

Proof. Using the product formula together with (2.3) and (2.4), we see that

$$(3.2) \quad d(X_s Y_s) = X_s dY_s + Y_s dX_s = Y_s d\beta_s.$$

The validity of (3.2), interpreted as Riemann–Stieltjes integrals, follows since the continuity and monotonicity of Y_s implies that it is of bounded variation. By partial integration, we have

$$(3.3) \quad X_s Y_s = \int_0^s Y_r d\beta_r = y\beta_s + \int_0^s (\beta_s - \beta_r) dY_r,$$

since $X_0 = 0$. Employing the time reparametrization of Section 2.1, using $d\tilde{Y}_r = dr/(2\sqrt{y^2 + r})$, (3.3) becomes

$$(3.4) \quad \tilde{X}_s \sqrt{y^2 + s} = y\beta_{\theta_s} + \int_0^s (\beta_{\theta_s} - \beta_{\theta_r}) \frac{dr}{2\sqrt{y^2 + r}}.$$

In order to prove the result, we shall bound $\tilde{W}_s = \tilde{X}_s/\tilde{Y}_s = \tilde{X}_s/\sqrt{y^2 + s}$. We have by (3.4)

$$(3.5) \quad \tilde{W}_s = \frac{y\beta_{\theta_s}}{y^2 + s} + \frac{1}{y^2 + s} \int_0^s (\beta_{\theta_s} - \beta_{\theta_r}) \frac{dr}{2\sqrt{y^2 + r}}.$$

We write $R_s = \sup_{r \leq s} |\tilde{W}_r|$ and note that by (2.12) and $\|\beta\|_{\frac{1}{2}} \leq \sigma$,

$$(3.6) \quad |\beta_{\theta_s}| \leq \sigma |\theta_s|^{\frac{1}{2}} \leq \frac{\sigma}{2} \sqrt{\int_0^s (\tilde{W}_u^2 + 1) du} \leq \frac{\sigma\sqrt{s}}{2} \sqrt{R_s^2 + 1}$$

and

$$(3.7) \quad \begin{aligned} \left| \int_0^s (\beta_{\theta_s} - \beta_{\theta_r}) \frac{dr}{2\sqrt{y^2 + r}} \right| &\leq \int_0^s \sigma \sqrt{\theta_s - \theta_r} \frac{dr}{2\sqrt{y^2 + r}} \\ &\leq \frac{\sigma}{2} \int_0^s \sqrt{\int_r^s (\tilde{W}_u^2 + 1) du} \frac{dr}{2\sqrt{y^2 + r}} \\ &\leq \frac{\sigma}{2} \sqrt{R_s^2 + 1} \int_0^s \sqrt{s - r} \frac{dr}{2\sqrt{y^2 + r}}. \end{aligned}$$

Next, we observe that

$$\begin{aligned}
 \int_0^s \sqrt{s-r} \frac{dr}{2\sqrt{y^2+r}} &= (y^2+s) \int_{\frac{y}{\sqrt{y^2+s}}}^1 \sqrt{1-u^2} du \\
 &= (y^2+s) \left(\frac{\pi}{4} - \int_0^{\frac{y}{\sqrt{y^2+s}}} \sqrt{1-u^2} du \right) \\
 (3.8) \qquad &= (y^2+s) \left(\frac{\pi}{4} - I \left(\frac{y}{\sqrt{y^2+s}} \right) \right),
 \end{aligned}$$

where $I(x) = \frac{1}{2} \arcsin(x) + \frac{1}{2}x\sqrt{1-x^2}$. Putting together equations (3.5)-(3.8), we get

$$\begin{aligned}
 |\tilde{W}_s| &\leq \frac{y|\beta_{\theta_s}|}{y^2+s} + \frac{1}{y^2+s} \left| \int_0^s (\beta_{\theta_s} - \beta_{\theta_r}) \frac{dr}{2\sqrt{y^2+r}} \right| \\
 &\leq \frac{\sigma\sqrt{R_s^2+1}}{2} \left(\frac{y\sqrt{s}}{y^2+s} + \frac{\pi}{4} - I \left(\frac{y}{\sqrt{y^2+s}} \right) \right).
 \end{aligned}$$

It can be checked that $I(y/\sqrt{y^2+s}) \geq y\sqrt{s}/(y^2+s)$, and hence

$$|\tilde{W}_s| \leq \frac{\pi\sigma\sqrt{R_s^2+1}}{8}.$$

This implies that $R_s \leq \pi\sigma\sqrt{R_s^2+1}/8$ and hence that

$$R_s \leq \frac{\pi\sigma}{\sqrt{64 - \pi^2\sigma^2}},$$

which proves the proposition. □

Now part (ii) of Theorem 1.1 follows by (2.7).

Remark. At first it might seem that the statement $|W_s(iy)| \leq K$ for $y > 0$ is stronger than $\mathcal{C}_{t,\sigma} \leq K$, but in fact, they are equivalent. Indeed, the curve $(f_t(\lambda_t + iy), y > 0)$ is the curve generated by the driving function $\lambda_s^* = \lambda_{s \wedge t}$, which is clearly a Lip- $\frac{1}{2}$ function. Thus, the condition $\mathcal{C}_{t,\sigma} \leq K$ implies that $|W_s(iy)| \leq K$.

4. A bound in the range $0 \leq \sigma < 4$

This section is devoted to the proof of the following proposition, which will give part (i) of Theorem 1.1, as in the previous section.

Proposition 4.1. *Let $\lambda \in \Lambda_\sigma$ with $\sigma < 4$, fix some $t > 0$ and define $\hat{h}_s(iy) = X_s(iy) + iY_s(iy)$ as the solution to (2.2). Then, for all $s \in [0, t]$ and $y > 0$, we have*

$$(4.1) \qquad |W_s(iy)| = \left| \frac{X_s(iy)}{Y_s(iy)} \right| \leq L_\sigma.$$

The proof of Proposition 4.1 requires more work than that of Proposition 3.1. In proving this, we shall employ the time-change of Section 2.1 and bound X_s and θ_s by comparing them to some properly chosen functions, using a version of the Grönwall inequality, which we now state and prove.

Proposition 4.2. (Grönwall’s inequality) *Let $F(t, x)$ be a bounded, continuous function, which is increasing and continuously differentiable in the variable x . Let U be a continuous function on an interval $[0, T]$ such that*

$$U_t \leq \int_0^t F(r, U_r) \, dr$$

for every $t \in [0, T]$. If V is a continuous function defined on $[0, T]$, satisfying

$$V_t = \int_0^t F(r, V_r) \, dr$$

for $t \in [0, T]$, then $U_t \leq V_t$ for all $t \in [0, T]$.

Proof. We have that

$$U_t - V_t \leq \int_0^t (F(r, U_r) - F(r, V_r)) \, dr = \int_0^t \Theta(r)(U_r - V_r) \, dr,$$

where, writing $F'(t, x) = \partial_x F(t, x)$,

$$\Theta(r) = \int_0^1 F'(r, pU_r + (1 - p)V_r) \, dp.$$

By the continuity of U, V and F' , together with the dominated convergence theorem, we have that Θ is continuous. Moreover, F is increasing, that is, F' is nonnegative and it thus follows that Θ is nonnegative. Hence, the claim follows from the standard Grönwall inequality, since $U_0 - V_0 \leq 0$. \square

Remark. We can actually relax the assumptions on F somewhat and allow it to blow up at a point, say 0. Then V_t still dominates U_t , at least until the first time U hits 0. More precisely, the following holds by the very same proof. Let $t_U^\delta = \inf\{t \in [0, T]: U_t = \delta\}$ and $t_V^\delta = \inf\{t \in [0, T]: V_t = \delta\}$. Assume that for each t , $F(t, x)$ is increasing and continuously differentiable on $(0, \infty)$ in the variable x . In particular, $F'(t, x)$ is bounded on every compact subset of $[0, \infty) \times (0, \infty)$. If U_t and V_t are continuous,

$$U_t \leq U_0 + \int_0^t F(r, U_r) \, dr$$

for $t < t_U^0$,

$$V_t = V_0 + \int_0^t F(r, V_r) \, dr$$

for $t < t_V^0$ and $U_0 \leq V_0$, then for each $0 < \delta < U_0$ it holds that for all $t < \min(t_U^\delta, t_V^\delta)$, $U_t \leq V_t$. Moreover, this implies that $t_U^\delta \leq t_V^\delta$.

We now discuss the bound on X_s . Consider (2.8) and note that $W_s^2/(W_s^2 + 1) \leq 1$ for all s and that $\beta \in \Lambda_\sigma$. Hence, it makes sense to compare X_s with solutions to the equation

$$(4.2) \quad dZ_s = \sigma \, d\sqrt{s} - \frac{c}{Z_s} \, ds, \quad Z_0 = z_0,$$

We will carry out this analysis for functions X_s that have strayed from 0, and hence, by symmetry, it will only be necessary for us to consider solutions to (4.2) started from $z_0 > 0$. The solution of (4.2) depends heavily on the value of c and we shall only need the solution for $c = \sigma^2/8$, as will be seen later.

Lemma 4.3. *The solution, Z_s , to (4.2) with $c = \sigma^2/8$ and $z_0 > 0$ exists for all $s \geq 0$ and is given by*

$$(4.3) \quad Z_s = \frac{\sigma\sqrt{s}}{2} + z_0 \exp \left\{ \mathcal{W} \left(\frac{\sigma\sqrt{s}}{2z_0} \right) \right\},$$

where \mathcal{W} is the Lambert \mathcal{W} function, that is, the nonnegative solution to the equation

$$\mathcal{W}(x)e^{\mathcal{W}(x)} = x.$$

Proof. First, we note that $\mathcal{W}(0) = 0$ implies that $Z_0 = z_0$. Next, using that

$$\frac{d\mathcal{W}}{dx}(x) = \frac{1}{1 + \mathcal{W}(x)} e^{-\mathcal{W}(x)},$$

we have

$$\begin{aligned} \frac{dZ_s}{ds} &= \frac{\sigma}{4\sqrt{s}} + \frac{1}{1 + \mathcal{W} \left(\frac{\sigma\sqrt{s}}{2z_0} \right)} \frac{\sigma}{4\sqrt{s}} = \frac{\sigma}{2\sqrt{s}} - \frac{\sigma}{4\sqrt{s}} \frac{\mathcal{W} \left(\frac{\sigma\sqrt{s}}{2z_0} \right)}{1 + \mathcal{W} \left(\frac{\sigma\sqrt{s}}{2z_0} \right)} \\ &= \frac{\sigma}{2\sqrt{s}} - \frac{\sigma}{4\sqrt{s}} \frac{1}{1 + \frac{2z_0}{\sigma\sqrt{s}} \exp \left(\mathcal{W} \left(\frac{\sigma\sqrt{s}}{2z_0} \right) \right)} \\ &= \frac{\sigma}{2\sqrt{s}} - \frac{\sigma^2}{8} \frac{1}{\frac{\sigma\sqrt{s}}{2} + z_0 \exp \left(\mathcal{W} \left(\frac{\sigma\sqrt{s}}{2z_0} \right) \right)} = \frac{\sigma}{2\sqrt{s}} - \frac{\sigma^2}{8} \frac{1}{Z_s}, \end{aligned}$$

and thus we are done. □

We now turn to the bound for θ_s . For $x_0 > 0$ and $\sigma < 4$ we define the following function

$$(4.4) \quad H_{x_0}(x) = \left(\frac{\sigma\sqrt{x}}{2} + x_0 \exp \left\{ \mathcal{W} \left(\frac{\sigma\sqrt{x}}{2x_0} \right) \right\} \right)^2 = \frac{\sigma^2 x}{4} \left(1 + \frac{1}{\mathcal{W} \left(\frac{\sigma\sqrt{x}}{2x_0} \right)} \right)^2.$$

For $\kappa \in (\frac{\sigma^2}{4}, 4)$, let $M = M(\kappa)$ be such that

$$(4.5) \quad \frac{\sigma^2}{4} \left(1 + \frac{1}{\mathcal{W} \left(\frac{\sigma\sqrt{M}}{2x_0} \right)} \right)^2 = \kappa.$$

Since \mathcal{W} is an increasing function, it follows that $H_{x_0}(x) \leq \kappa x$ for $x \geq M$.

Lemma 4.4. *Fix $x_0, y_0 > 0$ and $\sigma < 4$ and let V_s denote the solution to the differential equation*

$$(4.6) \quad \frac{dV}{ds} = \frac{1}{4} \frac{H_{x_0}(V_s)}{y_0^2 + s} + \frac{1}{4}, \quad V_0 = 0.$$

Then, for any $\kappa \in (\frac{\sigma^2}{4}, 4)$,

$$V_s \leq \max \left(\frac{M}{y_0^2}, \frac{1}{4 - \kappa} \right) (y_0^2 + s),$$

where M and κ are related as in (4.5).

Proof. By (4.6), V is continuous and strictly increasing to ∞ . Thus $\tau = \inf\{s > 0: V_s \geq M\}$ is finite and for $s \leq \tau$, $V_s \leq M$. For $s > \tau$, we have that

$$\frac{dV_s}{ds} \leq \frac{\kappa}{4} \frac{V_s}{y_0^2 + s} + \frac{1}{4},$$

since $H_{x_0}(x) \leq \kappa x$ for $x \geq M$ and thus

$$V_s - V_\tau \leq \int_\tau^s \left(\frac{\kappa}{4} \frac{V_r}{y_0^2 + r} + \frac{1}{4} \right) dr.$$

Let N_s be the solution to the differential equation

$$\frac{dN_s}{ds} = \frac{\kappa}{4} \frac{N_s}{y_0^2 + s} + \frac{1}{4}, \quad s > \tau,$$

given N_τ . Then for $s > \tau$,

$$N_s = N_\tau \left(\frac{y_0^2 + s}{y_0^2 + \tau} \right)^{\frac{\kappa}{4}} + \frac{1}{4 - \kappa} (y_0^2 + s) - \frac{1}{4 - \kappa} (y_0^2 + s)^{\frac{\kappa}{4}} (y_0^2 + \tau)^{1 - \frac{\kappa}{4}},$$

and by Proposition 4.2,

$$V_s \leq V_\tau \left(\frac{y_0^2 + s}{y_0^2 + \tau} \right)^{\frac{\kappa}{4}} + \frac{1}{4 - \kappa} (y_0^2 + s) - \frac{1}{4 - \kappa} (y_0^2 + s)^{\frac{\kappa}{4}} (y_0^2 + \tau)^{1 - \frac{\kappa}{4}}.$$

Thus,

$$\frac{V_s}{y_0^2 + s} - \frac{1}{4 - \kappa} \leq \left(\frac{y_0^2 + s}{y_0^2 + \tau} \right)^{\frac{\kappa}{4} - 1} \left(\frac{V_\tau}{y_0^2 + \tau} - \frac{1}{4 - \kappa} \right).$$

Since $y_0^2 + \tau \leq y_0^2 + s$, this implies that either

$$\frac{V_s}{y_0^2 + s} - \frac{1}{4 - \kappa} \leq 0 \quad \text{or} \quad \frac{V_s}{y_0^2 + s} \leq \frac{V_\tau}{y_0^2 + \tau} \leq \frac{M}{y_0^2}.$$

Thus we have that for $s > \tau$,

$$V_s \leq \max \left(\frac{M}{y_0^2}, \frac{1}{4 - \kappa} \right) (y_0^2 + s)$$

which, together with the bound $V_s \leq M$ for $s \leq \tau$, concludes the proof. □

We are now ready to prove Proposition 4.1.

Proof of Proposition 4.1. Fix $\sigma < 4$ and $t > 0$ and let $K_\sigma = \sigma/\sqrt{16 - \sigma^2}$. If $|W_s| \leq K_\sigma$ for all $s \leq t$, we are done, since $K_\sigma \leq L_\sigma$. Assume the contrary and let $s_1 > 0$ be such that $|W_{s_1}| > K_\sigma$. By symmetry, we may assume that $W_{s_1} > 0$. Let $s_0 = \sup\{s < s_1: W_s \leq K_\sigma\}$ and write $(\widehat{X}_s, \widehat{Y}_s) := (X_{s_0+s}, Y_{s_0+s})$ for $s \in [0, s_1 - s_0]$. Then, by (2.8),

$$\widehat{X}_s = \widehat{X}_0 + \beta_{s_0+s} - \beta_{s_0} - \int_0^s \frac{2W_{s_0+r}^2}{W_{s_0+r}^2 + 1} \frac{1}{\widehat{X}_r} dr \leq \widehat{X}_0 + \sigma\sqrt{s} - \frac{\sigma^2}{8} \int_0^s \frac{1}{\widehat{X}_r} dr,$$

since $w \mapsto w^2/(w^2 + 1)$ is an increasing function and $W_{s_0+r} \geq K_\sigma$ for $r \in [0, s_1 - s_0]$. By the remark after Proposition 4.2, together with Lemma 4.3,

$$(4.7) \quad \widehat{X}_s \leq \frac{\sigma\sqrt{s}}{2} + \widehat{X}_0 \exp \left\{ \mathcal{W} \left(\frac{\sigma\sqrt{s}}{2\widehat{X}_0} \right) \right\}.$$

Next, we note that

$$d\widehat{Y}_s^2 = \frac{4\widehat{Y}_s^2}{\widehat{X}_s^2 + \widehat{Y}_s^2} ds, \quad \widehat{Y}_0 = Y_{s_0}.$$

Reparametrizing as in Section 2.1, that is, defining θ_s as the inverse function of $\widehat{Y}_s^2 - Y_{s_0}^2$, we have

$$\theta_s = \frac{1}{4} \int_0^s \left(\frac{\widehat{X}_{\theta_r}^2}{Y_{s_0}^2 + r} + 1 \right) dr \leq \frac{1}{4} \int_0^s \left(\frac{H_{X_{s_0}}(\theta_r)}{Y_{s_0}^2 + r} + 1 \right) dr$$

where $H_{X_{s_0}}$ is defined as in (4.4). Thus, by Proposition 4.2, $\theta_s \leq V_s$ where V_s is the solution to (4.6) with $(x_0, y_0) = (X_{s_0}, Y_{s_0})$. By Lemma 4.4, we have

$$(4.8) \quad \theta_s \leq \max \left(\frac{M}{Y_{s_0}^2}, \frac{1}{4 - \kappa} \right) (Y_{s_0}^2 + s),$$

where $\kappa \in (\frac{\sigma^2}{4}, 4)$ and $M = M(\kappa)$ is defined by (4.5). Moreover,

$$\frac{\widehat{X}_{\theta_s}^2}{\widehat{Y}_{\theta_s}^2} = \frac{\widehat{X}_{\theta_s}^2}{Y_{s_0}^2 + s} \leq \frac{H_{X_{s_0}}(\theta_s)}{Y_{s_0}^2 + s}.$$

If $\theta_s \leq M$, then

$$\frac{H_{X_{s_0}}(\theta_s)}{Y_{s_0}^2 + s} \leq \frac{H_{X_{s_0}}(M)}{Y_{s_0}^2 + s} = \frac{\kappa M}{Y_{s_0}^2 + s} \leq \frac{\kappa M}{Y_{s_0}^2}.$$

Recalling that $H_{X_{s_0}}(x) \leq \kappa x$ for $x \geq M$, we have that if $\theta_s > M$, then

$$\frac{H_{X_{s_0}}(\theta_s)}{Y_{s_0}^2 + s} \leq \frac{\kappa \theta_s}{Y_{s_0}^2 + s} \leq \max \left(\frac{\kappa M}{Y_{s_0}^2}, \frac{\kappa}{4 - \kappa} \right).$$

Thus,

$$(4.9) \quad \frac{|X_{s_1}|}{Y_{s_1}} \leq \max \left(\frac{\sqrt{\kappa} \sqrt{M}}{Y_{s_0}}, \frac{\sqrt{\kappa}}{\sqrt{4 - \kappa}} \right).$$

Finally, we minimize (4.9), as a function of κ . Note that this is achieved for κ such that

$$\frac{\kappa M(\kappa)}{Y_{s_0}^2} = \frac{\kappa}{4 - \kappa}.$$

Since $X_{s_0}/Y_{s_0} = K_\sigma$, we obtain L_σ as defined by (1.4), which concludes the proof. \square

5. Regularity and winding rates

5.1. Hölder exponents. This section proves Corollaries 1.2 and 1.3, that is, we estimate the Hölder exponents for the curve $\gamma \in \Gamma_\sigma$ depending on σ . The arguments given here are standard, but we choose to give short derivations here for the convenience of the reader. In this section, constants may vary between the lines, even though they are denoted in the same way.

Proof of Corollary 1.2 and Corollary 1.3. Fix $\sigma < 4$, $0 < y \leq 1$, $\varepsilon > 0$ and $\varepsilon \leq t \leq 1$ and let $s \in [0, y^2]$. First, we note that

$$(5.1) \quad \begin{aligned} |\gamma(t+s) - \gamma(t)| &\leq |\gamma(t+s) - f_{t+s}(\lambda_{t+s} + iy)| + |\gamma(t) - f_t(\lambda_t + iy)| \\ &+ |f_{t+s}(\lambda_{t+s} + iy) - f_{t+s}(\lambda_t + iy)| + |f_{t+s}(\lambda_t + iy) - f_t(\lambda_t + iy)|. \end{aligned}$$

The first two terms we bound as follows. Since $\gamma(t) = f_t(\lambda_t + i0^+)$, we have

$$|\gamma(t) - f_t(\lambda_t + iy)| \leq \int_0^y |f'_t(\lambda_t + ir)| dr.$$

Moreover, we let

$$(5.2) \quad m_\sigma = \begin{cases} \min\left(L_\sigma, \frac{\pi\sigma}{\sqrt{64-\pi^2\sigma^2}}\right), & \text{if } \sigma < \frac{8}{\pi}, \\ L_\sigma & \text{if } \sigma \geq \frac{8}{\pi}. \end{cases}$$

and write $\xi_\sigma = (m_\sigma^2 - 1)/(m_\sigma^2 + 1) \in (-1, 1)$. By (2.9) and the fact that the function $x \mapsto (x^2 - 1)/(x^2 + 1)$ is increasing on $(0, \infty)$ together with Proposition 3.1 and Proposition 4.1 we have that

$$(5.3) \quad |f'_t(\lambda_t + ir)| = \exp\left\{\int_0^t \frac{W_u^2 - 1}{W_u^2 + 1} d\log Y_u\right\} \leq Y_t^{\xi_\sigma} r^{-\xi_\sigma}.$$

By (2.5), we have that for $u \in [0, s]$,

$$Y_{t+u}^{\xi_\sigma} \leq C(\sigma, \varepsilon),$$

since $s, t \leq 1$ and therefore

$$\int_0^y |f'_t(\lambda_t + ir)| dr \leq C(\sigma, \varepsilon) \int_0^y r^{-\xi_\sigma} dr = \frac{C(\sigma, \varepsilon)}{1 - \xi_\sigma} y^{1-\xi_\sigma}.$$

The same statement holds with $t + s$ in place of t and thus we have a bound on the first two terms of (5.1). Let $I_{s,t}^y$ denote the line segment connecting $\lambda_t + iy$ to $\lambda_{t+s} + iy$. Using the distortion theorem, (5.3) and that $\sqrt{s} \leq y$, we have that

$$\begin{aligned} |f_{t+s}(\lambda_{t+s} + iy) - f_{t+s}(\lambda_t + iy)| &\leq |\lambda_{t+s} - \lambda_t| \max_{w \in I_{s,t}^y} |f'_{t+s}(w)| \leq \sigma\sqrt{s} \max_{w \in I_{s,t}^y} |f'_{t+s}(w)| \\ &\leq C(\sigma)y |f'_{t+s}(\lambda_{t+s} + iy)| \leq Cy^{1-\xi_\sigma}. \end{aligned}$$

Finally, since $s \in [0, y^2]$, Lemma 3.5 of [6] and (5.3) imply that

$$|f_{t+s}(\lambda_t + iy) - f_t(\lambda_t + iy)| \leq Cy |f'_t(\lambda_t + iy)| \leq Cy^{1-\xi_\sigma}.$$

Thus, by (5.1) and the above inequalities, letting $s = y^2$, we have

$$|\gamma(t+s) - \gamma(t)| \leq C(\sigma, \varepsilon) s^{\frac{1}{1+m_\sigma^2}},$$

that is, γ is Hölder continuous with exponent α for each

$$\alpha \leq \frac{1}{1+m_\sigma^2}$$

and this concludes the proof. □

Remark. We have seen that the Hölder exponent is determined by the behavior of the derivative near the tip of the curve, which in turn is estimated using (2.9). The derivative can be explicitly bounded if the reverse flow stays in a particular cone so that $\sup |W_r| \leq C$. However, the sharp behavior depends on the integrated values of $(W_r^2 - 1)/(W_r^2 + 1)$ and we expect that the optimal bound on the integral is strictly smaller than the integrated optimal L^∞ -bound. In the case of SLE, there is of course no almost sure L^∞ -bound, but the process W_r has an invariant distribution in an appropriately weighted measure, and (2.9) can be precisely estimated using this invariant distribution and an intermediate deviations argument, see [6]. In the case of a general Lip- $\frac{1}{2}$ function these techniques are not available.

5.2. Winding rates. Theorem 1.1 also easily implies estimates on the winding rate at the tip of the curve $\gamma \in \Gamma_\sigma$ depending on σ , that is, we obtain estimates on the growth rate of $|\arg f'_t(\lambda_t + iy)|$ as y tends to 0. Geometrically, this measures the winding of the hyperbolic geodesic from $\gamma(t)$ to ∞ in $\mathbf{H} \setminus \gamma([0, t])$, close to the tip $\gamma(t)$ when the geodesic is parametrized by harmonic measure. By (2.10) and (2.5) we have a trivial bound

$$|\arg f'_t(\lambda_t + iy)| \leq 2 \log \frac{Y_t}{y} \leq \log(y^2 + 4t) + 2 \log(y^{-1}),$$

since $2|W_s|/(W_s^2 + 1) \leq 1$. By the easy estimate $\mathcal{C}_{t,\sigma} \leq \sigma/\sqrt{4 - \sigma^2}$ of [13], we get a non-trivial bound in the case $\sigma < \sqrt{2}$. By virtue of Corollary 1.3, we have the following improvement for $\sigma < 4\sqrt{2}/\pi$.

Proposition 5.1. *Let $\gamma \in \Gamma_\sigma$ with $\sigma < 4\sqrt{2}/\pi$. Then*

$$|\arg f'_t(\lambda_t + iy)| \leq \frac{\pi\sigma\sqrt{64 - \pi^2\sigma^2}}{64} \log(y^2 + 4t) + \frac{\pi\sigma\sqrt{64 - \pi^2\sigma^2}}{32} \log y^{-1}$$

Proof. By (3.1) and since $\sigma < 4\sqrt{2}/\pi$, we have that

$$|W_s(iy)| \leq \frac{\pi\sigma}{\sqrt{64 - \pi^2\sigma^2}} < 1.$$

By (2.10), Proposition 3.1, Proposition 4.1, (2.5) and that the function $x \mapsto x/(x^2+1)$ is increasing on $[0, 1]$, we have that

$$\begin{aligned} |\arg f'_t(\lambda_t + iy)| &\leq 2 \int_0^t \frac{|W_r|}{W_r^2 + 1} d \log Y_r \leq 2 \frac{\pi\sigma\sqrt{64 - \pi^2\sigma^2}}{64} \log \left(\frac{Y_t}{y} \right) \\ &\leq \frac{\pi\sigma\sqrt{64 - \pi^2\sigma^2}}{64} \log(y^2 + 4t) + \frac{\pi\sigma\sqrt{64 - \pi^2\sigma^2}}{32} \log(y^{-1}) \end{aligned}$$

which is the desired estimate. □

6. Additional remarks

In this section we collect a few simple observations that follow essentially directly from known results. For a curve γ , let us consider the optimal Hölder exponent achievable through reparametrization:

$$\hat{\alpha}(\gamma) = \sup\{\alpha : \gamma \text{ can be reparametrized to be Hölder-}\alpha\}.$$

By Corollary 1.3, for small σ , we know that

$$\hat{\alpha}(\Gamma_\sigma) := \inf\{\hat{\alpha}(\gamma) : \gamma \in \Gamma_\sigma\} \geq 1 - \pi^2\sigma^2/64$$

which, as remarked, immediately gives an upper bound on the maximal dimension for $\gamma \in \Gamma_\sigma$. However, under weak regularity assumptions, satisfied by $\gamma \in \Gamma_\sigma$, the optimal estimate is equal to the maximal reciprocal Minkowski dimension. Recall that a k -quasiarc is the image of a line segment under a k -quasiconformal homeomorphism of \mathbf{C} .

Proposition 6.1. *Suppose γ is a quasiarc with Minkowski dimension d_M . Then*

$$(6.1) \quad \hat{\alpha}(\gamma) = d_M^{-1}.$$

In particular, if γ is a k -quasiarc, then

$$\hat{\alpha}(\gamma) \geq \frac{1}{1 + k^2}.$$

Remark. The second statement uses Smirnov’s result [14], but in fact, for small k , Ivrii’s recent stronger result [5] stating that the dimension of a k -quasiarc is at most $1 + \Sigma^2 k^2 + O(k^{8/3-\varepsilon})$ for small k , combined with Hedenmalm’s estimate $\Sigma < 1$ [4] gives a better bound for small k .

Sketch of proof. The first statement follows from the ideas of Section 2 of [1]. The second assertion follows from the first, combined with Smirnov’s result on the maximal Hausdorff dimension of a k -quasiarc, and the fact, due to Astala (see Theorem 1.5 of [2]), that the maximal Hausdorff dimension over the set of k -quasiarcs equals the corresponding maximal Minkowski dimension. (This is not true in general for a fixed quasiarc.) Let us sketch the proof of (6.1) following [1]. For a curve γ and $\delta > 0$, let $M(\gamma, \delta)$ be the minimal number of curve segments of diameter at most δ needed to cover γ . We first claim that if $M(\gamma, \delta) \lesssim \delta^{-r}$ then for any $r' > r$ there is a Hölder- $1/r'$ parametrization of γ . Indeed, choosing first any parametrization, $\gamma(s)$, $s \in [0, 1]$, not constant on any subinterval, we may define the following reparametrization

$$\tau(s) = \frac{\sum_n n^{-2} M(\gamma[0, s], 2^{-n}) 2^{-rn}}{\sum_n n^{-2} M(\gamma, 2^{-n}) 2^{-rn}}.$$

Note that the denominator is bounded. Suppose $\varepsilon > 0$ and $|\gamma(s_1) - \gamma(s_2)| \geq \varepsilon$. If $2^{-n} < \varepsilon$ and sufficiently small, then we have $M(\gamma[0, s_2], 2^{-n}) - M(\gamma[0, s_1], 2^{-n}) \geq 1$. Hence for all $\varepsilon > 0$ small enough,

$$\tau(s_2) - \tau(s_1) \geq C \sum_{n > -\log \varepsilon} n^{-2} 2^{-rn} \geq C' \varepsilon^{r'}.$$

On the other hand, we can estimate M in terms of d_M as follows: By the quasiarc property there is a constant $C_\gamma < \infty$ such that the following holds. Given $\delta > 0$, partition γ into segments of diameter $C_\gamma \delta$ by considering stopping times defined as follows: $t_0 = 0$ and then for $j = 1, 2, \dots, N_\delta$, $t_j = \inf\{t \geq t_{j-1} : |\gamma(t) - \gamma(t_{j-1})| \geq C_\gamma \delta\}$ (terminating if the end point of the curve is within distance $C_\gamma \delta$). Then given any cover of γ by balls of diameter δ , by the quasicircle property, any ball in this cover contains at most one of the partitioning points, $\{\gamma(t_j)\}$. Hence for any $r > d_M$, we obtain $M(\gamma, \delta) \leq N_\delta \lesssim \delta^{-r}$. \square

Given Proposition 6.1, we would like to relate k and σ quantitatively. Marshall and Rohde [11] show that these parameters are quantitatively related in the sense that $k \rightarrow 0$ as $\sigma \rightarrow 0$. In the other direction, taking $\lambda(t) = \sigma \sqrt{t}$ shows that one can not say anything for general quasiarcs, but if the dilatation of the quasiconformal homeomorphism of \mathbf{H} defining a quasislit tends to 1 (so that $k \rightarrow 0$), it does follow that $\sigma \rightarrow 0$. However, beyond these observations, no estimates appear to be available.

As was pointed out to us by Rohde, a recent result of Tran can be used to get an estimate for small σ . Let us sketch the argument. Fix $\lambda \in \Lambda_\sigma$ with $\sigma < 1/3$. Set $\tilde{\lambda} = \lambda/(3\|\lambda\|_{1/2})$ so that $\|\tilde{\lambda}\|_{1/2} = 1/3$. On the other hand, since $\tilde{\lambda} \in \Lambda_{1/3}$ we can use Theorem 1.3 of [15] to embed γ^λ in a holomorphic motion compatible with the Loewner equation in the following sense. For each $\tau \in \mathbf{D}$, it is possible to solve the Loewner equation (1.1) with the complex driving term, $t \mapsto \tau \tilde{\lambda}_t$. The solution extends to a conformal map $g_t: \hat{\mathbf{C}} \setminus L_t \rightarrow \hat{\mathbf{C}} \setminus R_t$, where L_t, R_t are both simple curves. The curve $L_t = L_t^\tau$ moves holomorphically with τ , and so if we write $S = [0, 2i]$, then there exists a holomorphic motion of S , $f: \mathbf{D} \times S \rightarrow \mathbf{C}$, such that $f(3\|\lambda\|_{1/2}, S) = \gamma^\lambda$ as a set. By the generalized λ -lemma, f extends to a holomorphic

motion of \mathbf{C} , $F: \mathbf{D} \times \mathbf{C} \rightarrow \mathbf{C}$, and for each $\tau \in \mathbf{D}$, $F(\tau, \cdot): \mathbf{C} \rightarrow \mathbf{C}$ is a quasiconformal homeomorphism of dilatation at most $(1 + |\tau|)/(1 - |\tau|)$. Setting $\tau = 3\|\lambda\|_{1/2}$ we conclude the following.

Proposition 6.2. *Suppose $\gamma \in \Gamma_\sigma$ with $\sigma < 1/3$. Then γ is a 3σ -quasiarc.*

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