

# Constructing uniform spaces

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**Abstract.** We exhibit geometric conditions that ensure a metric space is uniform.

## Sisätieyhtenäisten avaruuksien rakentaminen

**Tiivistelmä.** Esitämme joukon geometrisia ehtoja, jotka takaavat metrisen avaruuden sisätieyhtenäisyyden.

## 1. Introduction

Throughout this section  $X$  is a rectifiably connected non-complete locally complete metric space. These are the minimal requirements for  $X$  to support a *quasihyperbolic distance*  $k = k_X$ , and we dub  $X$  a *quasihyperbolic metric space*; see Section 2 for precise definitions.

Roughly speaking, such an  $X$  is a *uniform metric space* provided each pair of points can be joined by a path that moves away from the boundary of  $X$  and whose length is comparable to the distance between the points. See §2.B for a precise definition.

The class of Euclidean uniform domains was introduced by Martio and Sarvas in [MS79] and has proven to be invaluable in geometric function theory, potential theory, geometric group theory, and especially for the “analysis in metric spaces” program; e.g., see [Geh87, Väi88, Jon81, Aik04, Aik06, BS07, CT95, CGN00, Gre01, BHK01, HSX08]. A finitely connected proper subdomain of the plane is uniform if and only if each boundary component is either a point or a quasicircle, but in general there are no such simple geometric criterion for uniformity.

Given their fundamental importance, it seems worthwhile to investigate two questions.

- When can we “poke holes” in a uniform space and still have a uniform space?
- + When can we “fill in” some boundary points of a uniform space and keep uniformity?

As a warm up, we have the following result, similar to [Her11, Prop. 2.3]. While surely not surprising to those well versed in uniform space theory, our discussion employs some tools that may not be well known. Again, see §2.B for definitions.

**Theorem A.** *Let  $X$  be a quasihyperbolic metric space. Let  $o \in X$  be a fixed point and put  $X_\star := X \setminus \{o\}$ . If  $X_\star$  is  $C_\star$ -uniform, then for any  $C > C_\star$*

$$(1.1) \quad X \text{ is } C\text{-uniform and } C_1\text{-annular quasiconvex at } o$$

where  $C_1 = 2(C_\star + 1)$ . Conversely, if (1.1) holds, then  $X_\star$  is  $C_\star$ -uniform with  $C_\star = C_\star(C, C_1)$ .

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An open subspace  $\Omega$  of  $X$  is *uniformly collared* provided  $X$  is uniform and there are disjointed open sets  $U_i$  such that

$$B := X \setminus \Omega = \bigcup_i B_i \quad \text{where } B_i := B \cap U_i$$

and such that each *collar*  $\Omega_i := \Omega \cap U_i$  is a uniform space.<sup>1</sup> This terminology was introduced in the Euclidean setting by Astala and Heinonen in [AH88]; see also [HK91]. We say that  $\Omega$  is *uniformly collared with fat collars* provided it is uniformly collared and there is a positive constant  $\Phi$  such that

$$(1.2) \quad \frac{1}{\Phi} \operatorname{diam}(B_i) \leq \operatorname{dist}(B_i, \partial X) \leq \Phi \operatorname{dist}(B_i, \operatorname{bd} U_i).$$

**Theorem B.** *Let  $\Omega$  be an open subspace of a  $C_0$ -uniform space  $X$ . Suppose  $\Omega$  is uniformly collared with  $C_1$ -uniform  $\Phi$ -fat collars. Then  $\Omega$  is  $C$ -uniform with  $C = C(C_0, C_1, \Phi)$ .*

As an application of the above, we establish the following.

**Theorem C.** *Let  $X$  be a quasihyperbolic metric space. Let  $\Omega := X \setminus A$  where  $A \subset X$ . Assume there is a constant  $\kappa \in (0, 1)$  such that*

$$(1.3) \quad \forall a \neq b \text{ in } A, \quad k(a, b) \geq \kappa.$$

*If  $\Omega$  is  $C$ -uniform, then for any  $C_0 > C$*

$$(1.4) \quad X \text{ is } C_0\text{-uniform and } C_1\text{-annular quasiconvex at each } a \in A$$

*with  $C_1 = 2(C + 1)$ . Conversely, if both (1.4) and*

$$(1.5) \quad \forall a \in A, \quad \mathbf{B}\left(a; \frac{\kappa}{4C_0} \operatorname{dist}(a, \partial X)\right) \text{ is } C_2\text{-uniform}$$

*hold, then  $\Omega$  is  $C$ -uniform with  $C = C(C_0, C_1, C_2, \kappa)$ .*

A special case of Theorem C, with  $\kappa = 1/2$  and  $A \subset X$  a countable subset of a Banach space<sup>2</sup> uniform domain  $X$ , was proved in [HVW17]. Theorems B and C were established in the Euclidean setting in [Her89]; see also [Her87].

We can replace (1.3) by the (*a priori* stronger, but here equivalent) condition that for some positive constant  $v$ ,

$$\forall a \neq b \text{ in } A, \quad |a - b| \geq v \operatorname{dist}(a, \partial X).$$

The condition (1.5) can be relaxed, e.g., to asking that there exist an  $\varepsilon \in (0, \kappa/4C_0]$  such that for each  $a \in A$  there is a  $C_2$ -uniform ball  $\mathbf{B}(a; r_a)$  with  $r_a / \operatorname{dist}(a, \partial X) \in [\varepsilon, \kappa/4C_0]$ .

Our results inspire some natural questions.

- (A) When is a metric space annular quasiconvex?
- (B) What properties of a metric space ensure that its balls are uniform spaces?
- (C) Which properties of Euclidean uniformly collared spaces (e.g., see [HK91]) have metric space analogs?

Theorems A, B, C are established in §§3.A, 3.B, 3.C respectively.

<sup>1</sup>There should be a single uniformity constant for the collars.

<sup>2</sup>Banach spaces are annular quasiconvex at each point and balls are 2-uniform.

## 2. Metric space definitions

Our notation is relatively standard. We write  $C = C(D, \dots)$  to indicate a constant  $C$  that depends only on the data  $D, \dots$ . For real numbers  $r$  and  $s$ ,

$$r \wedge s := \min\{r, s\} \quad \text{and} \quad r \vee s := \max\{r, s\}.$$

**2.A. Metric space notation and terminology.** Throughout this section  $X$  is an arbitrary metric space with distance denoted  $|x - y|$ ; this is not meant to imply that  $X$  possesses any sort of linear or group structure. In this setting, all topological notions refer to the metric topology; here  $\text{cl}(A), \text{bd}(A), \text{int}(A)$  are the topological closure, boundary, interior (respectively) of  $A \subset X$ .

The open ball, sphere, closed ball of radius  $r$  centered at the point  $a \in X$  are

$$\begin{aligned} \text{B}(a; r) &:= \{x : |x - a| < r\}, & \text{S}(a; r) &:= \{x : |x - a| = r\}, \\ \text{B}[a; r] &:= \text{B}(a; r) \cup \text{S}(a; r). \end{aligned}$$

The closed annular ring centered at  $a$  with inner radius  $r$  and outer radius  $s$  is

$$\text{A}[a; r, s] := \text{B}[a; s] \setminus \text{B}(a; r) = \{x : r \leq |x - a| \leq s\}.$$

Recall that every metric space can be isometrically embedded into a complete metric space. We let  $\bar{X}$  denote the metric completion of the metric space  $X$ ; thus  $\bar{X}$  is the closure of the image of  $X$  under such an isometric embedding. We call  $\partial X := \bar{X} \setminus X$  the metric boundary of  $X$ . When  $X$  is non-complete,  $\delta(x) = \delta_X(x) := \text{dist}(x, \partial X)$  is the distance from a point  $x \in X$  to the boundary  $\partial X$  of  $X$ . Note that  $\partial X$  is closed in  $\bar{X}$  if and only if  $\delta(x) > 0$  for all  $x \in X$ ; e.g., this holds when  $X$  is locally compact.

When  $A \subset X$ , there is a natural embedding  $\bar{A} \hookrightarrow \bar{X}$  and  $\text{bd}(A) \subset \partial A$ . Here if  $A \subset X$  is open and  $X$  complete, then  $\partial A = \text{bd}(A)$ , but in general  $\bar{A} = \text{cl}(A)$  and  $\partial A = \overline{\text{bd}(A)} \setminus A$  where  $\overline{\text{cl}}$  and  $\overline{\text{bd}}$  denote topological closure and boundary in  $\bar{X}$ .

A metric space  $X$  is *locally complete* provided each point has an open neighborhood which is complete. When  $X$  is non-complete, this is equivalent to requiring that  $\delta(x) > 0$  for all  $x \in X$ , or,  $\partial X$  is closed in  $\bar{X}$ , or,  $X$  is open in  $\bar{X}$ .

**2.A.1. Paths, arcs, & length.** A *path in  $X$*  is a continuous map  $\mathbb{R} \supset I \xrightarrow{\gamma} X$  where  $I = I_\gamma$  is an interval (called the *parameter interval for  $\gamma$* ) that may be closed or open or neither and finite or infinite. The *trajectory* of such a path  $\gamma$  is  $|\gamma| := \gamma(I)$  which we call a *curve* and often denote by just  $\gamma$ . When  $I$  is closed and  $I \neq \mathbb{R}$ ,  $\partial\gamma := \gamma(\partial I)$  denotes the set of *endpoints of  $\gamma$*  and consists of one or two points depending on whether or not  $I$  is compact. For example, if  $I_\gamma = [u, v] \subset \mathbb{R}$ , then  $\partial\gamma = \{\gamma(u), \gamma(v)\}$ . When  $\partial\gamma = \{a, b\}$ , we write  $\gamma: a \curvearrowright b$  (*in  $X$* ) to indicate that  $\gamma$  is a path (in  $X$ ) with *initial point  $a$*  and *terminal point  $b$* ; this notation is meant to imply an orientation— $a$  precedes  $b$  on  $\gamma$ .

We call  $\gamma$  a *compact path* if its parameter interval  $I$  is compact. An *arc  $\alpha$*  is an injective compact path. Given points  $a, b \in |\alpha|$ , there are unique  $u, v \in I$  with  $\alpha(u) = a$ ,  $\alpha(v) = b$  and we write  $\alpha[a, b] := \alpha|_{[u, v]}$ . We also use this notation for a general path  $\gamma$ , but here  $\gamma[a, b]$  denotes the unique injective subpath of  $\gamma$  that joins  $a, b$  obtained by using the last time  $\gamma$  is at  $a$  up to the first time  $\gamma$  is at  $b$ .

When  $\alpha: a \curvearrowright b$  and  $\beta: b \curvearrowright c$  are paths that join  $a$  to  $b$  and  $b$  to  $c$  respectively,  $\alpha \star \beta$  denotes the concatenation of  $\alpha$  and  $\beta$ ; so  $\alpha \star \beta: a \curvearrowright c$ . Of course,  $|\alpha \star \beta| = |\alpha| \cup |\beta|$ . Also, the *reverse of  $\gamma$*  is the path  $\tilde{\gamma}$  defined by  $\tilde{\gamma}(t) := \gamma(1 - t)$  (when  $I_\gamma = [0, 1]$ ) and going from  $\gamma(1)$  to  $\gamma(0)$ . Of course,  $|\tilde{\gamma}| = |\gamma|$ .

Every compact path contains an arc with the same endpoints; see [Väi94].

The length of a compact path  $[0, 1] \xrightarrow{\gamma} X$  is defined in the usual way by

$$\ell(\gamma) := \sup \left\{ \sum_{i=1}^n |\gamma(t_i) - \gamma(t_{i-1})| \mid 0 = t_0 < t_1 < \cdots < t_n = 1 \right\},$$

$\gamma$  is *rectifiable* when  $\ell(\gamma) < \infty$ , and  $X$  is *rectifiably connected* provided each pair of points in  $X$  can be joined by a rectifiable path. Every rectifiable path can be parametrized with respect to its arclength [Väi71, p.5]. When  $\gamma$  is a rectifiable path, we tacitly assume its parameter interval is  $I_\gamma = [0, \ell(\gamma)]$  unless specifically stated otherwise.

Every rectifiably connected metric space  $X$  admits a natural *intrinsic* distance, its so-called (*inner*) *length distance* given by

$$l(a, b) := \inf \{ \ell(\gamma) \mid \gamma: a \rightsquigarrow b \text{ a rectifiable path in } X \}.$$

A metric space  $(X, |\cdot|)$  is a *length space* provided for all points  $a, b \in X$ ,  $|a - b| = l(a, b)$ ; it is also common to call such a  $|\cdot|$  an *intrinsic* distance function. Notice that an  $l$ -geodesic  $[x, y]_l$  is a shortest curve joining  $x$  and  $y$ .

There are two useful properties of length spaces that we use repeatedly. First, for any open set  $U$  in a length space  $X$ , we always have  $\text{dist}(x, \text{bd } U) = \text{dist}(x, X \setminus U)$  for all points  $x \in U$ . Second,  $\bar{X}$  is also a length space. In fact, for all  $x \in X, \xi \in \partial X, \varepsilon > 0$  there is a path  $\gamma: x \rightsquigarrow \xi$  in  $X \cup \{\xi\}$  with  $\ell(\gamma) < |x - \xi| + \varepsilon$ .

**2.A.2. Quasihyperbolic distance.** Recall that  $X$  is a *quasihyperbolic metric space* if it is non-complete, locally complete, and rectifiably connected. In such a space,  $\delta(x) = \delta_X(x) := \text{dist}(x, \partial X) > 0$  for all  $x \in X$ , so  $\delta^{-1}ds$  is a conformal metric that we call the *quasihyperbolic metric* on  $X$ . The length distance induced by the quasihyperbolic metric  $\delta^{-1}ds$  is dubbed the *quasihyperbolic distance*  $k = k_X$  in  $X$ . In a locally compact quasihyperbolic space, this is a geodesic distance: there are always  $k$ -geodesics joining any two points in  $X$ .

The following basic estimates for quasihyperbolic distance were first established for Euclidean domains by Gehring and Palka [GP76, 2.1]. For all  $a, b \in X$  and any rectifiable path  $\gamma: a \rightsquigarrow b$  in  $X$

$$(2.1a) \quad k(a, b) \geq \log \left( 1 + \frac{l(a, b)}{\delta(a) \wedge \delta(b)} \right) \geq \log \left( 1 + \frac{|a - b|}{\delta(a) \wedge \delta(b)} \right) \geq \left| \log \frac{\delta(a)}{\delta(b)} \right|$$

which is a special case of the more general inequality

$$(2.1b) \quad \ell_k(\gamma) \geq \log \left( 1 + \frac{\ell(\gamma)}{\text{dist}(|\gamma|, \partial X)} \right).$$

**2.B. Quasiconvex, annular quasiconvex, and uniform spaces.** A rectifiable path  $\gamma: a \rightsquigarrow b$  is *C-quasiconvex*,  $C \geq 1$ , if its length is at most  $C$  times the distance between its endpoints; i.e., if  $\gamma$  satisfies

$$\ell(\gamma) \leq C |a - b|.$$

A metric space is *C-quasiconvex* if each pair of points can be joined by a  $C$ -quasiconvex path. A 1-quasiconvex metric space is a *geodesic* space, and a space is a length space if and only if it is  $C$ -quasiconvex for all  $C > 1$ . By cutting out loops, we can always replace a  $C$ -quasiconvex path with a  $C$ -quasiconvex arc having the same endpoints; see [Väi94].

The inequalities in (2.1a) yield the following ‘local’ estimates for quasihyperbolic distances.

**2.2. Fact.** Let  $X$  be a  $C$ -quasiconvex quasihyperbolic metric space. Then for all  $x, a \in X$ ,

$$k(x, a) \leq 1 \text{ or } \frac{|x - a|}{\delta(a)} \leq \frac{1}{2C} \implies \frac{1}{2} \frac{|x - a|}{\delta(a)} \leq k(x, a) \leq 2C \frac{|x - a|}{\delta(a)}.$$

**2.B.1. Annular quasiconvexity.** A metric space  $X$  is  $C$ -annular quasiconvex at  $p \in X$  provided it is connected and for all  $r > 0$ , points in  $A[p; r, 2r]$  can be joined by  $C$ -quasiconvex paths lying in  $A[p; r/C, 2Cr]$ . We call  $X$   $C$ -annular quasiconvex if it is  $C$ -annular quasiconvex at each point. Examples of quasiconvex and annular quasiconvex metric spaces include Banach spaces and upper regular Loewner spaces; the latter includes Carnot groups and certain Riemannian manifolds with non-negative Ricci curvature; see [HK98, 3.13,3.18, Section 6]. Korte [Kor07] proved that doubling metric measure spaces that support a  $(1, p)$ -Poincaré inequality with sufficiently small  $p$  are annular quasiconvex.

To the best of our knowledge, the notion of annular quasiconvexity was introduced in [Kor07] and [BHX08]; it was an essential ingredient in [HSX08]. A similar concept was employed in [Mac10].

**2.B.2. Uniformity.** Roughly speaking, a metric space is *uniform* when points in it can be joined by paths that are not “too long” and “move away” from the region’s boundary. More precisely, a quasihyperbolic metric space  $X$  is  $C$ -uniform (for some constant  $C \geq 1$ ) provided each pair of points can be joined by a  $C$ -uniform arc. Here a rectifiable  $\gamma: a \rightsquigarrow b$  is a  $C$ -uniform arc if and only if it is both a  $C$ -quasiconvex arc and a *double  $C$ -cone arc*; this latter condition means that

$$(2.3) \quad \forall x \in |\gamma|, \quad \ell(\gamma[x, a]) \wedge \ell(\gamma[x, b]) \leq C\delta(x).$$

Double cone arcs are often called *cigar arcs*. In [Väi88] Väisälä provides a description of various possible double cone conditions (which he calls *length cigars*, *diameter cigars*, *distance cigars*, and *Möbius cigars*). The work [Mar80] of Martio should also be mentioned.

To simplify an argument, we prevail upon the following characterization for uniform spaces established in [Her11, Prop. C].

**2.4. Fact.** A quasihyperbolic metric space is uniform if and only if it is plump and proximate points can be joined by uniform arcs. More precisely, if  $X$  is  $C$ -plump and  $3C$ -proximate points can be joined by  $B$ -uniform arcs, then  $X$  is  $18B^2C$ -uniform; conversely, if  $X$  is  $C$ -uniform, then it is  $4C$ -plump.

Two points  $x, y$  are  $C$ -proximate, for some constant  $C > 0$ , if  $|x - y| \leq C[\delta(x) \wedge \delta(y)]$ . If this holds, then also  $(C + 1)^{-1} \leq \delta(x)/\delta(y) \leq C + 1$ . A non-complete locally complete metric space  $U$  is  $C$ -plump,  $C \geq 1$ , provided for each  $x \in U$  and all  $r \in (0, \text{diam } U)$

$$(2.5) \quad \exists z \in B[x; r] \text{ with } \text{dist}(z, \partial U) \geq r/C.$$

This terminology was introduced by Väisälä in [Väi88] and perhaps is understood best when  $U$  is an open subspace of a length space  $X$ , for then (2.5) asserts that  $\text{dist}(z, X \setminus U) \geq r/C$ , so the ball  $B(z; r/C)$ , in  $X$ , is contained in  $U$ .

### 3. Proofs

Here we establish Theorems A, B, C as stated in the Introduction. In each of these,  $X$  is a given quasihyperbolic metric space.

**3.A. Proof of Theorem A.** Recall that  $o \in X$  and  $X_\star := X \setminus \{o\}$ . We let  $\delta_\star$  denote distance to  $\partial X_\star$ , so  $\delta_\star(x) := |x| \wedge \delta(x)$  where  $|x| := |x - o|$ .

To utilize Fact 2.4, we first verify the following.

**3.1. Lemma.** *Suppose  $X$  is  $C$ -uniform. Then  $X_\star := X \setminus \{o\}$  is  $12C$ -plump.*

*Proof.* Let  $a \in X_\star$  and  $r \in (0, \text{diam } X_\star)$ . We seek a point  $z \in \mathbf{B}[a; r]$  with  $\delta_\star(z) \geq r/12C$ .

Pick  $b \in X_\star$  with  $|a - b| \geq \frac{1}{2} \text{diam}(X_\star)$ . Let  $\gamma: a \curvearrowright b$  be a  $C$ -uniform arc in  $X$ . Let  $z_0$  be the arclength midpoint of  $\gamma$ . Then

$$\delta(z_0) \geq \frac{\ell(\gamma)}{2C} \geq \frac{|a - b|}{2C} \geq \frac{r}{4C}.$$

Assume  $|z_0 - a| \leq r/2$ . If  $|z_0| \geq r/12C$ , then  $z_0$  is the sought after point. Suppose  $|z_0| < r/12C$ . By examining paths from  $z_0$  to  $\partial X$ , we obtain a point  $z_1 \in \mathbf{S}(z_0; r/6C)$ . It follows that  $\delta_\star(z_1) \geq r/12C$ , and that

$$|z_1 - a| \leq |z_1 - z_0| + |z_0 - a| \leq \frac{r}{6C} + \frac{r}{2} \leq r,$$

so  $z_1$  is the sought after point.

Assume  $|z_0 - a| > r/2$ . Pick  $z_2 \in \gamma[z_0, a] \cap \mathbf{S}(a; r/2)$ . Then  $\delta(z_2) \geq r/2C$ . Thus if  $|z_2| \geq r/6C$ , then  $z_2$  is the sought after point. Suppose  $|z_2| < r/6C$ . By examining paths from  $z_2$  to  $\partial X$ , we obtain a point  $z_3 \in \mathbf{S}(z_2; r/3C)$ . It follows that  $\delta_\star(z_3) \geq r/6C$ , and that

$$|z_3 - a| \leq |z_3 - z_2| + |z_2 - a| = \frac{r}{3C} + \frac{r}{2} \leq r,$$

so  $z_3$  is the sought after point. □

Now we establish Theorem A. When  $X_\star$  is  $C_\star$ -uniform, it is not hard to check that  $X$  is  $C$ -uniform for any  $C > C_\star$  (this also follows from Theorem C) and the proof of (c)  $\implies$  (a) in [Her11, Prop. 2.3] shows that  $X$  is  $2(C_\star + 1)$ -annular quasiconvex at  $o$ .

For the converse, assume  $X$  is  $C$ -uniform and  $C_1$ -annular quasiconvex at  $o$ . By Lemma 3.1 we know that  $X_\star$  is  $12C$ -plump, so it suffices to show that there is a constant  $B$  such that  $36C$ -proximate points in  $X_\star$  can be joined by  $B$ -uniform arcs; then Fact 2.4 asserts that  $X_\star$  is  $C_\star$ -uniform with  $C_\star = 216B^2C$ .

Let  $a, b \in X_\star$  be  $36C$ -proximate; so,  $|a - b| \leq 36C(\delta_\star(a) \wedge \delta_\star(b))$ . By relabeling, if necessary, we may assume  $|a| \leq |b|$ . Now  $|a - b| \leq 36C|a|$ . Let  $\gamma_o: a \curvearrowright b$  be a  $C$ -uniform arc in  $X$ . Put  $R := |a|/10CC_1$ . Then  $\ell(\gamma_o) \leq C|a - b| \leq 36C^2|a|$ , so

$$R \geq (180C^3C_1)^{-1} \frac{\ell(\gamma_o)}{2}.$$

As  $|b| \geq |a|$ ,  $\{a, b\} \cap \mathbf{B}(o; |a|) = \emptyset$ . Suppose  $\gamma_o \cap \mathbf{B}(o; R) = \emptyset$ . Then for each  $x \in \gamma_o$ ,  $|x| \geq R$  and we readily deduce that  $\gamma_o$  is a  $180C^3C_1$ -uniform arc in  $X_\star$ .

Assume  $\gamma_o \cap \mathbf{B}(o; R) \neq \emptyset$ . Let  $a_o, b_o$  be the first, last points (respectively) of  $\gamma_o$  in  $\mathbf{S}(o; R)$ . Put  $\gamma := a \star \sigma \star b$  where  $\alpha := \gamma_o[a, a_o]$ ,  $\beta := \gamma_o[b_o, b]$  and where  $\sigma: a_o \curvearrowright b_o$  is a  $C_1$ -quasiconvex arc in  $\mathbf{A}[o; R/2C_1, C_1R]$ .

Note that as  $\alpha, \beta$  both join the spheres  $\mathbf{S}(o; R), \mathbf{S}(o; |a|)$ , they each have length at least  $|a| - R = (10CC_1 - 1)R \geq 9CC_1R$ . It follows that  $\delta(a_o) \vee \delta(b_o) \geq 9C_1R$ .

Evidently,  $\ell(\gamma) \leq C_1\ell(\gamma_o) \leq CC_1|a - b|$ , so to verify that  $\gamma$  is a uniform arc it remains to corroborate the double cone arc condition. To begin, let  $x \in \sigma$ . Then

$$|x| \geq \frac{R}{2C_1} \geq (360C^3C_1^2)^{-1} \frac{\ell(\gamma_o)}{2} \geq (360C^3C_1^3)^{-1} \frac{\ell(\gamma)}{2}.$$

Also,

$$9C_1R \leq \delta(a_o) \leq \delta(o) + |a_o| = \delta(o) + R$$

so

$$\delta(x) \geq \delta(o) - C_1R \geq (30C^3C_1)^{-1} \frac{\ell(\gamma)}{2}$$

and we see that the double cone condition holds for points in  $\sigma$  with constant  $360C^3C_1^3$ .

It remains to examine points  $x \in \alpha \cup \beta$ . Evidently,  $|x| \geq R \geq (180C^3C_1^2)^{-1}\ell(\gamma)/2$ . Let  $z_o$  be the arclength midpoint of  $\gamma_o$ ; so,  $z_o$  lies in  $\alpha$  or  $\beta$  or  $\gamma_o \setminus (\alpha \cup \beta)$ . If  $z_o$  lies in  $\gamma_o \setminus (\alpha \cup \beta)$ , then  $\alpha, \beta$  are both “short subarcs of  $\gamma_o$ ” and we readily see that

$$x \in \alpha \implies \ell(\gamma[x, a]) = \ell(\gamma_o[x, a]) \leq C\delta(x)$$

and

$$x \in \beta \implies \ell(\gamma[x, b]) = \ell(\gamma_o[x, b]) \leq C\delta(x)$$

and thus the double cone condition holds.

Suppose  $z_o \in \beta$ . Here  $\alpha$  is again a “short subarc” and we precede exactly as above for points  $x \in \alpha$ . Assume  $x \in \beta$ . When  $x \in \beta[z_o, b] = \gamma_o[z_o, b]$  we can—again—precede as above. So, assume  $x \in \beta[b_o, z_o]$ . Here

$$\delta(x) \geq \frac{\ell(\gamma_o[x, a])}{C} \geq \frac{\ell(\alpha)}{C} \geq 9C_1R \geq (20C^3C_1)^{-1} \frac{\ell(\gamma)}{2}.$$

Thus the double cone condition holds for points in  $\alpha \cup \beta$  with constant  $180C^3C_1^2$ . It now follows that  $\gamma$  is a  $B$ -uniform arc with  $B := 360C^3C_1^3$ .  $\square$

**3.B. Proof of Theorem B.** Here we assume  $\Omega$  is a uniformly collared subspace of a  $C_0$ -uniform space  $X$  with  $C_1$ -uniform  $\Phi$ -fat<sup>3</sup> collars as described in the Introduction. Also, since the associated hypotheses and conclusions are all bi-Lipschitz invariant, we may and do assume that  $X$  is a length space.

To join points, we start with a uniform arc in  $X$ . If this arc gets near some  $B_i$ , we replace (by “cutting and pasting”) an appropriate subarc with a uniform arc in  $\Omega_i$ .

Before immersing ourselves in the details, we discuss some basic immediate properties. First, since the open sets  $U_i$  are disjoint, each  $B_i$  is closed and, e.g.,  $\text{bd}(B) = \cup_i \text{bd}(B_i)$ . Also, while  $\partial B \subset \partial X$  may be empty or non-empty, for each  $i$ ,

$$d_i := \text{dist}(B_i, \partial X) > 0.$$

It’s not difficult to check that  $\Omega_i := \Omega \cap U_i = U_i \setminus B_i$ , and that  $\text{bd}(\Omega_i) = \text{bd}(B_i) \cup \text{bd}(U_i)$  and this is a disjoint union.

Next, as  $\Omega$  is open in  $X$  and  $X$  is open in  $\bar{X}$ , we (eventually) see that

$$\partial\Omega = \text{bd}(B) \cup \partial X \quad (\text{and this is a disjoint union})$$

---

<sup>3</sup>We assume  $\Phi \geq 2$ .

from which we deduce that for each  $x \in \Omega$ ,

$$\text{dist}(x, \partial\Omega) = \text{dist}(x, B) \wedge \text{dist}(x, \partial X) = \inf_i \text{dist}(x, B_i) \wedge \text{dist}(x, \partial X).$$

It also follows that for each  $x \in \Omega$ :

(3.2a)  $\quad$  If  $\exists i$  with  $\text{dist}(x, B_i) \leq d_i/2$ , then  $\text{dist}(x, \partial\Omega) = \text{dist}(x, B)$ .

(3.2b)  $\quad$  If  $\exists i$  with  $\text{dist}(x, B_i) \leq d_i/2\Phi$ , then  $\text{dist}(x, \partial\Omega) = \text{dist}(x, B_i)$ .

(3.2c)  $\quad$  If  $x \in \Omega_i$ , then  $\text{dist}(x, \partial\Omega) \geq \text{dist}(x, \partial\Omega_i)$ .

Now define

$$A_i := \left\{ x \in X \setminus B_i \mid \text{dist}(x, B_i) < \frac{d_i}{10\Phi} \right\} \quad \text{and} \quad A := \bigcup_i A_i.$$

From (3.2b) we see that

$$x \in \text{cl}(A_i) \implies \text{dist}(x, \partial\Omega) = \text{dist}(x, B_i)$$

and similarly

$$\text{dist}(x, \partial\Omega) = \text{dist}(x, \partial X) \implies x \notin \text{cl}(A).$$

Let  $a, b \in \Omega$  and let  $\gamma_o: a \curvearrowright b$  be a  $C_0$ -uniform arc in  $X$ . Suppose  $\gamma_o \cap A = \emptyset$ . Let  $x \in \gamma_o$ . Then for all  $i$ ,

$$\begin{aligned} \text{dist}(x, \partial X) &\leq \text{dist}(x, B_i) + \text{diam}(B_i) + \text{dist}(B_i, \partial X) \leq \text{dist}(x, B_i) + (\Phi + 1)d_i \\ &\leq (10\Phi(\Phi + 1) + 1) \text{dist}(x, B_i) \leq 20\Phi^2 \text{dist}(x, B_i), \end{aligned}$$

so  $\text{dist}(x, \partial\Omega) \geq (20\Phi^2)^{-1} \text{dist}(x, \partial X)$  and we deduce that  $\gamma_o$  is a  $20C_0\Phi^2$ -uniform arc in  $\Omega$ .

Suppose  $\gamma_o \cap A \neq \emptyset$  and, for a moment, assume  $\{a, b\} \cap A = \emptyset$ . Let  $J$  denote the set of all indices  $i$  with  $\gamma_o \cap A_i \neq \emptyset$ . For each  $j \in J$ : let  $a_j, b_j$  be the first, last points of  $\gamma_o$  in  $\text{bd}(A_j)$ ; let  $\sigma_j: a_j \curvearrowright b_j$  be a  $C_1$ -uniform arc in  $\Omega_j$ ; and, replace each subarc  $\gamma_o[a_j, b_j]$  with the corresponding  $\sigma_j$ .

If  $a \in A$ , say  $a \in A_{i_o}$ : let  $a_{i_o}$  be the last point of  $\gamma_o$  in  $\text{bd}(A_{i_o})$ ; let  $\alpha: a \curvearrowright a_{i_o}$  be a  $C_1$ -uniform arc in  $\Omega_{i_o}$ ; and, replace the subarc  $\gamma_o[a, a_{i_o}]$  with  $\alpha$ . Similarly, if  $b \in A_{j_o}$ , we get a  $C_1$ -uniform  $\beta: b_{j_o} \curvearrowright b$  in  $\Omega_{j_o}$  that replaces  $\gamma_o[b_{j_o}, b]$ , where  $b_{j_o}$  is the first point of  $\gamma_o$  in  $\text{bd}(A_{j_o})$ .

We now have an arc  $\gamma: a \curvearrowright b$  in  $\Omega$  that has been obtained by replacing certain subarcs of  $\gamma_o$  with appropriate subarcs  $\sigma_j$  or  $\alpha$  or  $\beta$ . As each of these new subarcs is  $C_1$ -quasiconvex, we see that

$$\ell(\gamma) \leq C_1 \ell(\gamma_o) \leq C_0 C_1 |a - b|,$$

so  $\gamma$  is a  $C_0 C_1$ -quasiconvex arc. It remains to verify the double cone condition.

Let  $x \in \gamma$ . Suppose  $x \notin \alpha \cup \beta \cup \bigcup_j \sigma_j$ . As above, where  $\gamma_o \cap A = \emptyset$ , we again see that  $\text{dist}(x, \partial\Omega) \geq \text{dist}(x, \partial X)/20\Phi^2$  and the double cone condition holds with  $C = 20C_0 C_1 \Phi^2$ .

Suppose  $x \in \alpha$ . If  $\ell(\gamma[x, a]) = \ell(\alpha[x, a]) \leq \ell(\alpha[x, a_o])$ , then  $\text{dist}(x, \partial\Omega) \geq \text{dist}(x, \partial\Omega_{i_o}) \geq C_1^{-1} \ell(\gamma[x, a])$  and the double cone condition holds with constant  $C = C_1$ .



Assume  $\ell(\alpha[x, a]) > \ell(\alpha[x, a_o])$ . Now

$$\begin{aligned} \ell(\gamma[x, a]) &= \ell(\alpha[x, a]) \leq \ell(\alpha) \leq C_1|a - a_o| \\ &\leq C_1(\text{dist}(a, B_{i_o}) + \text{diam}(B_{i_o}) + \text{dist}(a_o, B_{i_o})) \\ &\leq C_1(\Phi + 1)d_{i_o} \leq 2C_1\Phi d_{i_o}. \end{aligned}$$

If  $\ell(\alpha[x, a_o]) \geq d_{i_o}/20\Phi$ , then

$$\text{dist}(x, \partial\Omega) \geq \text{dist}(x, \partial\Omega_{i_o}) \geq C_1^{-1}\ell(\alpha[x, a_o]) \geq \frac{d_{i_o}}{20C_1\Phi} \geq \frac{\ell(\gamma[x, a])}{40C_1^2\Phi^2}.$$

On the other hand, if  $\ell(\alpha[x, a_o]) < d_{i_o}/20\Phi$ , then

$$\begin{aligned} \frac{d_{i_o}}{10\Phi} &= \text{dist}(a_o, B_{i_o}) = \text{dist}(a_o, \partial\Omega) \leq |x - a_o| + \text{dist}(x, \partial\Omega) \\ &\leq \ell(\alpha[x, a_o]) + \text{dist}(x, \partial\Omega) \end{aligned}$$

and so now

$$\text{dist}(x, \partial\Omega) \geq \frac{d_{i_o}}{20\Phi} \geq \frac{\ell(\gamma[x, a])}{40C_1\Phi^2}.$$

Thus in all cases, when  $x \in \alpha$ , the double cone condition holds with constant  $C = 40C_1^2\Phi^2$ .

A similar argument applies if  $x \in \beta$ .

Finally, suppose  $x \in \sigma_j$  for some  $j \in J$ . We demonstrate that

$$\ell(\gamma[x, a]) \wedge \ell(\gamma[x, b]) \leq 3C_0C_1\Phi d_j \quad \text{and} \quad d_j \leq 20C_1\Phi \text{dist}(x, \partial\Omega)$$

which gives the double cone condition with constant  $C = 60C_0C_1^2\Phi^2$ .

First, if

$$\ell(\sigma_j[x, a_j]) \wedge \ell(\sigma_j[x, b_j]) \geq \frac{d_j}{20\Phi},$$

then  $\text{dist}(x, \partial\Omega) \geq \text{dist}(x, \partial\Omega_j) \geq d_j/20C_1\Phi$ . Suppose

$$\ell(\sigma_j[x, z]) < \frac{d_j}{20\Phi} \quad \text{for some } z \in \{a_j, b_j\}.$$

Then

$$\frac{d_j}{10\Phi} = \text{dist}(z, B_j) = \text{dist}(z, \partial\Omega) \leq |x - z| + \text{dist}(x, \partial\Omega) \leq \ell(\sigma_j[x, z]) + \text{dist}(x, \partial\Omega)$$

whence again  $\text{dist}(x, \partial\Omega) \geq d_j/20C_1\Phi$ .

Next,  $\ell(\gamma[x, a]) \leq \ell(\sigma_j) + \ell(\gamma[a_j, a])$  and  $\ell(\gamma[x, b]) \leq \ell(\sigma_j) + \ell(\gamma[b_j, b])$ , so

$$\begin{aligned} \ell(\gamma[x, a]) \wedge \ell(\gamma[x, b]) &\leq \ell(\sigma_j) + \ell(\gamma[a_j, a]) \wedge \ell(\gamma[b_j, b]) \\ &\leq \ell(\sigma_j) + C_1(\ell(\gamma_o[a_j, a]) \wedge \ell(\gamma_o[b_j, b])). \end{aligned}$$

Now

$$\ell(\sigma_j) \leq C_1|a_j - b_j| \leq C_1(\text{dist}(a_j, B_j) + \text{diam}(B_j) + \text{dist}(b_j, B_j)) \leq C_1\left(\Phi + \frac{1}{5\Phi}\right)d_j.$$

Also, for  $z \in \{a_j, b_j\}$ ,

$$\text{dist}(z, \partial X) \leq \text{dist}(z, B_j) + \text{diam}(B_j) + \text{dist}(B_j, \partial X) \leq \left(\Phi + 1 + \frac{1}{10\Phi}\right)d_j.$$

If  $\ell(\gamma_o[a_j, a]) \leq \ell(\gamma_o[b_j, b])$ , then

$$\ell(\gamma_o[a_j, a]) = \ell(\gamma_o[a_j, a]) \wedge \ell(\gamma_o[a_j, b]) \leq C_0 \text{dist}(a_j, \partial X)$$

and similarly if  $\ell(\gamma_o[b_j, b]) \leq \ell(\gamma_o[a_j, a])$ , then

$$\ell(\gamma_o[b_j, b]) = \ell(\gamma_o[b_j, a]) \wedge \ell(\gamma_o[b_j, b]) \leq C_0 \text{dist}(b_j, \partial X).$$

Therefore

$$\ell(\gamma_o[a_j, a]) \wedge \ell(\gamma_o[b_j, b]) \leq C_0 \left( \Phi + 1 + \frac{1}{10\Phi} \right) d_j.$$

It now follows that

$$\ell(\gamma[x, a]) \wedge \ell(\gamma[x, b]) \leq C_1 \left( \Phi + \frac{1}{5\Phi} \right) d_j + C_0 C_1 \left( \Phi + 1 + \frac{1}{10\Phi} \right) d_j \leq 3C_0 C_1 \Phi d_j.$$

Examining all our various constants we see that  $\gamma: a \curvearrowright b$  is a  $C_0 C_1$ -quasiconvex double  $60C_0 C_1^2 \Phi^2$ -cone arc in  $\Omega$ .  $\square$

**3.C. Proof of Theorem C.** Here  $\Omega = X \setminus A$  and (1.3) holds for some constant  $\kappa \in (0, 1)$ .

First, suppose  $\Omega$  is  $C$ -uniform. The proof of (c)  $\implies$  (a) in [Her11, Prop. 2.3] shows that  $X$  is  $2(C + 1)$ -annular quasiconvex at all points  $a \in A$ . Let  $\varepsilon \in (0, 1)$ . We verify that  $X$  is  $(C + \varepsilon)$ -uniform.

Since  $A \subset \partial\Omega$ ,  $X = \Omega \cup A$  is  $C'$ -quasiconvex for any  $C' > C$  which permits use of Fact 2.2.

Let  $a, b \in X$ . Since we can join points in  $\Omega$  with  $C$ -uniform arcs, we may assume  $a, b \in A$ ; the case where one point lies in  $A$  and one in  $\Omega$  is similar and easier. We select  $a_o, b_o \in \Omega$  sufficiently near  $a, b$ , pick quasiconvex arcs  $\alpha: a \curvearrowright a_o, \beta: b_o \curvearrowright b$  and a uniform arc  $\gamma_o: a_o \curvearrowright b_o$  in  $\Omega$ , and then check that  $\gamma := \alpha \star \gamma_o \star \beta$  is  $(C + \varepsilon)$ -uniform.

For each  $a \in A$ , set  $\rho_a := v\delta(a)$  where  $v := \kappa/10C$ . Employing (1.3) in conjunction with Fact 2.2 we see that that the balls  $B(a; \rho_a)$ , with  $a \in A$ , are disjointed.

Fix points  $a_o \in B(a; \varepsilon\rho_a/10C^2), b_o \in B(b; \varepsilon\rho_b/10C^2)$  and let  $\alpha: a \curvearrowright a_o, \beta: b_o \curvearrowright b$  be  $(C + \varepsilon)$ -quasiconvex arcs. Note that

$$\ell(\alpha) \leq (C + \varepsilon)|a - a_o| \leq \frac{C + \varepsilon}{10C^2} \varepsilon\rho_a \leq \frac{\varepsilon}{5C} \rho_a$$

and similarly  $\ell(\beta) \leq \varepsilon\rho_b/5C$ .

Let  $\gamma_o: a_o \curvearrowright b_o$  be a  $C$ -uniform arc in  $\Omega$ . Put  $\gamma := \alpha \star \gamma_o \star \beta$ ; then  $\gamma: a \curvearrowright b$  in  $\Omega \cup \{a, b\}$ . Since  $|a - b| \geq \rho_a + \rho_b$  and  $|a_o - b_o| \leq |a - a_o| + |a - b| + |b - b_o|$ , we see that

$$\begin{aligned} \ell(\gamma) &\leq (C + \varepsilon)(|a - a_o| + |b - b_o|) + C|a_o - b_o| \\ &\leq (2C + \varepsilon)(|a - a_o| + |b - b_o|) + C|a - b| \\ &\leq \varepsilon \frac{2C + \varepsilon}{10C^2} (\rho_a + \rho_b) + C|a - b| \\ &\leq (C + \varepsilon)|a - b| \end{aligned}$$

and so  $\gamma$  is  $(C + \varepsilon)$ -quasiconvex.

To establish the double cone condition, let  $x \in \gamma$ , and let  $z_o$  be the arclength midpoint of  $\gamma_o$ . If  $x \in \alpha$ , it is not difficult to check that  $\delta(x) \geq \ell(\alpha) \geq \ell(\gamma([x, a]));$

similarly for  $x \in \beta$ . Assume  $x \in \gamma_o$ , say  $x \in \gamma_o[a_o, z_o]$ . Here

$$\delta(x) \geq \text{dist}(x, \partial\Omega) \geq C^{-1}\ell(\gamma_o[x, a_o]).$$

If  $\ell(\gamma_o[x, a_o]) \geq \rho_a/5$ , then  $\ell(\alpha) \leq (C/\varepsilon)\ell(\gamma_o[x, a_o])$ , so

$$\ell(\gamma[x, a]) = \ell(\gamma_o[x, a_o]) + \ell(\alpha) \leq \left(1 + \frac{C}{\varepsilon}\right)\ell(\gamma_o[x, a_o]) \leq (C + \varepsilon)\delta(x).$$

Finally, if  $\ell(\gamma_o[x, a_o]) \leq \rho_a/5$ , then

$$|x - a| \leq \frac{\rho_a}{5} + \frac{\varepsilon\rho_a}{10C^2} \leq \frac{2C^2 + \varepsilon}{10C^2}v\delta(a) \leq \frac{3v}{10}\delta(a)$$

so

$$\delta(x) \geq \left(1 - \frac{3v}{10}\right)\delta(a)$$

whence

$$\ell(\gamma[x, a]) \leq \frac{\rho_a}{5} + \frac{\varepsilon\rho_a}{5C} = \frac{C + \varepsilon}{5C}v\delta(a) \leq \frac{C + \varepsilon}{C} \frac{2v}{10 - 3v} \leq (1 + \varepsilon)\delta(x).$$

For the converse, suppose  $X$  is  $C_0$ -uniform and  $C_1$ -annular quasiconvex at each point of  $A$ . We show that  $\Omega := X \setminus A$  is uniformly collared with fat collars and appeal to Theorem B.

For each  $a \in A$ , set  $\rho_a := v_0\delta(a)$  where  $v_0 := \kappa/4C_0$ . Employing Fact 2.2 and (1.3) we see that the balls  $\mathbf{B}(a; \rho_a)$ , with  $a \in A$ , are disjointed. By assumption, each  $\mathbf{B}(a; \rho_a)$  is  $C_2$ -uniform and  $X$  is  $C_1$ -annularly quasiconvex at  $a$ ; by *the proof* of Theorem A,  $\mathbf{B}_*(a; \rho_a) := \mathbf{B}(a; \rho_a) \setminus \{a\}$  is  $C_*$ -uniform. Since  $A = X \setminus \Omega = \bigcup_{a \in A} \{a\}$  with  $\{a\} = \{a\} \cap \mathbf{B}(a; \rho_a)$ , we see that  $\Omega$  is uniformly collared. Evidently, the collars  $\mathbf{B}_*(a; \rho_a)$  are  $\Phi$ -fat with  $\Phi := 1/v_0 = 4C_0/\kappa$ .  $\square$

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