GEOMETRIC INTERSECTION NUMBERS ON A FIVE-PUNCTURED SPHERE

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Abstract. Let $\mathscr G$ be the set of all simple closed geodesics on a five-punctured sphere Σ_5 . In this article, we associate to each $\gamma \in \mathscr{G}$ four integers which are read off topologically from γ itself. These integers have three remarkable applications. First, the geometric intersection number of any two geodesics in $\mathscr G$ can be written explicitly in terms of the corresponding integers. Secondly, there is a homeomorphism of the completion of $\mathscr G$ onto a 3-sphere lying in \mathbb{R}^4 whose restriction to $\mathscr G$ is written explicitly in terms of these integers. Finally, these integers are related to trace polynomials of the corresponding transformations in a representation of $\pi_1(\Sigma_5)$ into PSL(2, C).

Introduction

According to Thurston, the set of all complete simple geodesics on a Riemann surface can be made into a topological space homeomorphic to a sphere whose dimension depends on the topology of the surface. By Thurston's result, the space $\overline{\mathscr{G}}_n$ of complete simple geodesics on an *n*-punctured sphere Σ_n with $n \geq 4$ is homeomorphic to a sphere of dimension $2n - 7$.

In [4], the author introduced to each simple closed geodesic γ on Σ_4 a pair of integers $I_X(\gamma) \geq 0$ and $N(\gamma)$ whose absolute values are geometric intersection numbers of γ with a fixed pair of simple curves on Σ_4 . With these integers, the author proved that the geometric intersection number of any two simple closed geodesics γ and δ on Σ_4 is

$$
2|I_X(\gamma)N(\delta) - I_X(\delta)N(\gamma)|.
$$

The geometric intersection formula above was used to prove the injectivity of a homeomorphism Ψ of $\overline{\mathscr{G}}_4$ onto the circle $\mathbf{R} \cup {\infty}$ with $\Psi(\gamma) = N(\gamma)/I_X(\gamma)$ for all simple closed geodesics γ . Moreover, if G is a Maskit four-punctured sphere group, and if $g \in G$ represents a simple closed geodesic γ on Σ_4 , then the first two high-order terms of the trace polynomial of g are written explicitly in terms of $I_X(\gamma)$ and $N(\gamma)$.

The aim of this article is to generalize the results in [4] to the case of a five-punctured sphere.

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Similar trace formulas for once and twice punctured tori are proved using different methods in [6] and [7] respectively. However, the methods adopted in [4], [6], [7] and in this article are all based on the cutting sequence technique developed by Birman and Series [2].

In [7], the trace formulas are obtained by factoring a representation of the first fundamental group of a twice punctured torus $\mathscr S$ in $SL(2, \mathbb C)$ as a representation of the fundamental groupoid $\pi_{1,2}(\mathscr{S}, p_1, p_2)$ on \mathscr{S} with two basepoints p_1 and p_2 , where one basepoint is chosen on each of the two cyclindrical subsurfaces obtained by cutting along a pair of disjoint curves, one passing through each of the punctures. The fundamental groupoid $\pi_{1,2}(\mathscr{S}, p_1, p_2)$ is the groupoid of homotopy classes of paths in $\mathscr S$ with endpoints in the set $\{p_1, p_2\}.$

In addition to trace formulas, in [7] Keen, Parker and Series also provide a set of projective coordinates for the set of all simple closed geodesics on \mathscr{S} , called the $\pi_{1,2}$ -coordinates. For every simple loop γ on \mathscr{S} , they consider the restriction of the integral weighted π_1 -train track associated with γ to each cylinder, and call the restricted train track the integral weighted $\pi_{1,2}$ -train track associated with γ by relating it to $\pi_{1,2}(\mathscr{S}, p_1, p_2)$. The $\pi_{1,2}$ -coordinates are integer functions of the integral weighted $\pi_{1,2}$ -train tracks.

In this article, we shall give a set of projective coordinates to the set $\mathscr G$ of all simple closed geodesics on a five punctured sphere Σ_5 equipped with a hyperbolic metric. By using the coordinates, we provide a 3-sphere structure for the set $\mathscr G$ of all complete simple geodesics on Σ_5 .

To enumerate the set $\mathscr G$, we start with a Fuchsian representation G of the first fundamental group of Σ_5 acting on the upper half plane $\mathcal U$. The Fuchsian group G is generated by two parabolic transformations X and Y , and two hyperbolic transformations S and T .

In Section 2, we introduce four integer functions I_X , I_Y , N_S and N_T on \mathscr{G} . The integer functions I_X and I_Y are analogues of the integer function I_X defined in [4], and N_S and N_T are analogues of the integer function N defined in [4]. The values of I_X and I_Y are non-negative. The sign of N_S and that of N_T are determined by the symmetry of \mathscr{D} , where \mathscr{D} is a fundamental domain for G acting on $\mathcal U$ with $\Gamma = \{S, S^{-1}, T, T^{-1}, X, X^{-1}, Y, Y^{-1}\}$ the set of side pairings.

For every $\gamma \in \mathscr{G}$, the integers $I_X(\gamma)$, $I_Y(\gamma)$, $N_S(\gamma)$ and $N_T(\gamma)$ are read off from the lift of γ to \mathscr{D} . The lift of γ to \mathscr{D} also determines words in elements of Γ representing γ, which are called Γ-words. We shall write Γ-words representing geodesics in $\mathscr G$ in a specific way, and call them cyclic semi-reduced Γ -words. In Section 2, we shall also relate these cyclic semi-reduced Γ-words to the integer functions I_X , I_Y , N_S and N_T .

By use of the integer functions I_X , I_Y , N_S and N_T , we prove a geometric intersection formula in Theorem 3.1. The geometric intersection formula says that if γ and δ are two geodesics in \mathscr{G} , then the geometric intersection number of γ with δ is

$$
2|I_X(\gamma)N_T(\delta) - I_X(\delta)N_T(\gamma)| + 2|I_Y(\gamma)N_S(\delta)|
$$

- $I_Y(\delta)N_S(\gamma)| + |I_{XY}(\gamma, \delta)| - I_{XY}(\gamma, \delta),$

where $I_{XY}(\gamma, \delta) = \{I_X(\gamma) - I_Y(\gamma)\} \cdot \{I_X(\delta) - I_Y(\delta)\}.$

As a consequence of the geometric intersection formula, we obtain the geometric intersection numbers of six fixed geodesics in $\mathscr G$ with an arbitrary geodesic $\gamma \in \mathscr{G}$. These geometric intersection numbers will be called the elementary intersection numbers of γ .

The elementary intersection numbers are used to construct a homeomorphism Ψ of $\overline{\mathscr{G}}$ onto a 3-sphere Δ lying in \mathbb{R}^6 (Theorem 4.3). We start with a function of G into Δ which maps each $\gamma \in \mathscr{G}$ to the point whose coordinates are the elementary intersection numbers of γ . Then, by a continuity argument, we extend the function to obtain a continuous map Ψ from $\overline{\mathscr{G}}$ onto Δ . The injectivity of Ψ is proved by the geometric intersection formula.

By post composing Ψ by a map from \mathbb{R}^6 into \mathbb{R}^4 , we obtain an embedding Φ of $\overline{\mathscr{G}}$ into \mathbb{R}^4 with

$$
\Phi(\gamma)=\left(\frac{I_X(\gamma)}{\sigma(\gamma)},\frac{N_T(\gamma)}{\sigma(\gamma)},\frac{I_Y(\gamma)}{\sigma(\gamma)},\frac{N_S(\gamma)}{\sigma(\gamma)}\right)
$$

for every $\gamma \in \mathscr{G}$, where $\sigma(\gamma) = I_X(\gamma) + |N_T(\gamma)| + I_Y(\gamma) + |N_S(\gamma)|$ (Theorem 4.4).

In the final section, we first find for each $\gamma \in \mathscr{G}$ a cyclic semi-reduced Γ-word $W(\gamma)$ to represent it, and write the word explicitly; see Theorem 5.1, Corollary 5.2 and Theorem 5.3. Then, we consider the Maskit embedding of the Teichmuller space of Σ_5 , which is a holomorphic family of Kleinian groups $G(\mu, \nu)$ parametrized by a subset \mathcal{M}_5 of \mathbb{C}^2 . For every $(\mu, \nu) \in \mathcal{M}_5$, the group $G(\mu, \nu)$ uniformizes a five-punctured sphere and three thrice punctured spheres.

For every $\gamma \in \mathscr{G}$, let $W(\gamma; \mu, \nu) \in G(\mu, \nu)$ be the image of $W(\gamma)$ under the canonical isomorphism of G onto $G(\mu, \nu)$. The trace tr $W(\gamma; \mu, \nu)$ of $W(\gamma; \mu, \nu)$ is a polynomial in μ and ν . For $\gamma \in \mathscr{G}$ with $m = I_X(\gamma) > 0$ or $n = I_Y(\gamma) > 0$, we prove in Theorem 5.5 that

tr
$$
W(\gamma; \mu, \nu) = \pm \{\mu^{2m} \nu^{2n} + 4N_T(\gamma)\mu^{2m-1} \nu^{2n} + 2N_S(\gamma)\mu^{2m} \nu^{2n-1} + \cdots \}
$$

energy $m > n$ and

whenever $m \geq n$, and

tr $W(\gamma; \mu, \nu) = \pm 4^{n-m} \{ \mu^{2m} \nu^{2n} + 4N_T(\gamma) \mu^{2m-1} \nu^{2n} + 2N_S(\gamma) \mu^{2m} \nu^{2n-1} + \cdots \}$ whenever $m \leq n$.

Together with the theory of pleating coordinates developed by Keen and Series [6], the trace formulas given above will be used to describe the shape of \mathcal{M}_5 . The work will appear elsewhere.

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1. Preliminaries

1.1. The space of complete simple geodesics. Let Σ_5 be a 5-punctured sphere equipped with a hyperbolic metric. A loop on Σ_5 with no self intersections will be called a *simple loop*. An *essential simple loop* on Σ_5 is a simple loop which is neither homotopically trivial nor homotopically equivalent to a puncture of Σ_5 . A finite union of pairwise disjoint essential simple loops on Σ_5 will be called a multiple simple loop.

Let $\mathscr G$ be the set of all free homotopy classes of non-oriented essential simple loops on Σ_5 . Every element of $\mathscr G$ contains a unique geodesic γ on Σ_5 . By abuse of notation, we shall also use γ for the free homotopy class containing γ .

Let \mathscr{GL} be the set of all free homotopy classes of non-oriented multiple simple loops on Σ_5 . It is clear that $\mathscr G$ is a subset of $\mathscr GL$.

Let α be a multiple simple loop on Σ_5 . All connected components of α fall into at most two distinct free homotopy classes. There are integers $p \geq 0$ and $q \geq 0$ with $p + q > 0$ such that α has exactly p connected components freely homotopic to a $\gamma \in \mathscr{G}$, and has exactly q connected components freely homotopic to a $\gamma' \in \mathscr{G}$, where $\gamma \neq \gamma'$. We shall write $[\alpha] = p\gamma \oplus q\gamma'$, where $[\alpha]$ is the free homotopy class represented by α . Similarly, the free homotopy class represented by a curve β on Σ_5 will be denoted by $[\beta]$.

Let $[\mathscr{G}, \mathbf{R}_{+}]$ be the set of all functions from \mathscr{G} into the set \mathbf{R}_{+} of all nonnegative real numbers. We provide $\mathscr G$ with the discrete topology, and provide $[\mathscr{G}, \mathbf{R}_{+}]$ with the compact-open topology. It is well known that $[\mathscr{G}, \mathbf{R}_{+}]$ is homeomorphic to the product space $\prod_{\gamma \in \mathscr{G}} \mathbf{R}^{\gamma}_{+}$, where each \mathbf{R}^{γ}_{+} is a copy of \mathbf{R}_{+} .

Two elements f and g of $[\mathscr{G}, \mathbf{R}_{+}] - \{0\}$ are called projectively equivalent if there is a positive number t such that $f = tg$. Let $P[\mathscr{G}, \mathbf{R}_{+}]$ be the set of all projective equivalence classes in $[\mathscr{G}, \mathbf{R}_{+}] - \{0\}$ provided with the quotient topology. Let π be the quotient map of $[\mathscr{G}, \mathbf{R}_{+}] - \{0\}$ onto $P[\mathscr{G}, \mathbf{R}_{+}].$

For any two curves α_1 and α_2 on Σ_5 , let $\#(\alpha_1 \cap \alpha_2)$ denote the cardinality of the intersection $\alpha_1 \cap \alpha_2$. The geometric intersection number $i([\alpha_1], [\alpha_2])$ of $[\alpha_1]$ with $\lbrack \alpha_2 \rbrack$ is defined by

$$
i([\alpha_1], [\alpha_2]) = \min\{\#(\alpha'_1 \cap \alpha'_2) : [\alpha'_j] = [\alpha_j] \text{ for } j = 1, 2\}.
$$

It follows immediately from the definition that if $[\alpha] = p\gamma \oplus q\gamma'$, then for any curve β on Σ_5

$$
i([\alpha], [\beta]) = pi(\gamma, [\beta]) + qi\gamma', [\beta]),
$$

where p and q are non-negative integers with $p+q>0$, and where γ and γ' are disjoint geodesics in \mathscr{G} .

Each $\alpha \in \mathscr{GL}$ induces a function $I_{\alpha}: \mathscr{G} \longrightarrow \mathbf{R}_{+}$ given by

$$
I_{\alpha}(\gamma) = i(\alpha, \gamma)
$$
 for all $\gamma \in \mathscr{G}$.

Let $\mathscr{I} : \mathscr{GL} \longrightarrow [\mathscr{G}, \mathbf{R}_{+}]$ be defined by

$$
\mathscr{I}(\alpha) = I_{\alpha} \quad \text{for all } \alpha \in \mathscr{GL}.
$$

It is a well-known fact that the composition $\pi\mathscr{I}$ is injective; see [5]. This allows us to identify \mathscr{GL} with $\pi \mathscr{I}(\mathscr{GL})$.

Let $\overline{\pi\mathscr{I}(\mathscr{G}\mathscr{L})}$ and $\overline{\pi\mathscr{I}(\mathscr{G})}$ denote the closures of $\pi\mathscr{I}(\mathscr{G}\mathscr{L})$ and $\pi\mathscr{I}(\mathscr{G})$ in $P[\mathscr{G}, \mathbf{R}_{+}]$, respectively. Poénaru proved that $\overline{\pi \mathscr{I}(\mathscr{G} \mathscr{L})} = \overline{\pi \mathscr{I}(\mathscr{G})}$, (Theorem 4 of [5] Exposé 4).

Note that an element $\mathscr L$ of $P[\mathscr G, \mathbf R_+]$ is in $\overline{\pi \mathscr I(\mathscr G)}$ if and only if for any l in $[\mathscr{G}, \mathbf{R}_{+}] - \{0\}$ with $\pi(l) = \mathscr{L}$ there is a sequence $\{t_k\}_{k=1}^{\infty}$ of positive numbers, and there is a sequence $\{\gamma_k\}_{k=1}^{\infty}$ of geodesics in $\mathscr G$ such that the sequence $\{t_k\}_{k=1}^{\infty}$ converges to l. A sequence $\{l_k\}_{k=1}^{\infty}$ in $[\mathscr{G},\mathbf{R}_{+}]$ is called *convergent* to $l \in [\mathscr{G},\mathbf{R}_{+}]$ if for every $\gamma \in \mathscr{G}$ the sequence $\{l_k(\gamma)\}_{k=1}^{\infty}$ converges in **R** to $l(\gamma)$.

According to Thurston, $\overline{\pi\mathscr{I}(\mathscr{G})}$ is homeomorphic to a 3-sphere. In Section 4, we shall construct a homeomorphism of $\overline{\pi\mathscr{I}(\mathscr{G})}$ onto a 3-sphere lying in \mathbb{R}^4 (see Theorem 4.4).

1.2. Cyclic reduced words. To enumerate free homotopy classes in \mathscr{GL} , we consider the action of the fundamental group $\pi_1(\Sigma_5)$ on the upper half plane $\mathscr{U} = \{z \in \mathbf{C} : \text{Im } z > 0\}.$

Let G be the subgroup of $PSL(2, \mathbf{R})$ generated by the transformations:

$$
X = \begin{pmatrix} 1 & 6 \\ 1 & 0 \end{pmatrix}, \quad Y = \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}, \quad S = \begin{pmatrix} 3 & 4 \\ 2 & 3 \end{pmatrix} \quad \text{and} \quad T = \begin{pmatrix} 5 & 12 \\ 2 & 5 \end{pmatrix}.
$$

For $j = 1, 2, 3$, let

$$
C'_{j} = \{ z \in \mathbf{C} : |2z + 2j - 1| = 1 \} \text{ and } C_{j} = \{ z \in \mathbf{C} : |2z - (2j - 1)| = 1 \},\
$$

and let

$$
C'_4 = \{ z \in \mathbf{C} : \text{Re } z = -3 \}
$$
 and $C_4 = \{ z \in \mathbf{C} : \text{Re } z = 3 \}.$

It is clear that $\mathscr{U}/G = \Sigma_5$, and that the domain $\mathscr{D} \subset \mathscr{U}$ bounded by C_j and C'_{j} , $1 \leq j \leq 4$, is a fundamental domain for G acting on \mathscr{U} . We shall schematically draw $\mathscr D$ as a rectangular region shown in Figure 1, where the points on the boundary of \mathscr{D} marked by " \times " correspond to punctures of Σ_5 .

It is well known that every free homotopy class in $\mathscr G$ corresponds to a unique conjugacy class in G. We shall find a representative for each conjugacy class in G by using Birman and Series' cutting sequence technique [2].

Let Γ denote the set of all side pairings of \mathscr{D} , i.e.,

$$
\Gamma = \{X, X^{-1}, Y, Y^{-1}, S, S^{-1}, T, T^{-1}\}.
$$

Figure 1. The fundamental domain \mathscr{D} .

For every $E \in \Gamma$, we label the common side s of $\mathscr D$ and $E(\mathscr D)$ by E^{-1} on the side inside \mathscr{D} , and by E on the side inside $E(\mathscr{D})$; see Figure 1. The side s will be called the E -side of \mathscr{D} .

For every $q \in G$, the image $q(\mathscr{D})$ will be called a *G*-translate of \mathscr{D} . We transport the above side labelling to all G -translates of \mathscr{D} .

Let γ be an arbitrary closed curve on Σ_5 . Let $\tilde{\gamma}$ be a lift of γ to $\mathscr U$ which projects to γ bijectively, and let $z_0 \in \mathscr{U}$ be an endpoint of $\tilde{\gamma}$. Without loss of generality, assume that there is a $g_0 \in G$ and there is a $\xi_0 \in \mathscr{D}$ such that $z_0 = q_0(\xi_0).$

We orient $\tilde{\gamma}$ so that its initial point is z_0 . The arc $\tilde{\gamma}$ cuts in order the Gtranslates $g_0(\mathscr{D}), g_1(\mathscr{D}), \ldots, g_k(\mathscr{D})$ of \mathscr{D} . Then the terminal point of $g_0^{-1}(\tilde{\gamma})$ is $g_0^{-1} \circ g_k(\xi_0)$, and γ is represented by $g = g_0^{-1} \circ g_k$.

For every integer j with $1 \leq j \leq k$, assume that the common side of $g_{j-1}(\mathscr{D})$ and $g_j(\mathscr{D})$ on the side inside $g_j(\mathscr{D})$ is labelled by $E_j \in \Gamma$. Then

$$
E_j(D) = g_{j-1}^{-1}(g_j(D)),
$$

or equivalently $E_j = g_{j-1}^{-1}$ $j-1$ ∘ g_j . Thus

$$
g = g_0^{-1} \circ g_k = (g_0^{-1} \circ g_1) \circ (g_1^{-1} \circ g_2) \circ \cdots \circ (g_{k-1}^{-1} \circ g_k) = E_1 \circ E_2 \circ \cdots \circ E_k.
$$

We call $E_1 \circ E_2 \circ \cdots \circ E_k$ a Γ -word representing γ .

From now on, we shall simply write the composition of a function f followed by the other function q as $q f$. Thus, we write

$$
E_1 \circ E_2 \circ \cdots \circ E_k = \prod_{j=1}^k E_j.
$$

A Γ -word $\prod_{j=1}^{k} E_j$ will be called *reduced* if $E_j \neq E_{j+1}^{-1}$ for $1 \leq j \leq k-1$. It is called *cyclically reduced* if in addition $E_1 \neq E_k^{-1}$.

Let γ be a simple loop on Σ_5 . Using the above notation, for every integer j with $0 \leq j \leq k$, let l_j be the image of the intersection of $\tilde{\gamma}$ with $g_j(\mathscr{D})$ mapped by g_j^{-1} , where $\overline{\mathscr{D}}$ is the relative closure of \mathscr{D} in \mathscr{U} . The union $l_0 \cup l_k$ forms a simple arc in $\overline{\mathscr{D}}$ connecting the E_k^{-1} -side to the E_1 -side. We shall simply write the simple arc as l_k . If $k > 1$ and if $1 \leq j \leq k-1$, then l_j is a simple arc in \overline{D} connecting the E_j^{-1} -side to the E_{j+1} -side. Each of these simple arcs l_1, \ldots, l_k will be called a *strand* of γ .

Let α be a multiple simple loop on Σ_5 . A strand of a connected component of α will be also called a *strand* of α .

A loop on Σ_5 will be called *reduced* if it is represented by a reduced Γ -word. A multiple simple loop α on Σ_5 will be called *reduced* if every connected component of α is reduced. It is easy to see that a simple loop or a multiple simple loop on Σ_5 is reduced if and only if every strand of the loop connects two different sides of \mathscr{D} .

If $\gamma \in \mathscr{G}$ is a geodesic, then every strand of γ is a hyperbolic geodesic arc, and thus every strand of γ must connect two different sides of $\mathscr D$ since $\mathscr D$ is a geodesic polygon. This proves that every simple closed geodesic on Σ_5 is a reduced loop. Thus every free homotopy class of multiple simple loops on Σ_5 contains a reduced one.

If $\gamma \in \mathscr{G}$ is a geodesic represented by a reduced Γ-word W, then γ is also represented by an arbitrary cyclic permutation of W. If $\gamma' \in \mathscr{G}$ is a geodesic which has the same underlying set as γ but with opposite orientation, then γ' is represented by W^{-1} . Because we are only interested in non-oriented simple loops, we shall identify all reduced Γ -words which are cyclic permutations of W or cyclic permutations of W^{-1} , and call any one of them a cyclic reduced Γ word representing γ and its free homotopy class. Every cyclic reduced Γ -word is cyclically reduced.

Figure 2. From the left to the right: γ_{11} , γ_{12} , γ_{13} , γ_{21} , γ_{22} , γ_{23} .

As examples, let $\gamma_{jk} \in \mathscr{G}$ be the geodesics given in Figure 2. Each γ_{jk} is represented by a cyclic reduced Γ-word W_{ik} as follows:

$$
W_{11} = T
$$
, $W_{12} = X^{-1}S$, $W_{13} = XT^{-1}S$,
\n $W_{21} = S$, $W_{22} = Y^{-1}T$, $W_{23} = S^{-1}YT$.

For simplicity, we shall also write $\gamma_{11} = \gamma_T$ and $\gamma_{21} = \gamma_S$.

1.3. Subwords and admissible subarcs. The purpose of this subsection is to find some necessary conditions for cyclic reduced Γ-words representing geodesics in $\hat{\mathscr{G}} = \mathscr{G} - \{\gamma_S, \gamma_T\}$ from the geometry of the corresponding geodesics.

Let $\gamma \in \hat{\mathscr{G}}$ be a geodesic represented by a cyclic reduced Γ-word $W(\gamma)$ given by

$$
W(\gamma) = \prod_{j=1}^{k} E_j.
$$

Note that $k > 1$ since $\gamma \in \hat{\mathscr{G}}$. For any two integers j, l with $1 \leq j \leq k$ and $1 \leq l \leq k$, the reduced Γ-word

$$
(1) \t W' = E_j \cdots E_{j+l-1}
$$

will be called a *subword* of $W(\gamma)$, where $E_{i+i} = E_{i+i-k}$ whenever $1 \leq i \leq l$ and $i + j > k$.

Now, we shall relate W' to γ geometrically. For every i, let l_i be the strand of γ connecting the E_{i-1}^{-1} i_{i-1}^{-1} -side to the E_i -side, where $E_{i-1} = E_k$ if $i = 1$. Assume that $1 \leq l \leq k$, i.e., $W' \neq W(\gamma)$. We think that W' "represents" a subarc γ' of γ . We choose γ' to be the projection of the union $\bigcup_{i=j}^{j+l-1} l_i$ to Σ_5 . Each of the arcs l_j , ..., l_{j+l-1} is called a *strand* of γ' .

The subarc γ' has two distinct endpoints. One of the two endpoints is the projection of the endpoint of l_j on the E_{j-1}^{-1} j^{-1}_{j-1} -side, and the other endpoint is the projection of the endpoint of l_{j+l-1} on the E_{j+l-1} -side.

The word given in equation (1) is not clear enough to indicate that γ' has an endpoint which is the projection of a point lying on the E_{i-}^{-1} $j-1$ -side. Also, to be different from cyclic reduced words representing simple closed geodesics, we shall write the reduced Γ -word representing γ' as

(2)
$$
\vec{E}_{j-1}W' = \vec{E}_{j-1}E_j \cdots E_{j+l-1},
$$

where \vec{E}_{j-1} is to indicate that $\vec{E}_{j-1}W'$ is not cyclic, and one of the endpoints of γ' is the projection of a point on the E_{i-}^{-1} $j-1$ -side.

A subarc of a geodesic $\gamma \in \mathscr{G}$ will be called *admissible* if either it is γ itself, or it is represented by a reduced Γ -word as given in equation (2).

Remark 1.1. Let $\gamma \in \hat{\mathscr{G}}$ be a geodesic represented by a cyclic reduced Γword $W(\gamma)$. From now on, for $\varepsilon = \pm 1$, $E \in \Gamma$, $E_1, E_2 \in \Gamma - \{E^{\pm 1}\}\,$ and an integer $k > 1$, we shall write

$$
E_1 \underbrace{E^{\varepsilon} \cdots E^{\varepsilon}}_{k \text{ times}} E_2 = E_1 E^{k \varepsilon} E_2
$$

if above word is a subword of $W(\gamma)$.

By the same reasoning as that in [4, Section 3], there are no admissible subarcs of γ represented by any one of the following words:

$$
\begin{aligned} \vec{X}^{\varepsilon}X^{\varepsilon},\qquad &\vec{Y}^{\varepsilon}Y^{\varepsilon},\qquad &\vec{T}^{\delta}X^{\varepsilon}T^{\delta},\quad &\vec{S}^{\delta}Y^{\varepsilon}S^{\delta},\\ \vec{X}^{\varepsilon}T^{k}X^{\delta},\quad &\vec{Y}^{\varepsilon}S^{k}Y^{\delta},\quad &\vec{T}^{\varepsilon}S^{\delta}T^{\varepsilon},\qquad &\vec{S}^{\varepsilon}T^{\delta}S^{\varepsilon}, \end{aligned}
$$

where ε , $\delta \in \{1, -1\}$, and $k \neq 0$ is an integer. Thus none of the following is a subword of $W(\gamma)$:

$$
X^{\varepsilon}X^{\varepsilon}, \qquad Y^{\varepsilon}Y^{\varepsilon}, \qquad T^{\delta}X^{\varepsilon}T^{\delta}, \quad S^{\delta}Y^{\varepsilon}S^{\delta},
$$

$$
X^{\varepsilon}T^{k}X^{\delta}, \quad Y^{\varepsilon}S^{k}Y^{\delta}, \quad T^{\varepsilon}S^{\delta}T^{\varepsilon}, \qquad S^{\varepsilon}T^{\delta}S^{\varepsilon}.
$$

Figure 3.

Proposition 1.1. Let $\gamma \in \mathscr{G}$ be a geodesic represented by a cyclic reduced Γ-word W, and let $k \neq 0$ be an integer.

(i) If $E_1, E_2 \in \{T^{\pm 1}, X^{\pm 1}\}$, and if $E_1 S^k E_2$ is a subword of W, then $|k| = 1$. (ii) If $E_1, E_2 \in \{S^{\pm 1}, Y^{\pm 1}\}$, and if $E_1 T^k E_2$ is a subword of W, then $|k| = 1$.

Proof. We shall prove the statement (i). The statement (ii) will follow by a similar argument.

Assume that $k > 0$. We choose once for all an orientation on the S^{-1} side. Let ζ be the fixed point of the transformation $S^{-1}T$. If P and P' are two distinct points lying on the S^{-1} -side, and if P lies between P' and ζ , then we write $P \prec P'$. This gives an orientation to the S-side as well. For any two distinct points Q and Q' lying on the S-side, if $S^{-1}(Q) \prec S^{-1}(Q')$, then we write $Q \prec Q'$.

Let γ' be the admissible subarc of γ represented by $\vec{E}_1 S^k E_2$. Let l_1 be the strand of γ' joining the E_1^{-1} -side to the S-side with the endpoint Q_1 on the S-side. Let l_2 be the strand of γ' joining the S^{-1} -side to the E_2 -side with the endpoint P_2 on the S^{-1} -side.

Suppose that $k > 1$. Then γ' has a strand l joining the S^{-1} -side to the S-side with the endpoint $P_1 = S^{-1}(Q_1)$ on the S^{-1} -side. Let Q be the endpoint of l on the S-side. Since γ is simple, we have $Q_1 \prec Q$ (see Figure 3). But, now, we have $P_1 \prec P_2$. This implies that l_2 intersects l which is a contradiction. Hence, $k = 1$.

By the same reasoning as above, one proves that $k = -1$ if $k < 0$.

1.4. π_1 -train tracks. In Section 3, we shall need π_1 -train tracks introduced by Birman and Series (see [1]). A π_1 -train track τ on $\mathscr D$ is a collection of mutually disjoint simple arcs l_j in $\overline{\mathscr{D}}$ with endpoints lying on the sides of \mathscr{D} such that

(i) except endpoints each l_i is contained in \mathscr{D} ,

(ii) each l_i joins two distinct sides of \mathscr{D} , and

(iii) each pair of distinct sides of $\mathscr D$ are connected by at most one l_i .

A π_1 -train track τ on $\mathscr D$ is called *integral weighted* if every arc in τ is assigned a non-negative integer.

Every reduced multiple simple loop α on Σ_5 can be associated with an integral weighted π_1 -train track as described below.

We choose for each $E \in \Gamma$ a point $P(E)$ on the E-side of $\mathscr D$ so that $P(E^{-1})$ and $P(E)$ are identified by the transformation E.

For any two distinct $E_1, E_2 \in \Gamma$, let $n_{\alpha}(E_1, E_2)$ be the number of strands of α connecting the E_1 -side to the E_2 -side of \mathscr{D} . If $n_{\alpha}(E_1, E_2) > 0$, then we collapse all strands of α which connect the E_1 -side to the E_2 -side into a single arc from $P(E_1)$ to $P(E_2)$ weighted by the integer $n_{\alpha}(E_1, E_2)$. These weighted arcs form the required integral weighted π_1 -train track $\tau(\alpha)$ on \mathscr{D} (see [1, Theorem 1.3]).

It is clear that if α and β are freely homotopic reduced multiple simple loops on Σ_5 , then $n_{\alpha}(E_1, E_2) = n_{\beta}(E_1, E_2)$ whenever $E_1, E_2 \in \Gamma$ are distinct, and thus $\tau(\alpha) = \tau(\beta)$. Since every free homotopy class of multiple simple loops on Σ_5 contains a reduced one, we may write

$$
n_{[\alpha]}(E_1, E_2) = n_{\alpha}(E_1, E_2)
$$

whenever α is a reduced multiple simple loop on Σ_5 , and call $n_{\alpha}(E_1, E_2)$ the number of strands of [α] connecting the E_1 -side to the E_2 -side. Similarly, we write

$$
\tau([\alpha]) = \tau(\alpha).
$$

Let $[\alpha]$, $[\alpha_1]$ and $[\alpha_2]$ be any three elements of \mathscr{GL} . If, as subsets of $\overline{\mathscr{D}}$, $\tau([\alpha])$ is the union of $\tau([\alpha_1])$ and $\tau([\alpha_2])$, and if there are two fixed non-negative integers p and q with $p + q > 0$ satisfying

$$
n_{[\alpha]}(E_1, E_2) = pn_{[\alpha_1]}(E_1, E_2) + qn_{[\alpha_2]}(E_1, E_2)
$$

for any two distinct $E_1, E_2 \in \Gamma$, then we shall write

$$
[\alpha] = p[\alpha_1] + q[\alpha_2].
$$

From the definition, we see that $[\alpha] = p\gamma + q\gamma'$ if $[\alpha] = p\gamma \oplus q\gamma'$, where $p \ge 0$, $q \ge 0$ are integers with $p + q > 0$, and where $\gamma, \gamma' \in \mathscr{G}$ are disjoint geodesics.

2. Four integer functions

In Section 4, we shall construct a homeomorphism Φ of $\overline{\pi\mathscr{I}(\mathscr{GL})}$ onto a 3-sphere lying in \mathbb{R}^4 . For $\alpha \in \mathscr{GL}$, the value $\Phi(\alpha)$ is written in terms of four integers $I_X(\alpha) \geq 0$, $I_Y(\alpha) \geq 0$, $N_S(\alpha)$ and $N_T(\alpha)$. The sign of $N_S(\alpha)$ and that of $N_T(\alpha)$ are determined by the geometry of α . The integers $I_X(\alpha)$, $I_Y(\alpha)$, $|N_S(\alpha)|$ and $|N_T(\alpha)|$ are numbers of strands of α .

The integer functions I_X and I_Y are analogues of the integer function I_X given in [4], and the integer functions N_S and N_T are analogues of the integer function N given in [4]. In this section, we shall define the integer functions I_X , I_Y , N_S and N_T , and discuss their properties.

2.1. Elementary intersection numbers. For the construction of the homeomorphism Φ , we shall start with a homeomorphism Ψ of $\pi \mathscr{I}(\mathscr{GL})$ onto a 3-sphere lying in \mathbb{R}^6 whose value at every $\alpha \in \mathscr{GL}$ is written in terms of the geometric intersection numbers of α with the six geodesics γ_{ik} given in Figure 2. These six geometric intersection numbers $i(\alpha, \gamma_{ik})$ will be called the *elementary intersection numbers* of α .

To compute elementary intersection numbers, we consider the projections of the sides of $\mathscr D$ to Σ_5 . For $E \in \{S, T, X, Y\}$, the E-side of $\mathscr D$ projects to Σ_5 a simple curve β_E connecting exactly two punctures. Write

$$
I_E(\alpha) = i(\alpha, [\beta_E])
$$

for all $\alpha \in \mathscr{GL}$. Note that

 $I_E(\alpha) = \#\{\text{strands of } \alpha \text{ which meet the } E\text{-side (or the } E^{-1}\text{-side})\}.$

Thus, we have

(3)
$$
i(\alpha, \gamma_{11}) = 2I_X(\alpha), \quad i(\alpha, \gamma_{21}) = 2I_Y(\alpha), i(\alpha, \gamma_{12}) = 2I_T(\alpha), \quad i(\alpha, \gamma_{22}) = 2I_S(\alpha).
$$

We shall prove later that the elementary intersection numbers of α can be written in terms of $I_X(\alpha)$, $I_Y(\alpha)$, $N_S(\alpha)$ and $N_T(\alpha)$ (see Corollary 3.4). This allows us to construct the homeomorphism Ψ by use of the functions I_X , I_Y , N_S and N_T .

For later use, we extend the integer functions I_E to admissible subarcs of geodesics in $\mathscr G$ as follows. For $E \in \Gamma$, and for an arbitrary admissible subarc γ' of a geodesic $\gamma \in \mathscr{G}$, let

 $I_E(\gamma') = #$ (strands of γ' which meet the E-side of \mathscr{D}).

Note that $I_E(\gamma) = I_{E^{-1}}(\gamma)$ for $\gamma \in \mathscr{G}$ and for $E \in \Gamma$.

2.2. Cyclic semi-reduced Γ-words. Let $\gamma \in \hat{\mathscr{G}} = \mathscr{G} - {\gamma_T, \gamma_S}$ be represented by a cyclic reduced Γ-word $W(\gamma)$. We have known that for $E \in$ $\{S, T, X, Y\}$ the integer $I_E(\gamma)$ is the number of strands of γ which meet the E-side. We may also relate the number $I_E(\gamma)$ to $W(\gamma)$ as follows

 $I_E(\gamma)$ = the total number of the letters E and E^{-1} appearing in $W(\gamma)$.

Therefore, to compute the elementary intersection numbers of $\gamma \in \widehat{\mathscr{G}}$ is equivalent to finding a cyclic reduced Γ-word representing γ .

In general, it is not easy to write cyclic reduced Γ-words representing geodesics in $\mathscr G$ explicitly. Therefore, we shall introduce *cyclic semi-reduced* Γ-words. Cyclic semi-reduced Γ-words also work for our purposes. To compute geometric intersection numbers, we only need a partial description of cyclic semi-reduced Γ-words, which will be given in Section 2.5. The complete description is given in Section 5.

Figure 4. From the left to the right: $\alpha_1, \alpha_2, \alpha_3, \alpha_4, \alpha_5, \alpha_6$.

To motivate the definition of cyclic semi-reduced Γ-words, we consider the geodesics represented by the following cyclic reduced Γ-words:

$$
W_1 = X S^{-1} Y, \qquad W_2 = T X^{-1} S^{-1} Y^{-1} S, \qquad W_3 = T X T^{-1} S^{-2} Y S,
$$

$$
W_4 = X^{-1} S Y^{-1}, \qquad W_5 = T^{-1} X S Y S^{-1}, \qquad W_6 = T^{-1} X^{-1} T S^2 Y^{-1} S^{-1}.
$$

Let α_j be the geodesic represented by W_j for $1 \leq j \leq 6$ (see Figure 4). By defining the zero power E^0 of the transformation E to be the identity transformation for $E = S$ or T, we may rewrite above words as

(4)
$$
W_j = T^{r_j} X^{\omega_j} T^{t_j} S^{p_j} Y^{\varepsilon_j} S^{q_j},
$$

where $\chi_i = (r_i, \omega_i, t_i, p_i, \varepsilon_i, q_i)$ are given below:

$$
\chi_1 = (0, 1, 0, -1, 1, 0),
$$
 $\chi_2 = (1, -1, 0, -1, -1, 1),$
\n $\chi_3 = (1, 1, -1, -2, 1, 1),$ $\chi_4 = (0, -1, 0, 1, -1, 0),$
\n $\chi_5 = (-1, 1, 0, 1, 1, -1),$ $\chi_6 = (-1, -1, 1, 2, -1, -1).$

From the word given in (4), we have

$$
I_X(\alpha_j) = 1
$$
, $I_Y(\alpha_j) = 1$, $I_S(\alpha_j) = |p_j| + |q_j|$ and $I_T(\alpha_j) = |r_j| + |t_j|$.

Now, we define the cyclic semi-reduced Γ -words representing geodesics in $\mathscr G$ as follows. Let $\gamma \in \hat{\mathscr{G}}$ be a geodesic represented by a cyclic reduced Γ-word $W(\gamma)$. If $Y^{\varepsilon}E$ or EY^{ε} is a subword of $W(\gamma)$ with $\varepsilon = \pm 1$ and $E \in \{X^{\pm 1}, T^{\pm 1}\},$ we shall write

$$
Y^{\varepsilon}E = Y^{\varepsilon}S^{0}E \text{ and } EY^{\varepsilon} = ES^{0}Y^{\varepsilon}.
$$

Similarly, if $E \in \{Y^{\pm 1}, S^{\pm 1}\}$, and if $X^{\varepsilon}E$ or EX^{ε} is a subword of $W(\gamma)$, then we write

$$
X^{\varepsilon}E = X^{\varepsilon}T^{0}E \quad \text{and} \quad EX^{\varepsilon} = ET^{0}X^{\varepsilon}.
$$

The resulting cyclic Γ-word will be called *semi-reduced*, still denoted by $W(\gamma)$.

2.3. Four automorphisms of \mathscr{GL} . Let α_j be the geodesics given in Section 2.2, and let W_j be the corresponding cyclic semi-reduced Γ-words. By considering the symmetry of the fundamental domain \mathscr{D} , we realize that for $1 \leq$ $j \leq 3$ the words W_{j+3} are the images of W_j under the automorphism Θ_1 of G defined by

$$
\Theta_1(E) = E^{-1}
$$
 for $E \in \{S, T, X, Y\}$.

There is another automorphism Θ_2 of G obtained from the symmetry of $\mathscr D$ defined by

$$
\Theta_2(S) = T
$$
, $\Theta_2(T) = S$, $\Theta_2(X) = Y$, $\Theta_2(Y) = X$.

For $j = 1$ or 2, the automorphism Θ_j induces an orientation reversing homeomorphism of Σ_5 onto itself which is also denoted by Θ_i . If $\gamma \in \mathscr{G}$ is a geodesic, let $\Theta_j(\gamma)$ denote the free homotopy class in $\mathscr G$ represented by the image of γ mapped by Θ_j . This defines an injective function, still denoted by Θ_j , of $\mathscr G$ onto itself such that if W is a cyclic reduced (or semi-reduced) Γ-word representing $\gamma \in \mathscr{G}$, then $\Theta_i(\gamma)$ is represented by $\Theta_i(W)$.

For instance, we have $\Theta_1(\alpha_j) = \alpha_{j+3}$ for $1 \leq j \leq 3$. For every integer j with $1 \leq j \leq 6$, the geodesic $\Theta_2(\alpha_j)$ is represented by the word

$$
\Theta_2(W_j) = S^{r_j} Y^{\omega_j} S^{t_j} T^{p_j} X^{\varepsilon_j} T^{q_j},
$$

where W_i is the cyclic semi-reduced Γ-word given in (4).

Now, we extend the functions Θ_1 and Θ_2 to \mathscr{GL} by defining

$$
\Theta_j(a\gamma \oplus b\gamma') = a\Theta_j(\gamma) \oplus b\Theta_j(\gamma')
$$

for $j = 1, 2$, where $a \ge 0$ and $b \ge 0$ are integers with $a + b > 0$, and where γ and γ' are disjoint geodesics in \mathscr{G} .

With the two maps Θ_1 and Θ_2 , we may simplify the argument on finding cyclic semi-reduced Γ-words by considering subsets of $\mathscr G$ which are related by Θ_1 and Θ_2 . Let

 $\mathscr{GL}_S^+=\{\alpha\in\mathscr{GL}:\alpha\,\text{ has no strands joining the }S^{-1}\text{-side to the }Y^\varepsilon\text{-side, }\varepsilon=\pm 1\},\$

and let

$$
\mathcal{GL}_S^- = \Theta_1(\mathcal{GL}_S^+), \ \mathcal{GL}_T^+ = \Theta_2(\mathcal{GL}_S^-) \ \text{and} \ \mathcal{GL}_T^- = \Theta_1(\mathcal{GL}_T^+) = \Theta_2(\mathcal{GL}_S^+).
$$

For $E = S$ or T, let $\mathscr{G}_E^+ = \mathscr{GL}_E^+ \cap \mathscr{G}$ and $\mathscr{G}_E^- = \mathscr{GL}_E^- \cap \mathscr{G}$. Note that for $E = S$ or T the sets \mathscr{GL}_E^+ and \mathscr{GL}_E^- are not disjoint since

$$
a\gamma_S \oplus b\gamma_T \in \mathscr{GL}_E^+ \cap \mathscr{GL}_E^-,
$$

where $a \geq 0$ and $b \geq 0$ are integers with $a + b > 0$.

The following proposition is an immediate consequence of the definition.

Proposition 2.1. If $\alpha \in \mathscr{GL}$, then $I_E(\Theta_1(\alpha)) = I_E(\alpha)$ for $E \in \{S, T, X, Y\}$ and

$$
I_X(\Theta_2(\alpha)) = I_Y(\alpha), \quad I_Y(\Theta_2(\alpha)) = I_X(\alpha),
$$

\n
$$
I_S(\Theta_2(\alpha)) = I_T(\alpha), \quad I_T(\Theta_2(\alpha)) = I_S(\alpha).
$$

Taking a further step to investigate the relations among the geodesics α_1 , α_2 and α_3 , we found that the geodesics α_1 , α_2 and α_3 are related by the automorphisms \mathcal{T}_1 and \mathcal{T}_2 of G defined by

$$
\mathcal{T}_1: \quad S \longrightarrow S, \quad T \longrightarrow T, \quad X \longrightarrow X, \quad Y \longrightarrow Y^{-1}S,
$$

$$
\mathcal{T}_2: \quad S \longrightarrow S, \quad T \longrightarrow T, \quad X \longrightarrow X^{-1}T, \quad Y \longrightarrow Y.
$$

From the definition, we obtain

$$
\Theta_2 \mathcal{I}_1 \Theta_2 = \mathcal{I}_2
$$
 and $\Theta_1 \mathcal{I}_j \Theta_1 = \mathcal{I}_j^{-1}$ for $j = 1, 2$.

For $j = 1$ or 2, the automorphism \mathcal{T}_j induces an orientation preserving homeomorphism of Σ_5 onto itself, denoted by \mathcal{T}_j as well. The homeomorphism \mathcal{T}_1 interchanges the two punctures on Σ_5 corresponding to the fixed point of Y and the fixed point of $Y^{-1}S$, and leaves the other punctures invariant. The homeomorphism \mathcal{T}_2 interchanges the two punctures on Σ_5 corresponding to the fixed point of X and the fixed point of $X^{-1}T$, and leaves the other punctures invariant.

Each \mathcal{T}_j also induces an injective function of $\mathscr G$ onto itself so that if W is a cyclic reduced (or semi-reduced) Γ-word representing $\gamma \in \mathscr{G}$, then $\mathscr{T}_i(\gamma)$ is represented by $\mathscr{T}_i(W)$. Now, α_1, α_2 and α_3 are related by \mathscr{T}_1 and \mathscr{T}_2 as follows:

$$
\mathscr{T}_1 \mathscr{T}_2^{-1}(\alpha_1) = \alpha_2
$$
 and $\mathscr{T}_1 \mathscr{T}_2^{-1}(\alpha_2) = \alpha_3$.

Like Θ_1 and Θ_2 , the functions \mathcal{T}_1 and \mathcal{T}_2 extend to \mathscr{GL} defined by

$$
\mathscr{T}_j(a\gamma \oplus b\gamma') = a\mathscr{T}_j(\gamma) \oplus b\mathscr{T}_j(\gamma'), \quad j = 1, 2,
$$

where $a \geq 0$ and $b \geq 0$ are integers with $a + b > 0$, and where γ and γ' are disjoint geodesics in \mathscr{G} .

Proposition 2.2. Let $\alpha \in \mathscr{GL}$.

(i) If $I_Y(\alpha) = 0$, then $\mathscr{T}_1(\alpha) = \alpha$.

(ii) If $I_X(\alpha) = 0$, then $\mathscr{T}_2(\alpha) = \alpha$.

(iii) If k is an integer, and if $E = X$ or Y, then $I_E(\mathcal{F}_1^k(\alpha)) = I_E(\alpha) =$ $I_E\big(\mathcal{T}_2^k(\alpha)\big)$.

Proof. For the proof of (i) and (ii), it suffices to consider the case where $\alpha \in \mathscr{G}$. Let W be a cyclic semi-reduced Γ-word representing α . If $I_Y(\alpha) = 0$, then Y and Y^{-1} are not subwords of W, and $\mathcal{T}_1(W) = W$. This proves that α is invariant under \mathcal{T}_1 . Similarly, α is invariant under \mathcal{T}_2 if $I_X(\alpha) = 0$.

Since γ_{11} and γ_{21} are invariant under \mathcal{T}_1 and \mathcal{T}_2 , we have

$$
i(\mathcal{I}_j^k(\alpha), \gamma_{m1}) = i(\alpha, \mathcal{I}_j^{-k}(\gamma_{m1})) = i(\alpha, \gamma_{m1})
$$

for $j, m \in \{1, 2\}$. Now, the statement (iii) follows from equation (3).

2.4. Definition of the integer functions N_S and N_T . Let $\gamma \in \mathscr{G}$ be a geodesic. If $\gamma \in \mathscr{G}_S^+$, let

 $N_S(\gamma) = \text{#(strands of } \gamma \text{ joining the } S\text{-side and the } S^{-1}\text{-side)}$

 $+$ #(strands of α joining the S-side and the Y^{ε}-side)

for $\varepsilon = \pm 1$. If $\gamma \in \mathscr{G}_T^+$, let

 $N_T(\gamma) = #$ (strands of γ joining the T-side and the T⁻¹-side) + #(strands of α joining the T⁻¹-side and the X^{ε}-side)

for $\varepsilon = \pm 1$. For $E = S$ or T, if $\gamma \in \mathscr{G}_{E}^{-}$, let $N_{E}(\gamma) = -N_{E}(\Theta_{1}(\gamma))$. From the definition, we have

Proposition 2.3. If $\gamma \in \hat{\mathscr{G}}$, then $N_S(\gamma) = -N_T(\Theta_2(\gamma))$ and $N_T(\gamma) =$ $-N_S(\Theta_2(\gamma)).$

For two integers $a \geq 0$ and $b \geq 0$ with $a + b > 0$, let

$$
N_S(a\gamma_S \oplus b\gamma_T) = a
$$
 and $N_T(a\gamma_S \oplus b\gamma_T) = b$.

Next, if $\gamma \in \widehat{\mathscr{G}}$ is a geodesic disjoint from γ_S , let

 $N_S(a\gamma_S \oplus b\gamma) = a$ and $N_T(a\gamma_S \oplus b\gamma) = bN_T(\gamma)$.

If $\gamma \in \widehat{\mathscr{G}}$ is a geodesic disjoint from γ_T , let

$$
N_S(a\gamma_T \oplus b\gamma) = bN_S(\gamma)
$$
 and $N_T(a\gamma_T \oplus b\gamma) = a$.

Finally, if γ_1 and γ_2 are disjoint geodesics in $\hat{\mathscr{G}}$, we define

$$
N_E(a\gamma_1 \oplus b\gamma_2) = aN_E(\gamma_1) + bN_E(\gamma_2) \text{ for } E = S, T.
$$

To interpret $N_S(\alpha)$ and $N_T(\alpha)$ geometrically for $\alpha \in \mathscr{GL}$, we need

Lemma 2.4. If γ_1 and γ_2 are disjoint geodesics in $\hat{\mathscr{G}}$, then

$$
N_S(\gamma_1)N_S(\gamma_2) \ge 0 \quad \text{and} \quad N_T(\gamma_1)N_T(\gamma_2) \ge 0.
$$

Proof. We shall prove $N_T(\gamma_1)N_T(\gamma_2) \geq 0$. This implies, by Proposition 2.3, that $N_S(\gamma_1)N_S(\gamma_2) \geq 0$. First, note that if $\gamma \in \hat{\mathscr{G}}$ with $N_T (\gamma) \neq 0$, then $I_X(\gamma) > 0$.

Suppose that $N_T(\gamma_1) > 0$ and $N_T(\gamma_2) < 0$. Then γ_1 has a strand l_1 joining the T^{-1} -side to the X^{ε} -side with $\varepsilon = \pm 1$, and has a strand l'_1 joining the $X^{-\varepsilon}$ side to some E-side with $E \in \{T^{-1}, S^{\pm 1}, Y^{\pm 1}\}$ so that its endpoint on $X^{-\varepsilon}$ -side is identified with that of l_1 on the X^{ε} -side by the transformation X^{ε} .

Similarly, γ_2 has a strand l_2 joining the T-side to the X^{δ} -side with $\delta = \pm 1$, and has a strand l'_2 joining the $X^{-\delta}$ -side to some E'-side with $E' \in \{T, S^{\pm 1}, Y^{\pm 1}\}\$ so that its endpoint on the $X^{-\delta}$ -side is identified with that of l_2 on the X^{δ} -side by the transformation X^{δ} .

Since $l_1 \cup l'_1$ must intersect $l_2 \cup l'_2$, then $i(\gamma_1, \gamma_2) > 0$. Contradiction! Now, for $\alpha \in \mathscr{GL}$ we have

$$
|N_S(\alpha)| = \#(\text{strands of } \alpha \text{ joining the } S\text{-side and the } S^{-1}\text{-side})
$$

+
$$
\#(\text{strands of } \alpha \text{ joining the } S^{\delta}\text{-side and the } Y^{\varepsilon}\text{-side});
$$

$$
|N_T(\alpha)| = \#(\text{strands of } \alpha \text{ joining the } T\text{-side and the } T^{-1}\text{-side})
$$

+ #(strands of α joining the T^b-side and the X^{ε}-side),

where $\delta, \varepsilon = \pm 1$.

Proposition 2.5. Let $\alpha \in \mathscr{GL}$.

(i) If $I_X(\alpha) > 0$, then $N_T(\alpha) \geq 0$ whenever $\alpha \in \mathscr{GL}_T^+$, and $N_T(\alpha) \leq 0$ whenever $\alpha \in \mathscr{GL}_T^-.$ Thus, $N_T(\Theta_1(\alpha)) = -N_T(\alpha)$.

(ii) If $I_Y(\alpha) > 0$, then $N_S(\alpha) \geq 0$ whenever $\alpha \in \mathscr{GL}_S^+$, and $N_S(\alpha) \leq 0$ whenever $\alpha \in \mathscr{GL}_S$. Thus, $N_S(\Theta_1(\alpha)) = -N_S(\alpha)$.

(iii) If $I_X(\alpha)I_Y(\alpha) > 0$, then

$$
N_S(\alpha) = -N_T(\Theta_2(\alpha))
$$
 and $N_T(\alpha) = -N_S(\Theta_2(\alpha)).$

Proof. The statement (ii) will follow from (i) by considering $\Theta_2(\alpha)$. The statement (iii) is a consequence of (i) and (ii). It remains to prove the statement (i).

Write $\alpha = a\gamma_1 \oplus b\gamma_2$, where $a \geq 0$ and $b \geq 0$ are integers with $a + b > 0$, and where γ_1 and γ_2 are disjoint geodesics in \mathscr{G} . If $ab = 0$, then the statement (i) holds trivially since $I_X(\alpha) > 0$.

Assume that $ab > 0$. Since $I_X(\alpha) > 0$, then $\gamma_1 \neq \gamma_T$ and $\gamma_2 \neq \gamma_T$. If $\gamma_1 = \gamma_S$, then $I_X(\gamma_2) > 0$, and $N_T(\alpha) = bN_T(\gamma_2)$. Now, the assertion follows from the definition of the function N_T on $\hat{\mathscr{G}}$.

Similarly, the statement (i) is true if $\gamma_2 = \gamma_S$. If $\gamma_1 \neq \gamma_S$ and $\gamma_2 \neq \gamma_S$, the proof is completed by Lemma 2.4.

2.5. Relating N_S and N_T to cyclic semi-reduced Γ-words. Now, we shall explain how to determine $N_S(\gamma)$ and $N_T(\gamma)$ from a cyclic semi-reduced Γ-word W representing $\gamma \in \widehat{\mathscr{G}}$. Note that $I_X(\gamma) > 0$ or $I_Y(\gamma) > 0$.

If $I_Y(\gamma) = n > 0$, then there are exactly n triples of integers $(p_i, \varepsilon_i, q_i)$ with $\varepsilon_i = \pm 1$ such that $E_i S^{p_i} Y^{\varepsilon_i} S^{q_i} E'_i$ is a subword of W for every integer $i \in \{1, \ldots, n\}$, where $E_i, E'_i \in \{T^{\pm 1}, X^{\pm 1}, Y^{\pm 1}\}$. From Remark 1.1, we have $E_i, E'_i \in \{T^{\pm 1}, X^{\pm 1}\}\$ for every *i*. Thus *W* must be of the form

(5)
$$
W = \prod_{i=1}^{n} S^{p_i} Y^{\varepsilon_i} S^{q_i} W_i,
$$

where each W_i is a semi-reduced Γ -word of the form

$$
W_i = \prod_{i=1}^{m_i} E_{ij}
$$

with $E_{i1}, E_{im_i} \in \{T^{\pm 1}, X^{\pm 1}\},$ and $E_{ij} \neq Y^{\pm 1}$ whenever $1 < j < m_i$.

If $I_X(\gamma) = n > 0$, then $I_Y(\Theta_2(\gamma)) = n$, and γ is represented by a cyclic semi-reduced Γ-word as given in equation (5). Thus γ is represented by a cyclic semi-reduced Γ-word W of the form

(6)
$$
W = \prod_{i=1}^{n} T^{p_i} X^{\varepsilon_i} T^{q_i} W_i,
$$

where $\varepsilon = \pm 1$, where p_i and q_i are integers, and where each W_i is a semi-reduced Γ-word of the form

$$
W_i = \prod_{i=1}^{m_i} E_{ij}
$$

with $E_{i1}, E_{im_i} \in \{S^{\pm 1}, Y^{\pm 1}\},$ and $E_{ij} \neq X^{\pm 1}$ whenever $1 < j < m_i$.

Before continuing our discussion, we shall find necessary conditions for the integers p_i and q_i given in (5) and (6).

Lemma 2.6. Let $\varepsilon = \pm 1$, let p and q be integers, let $\gamma \in \hat{\mathscr{G}}$, and let W be a cyclic semi-reduced $\Gamma\operatorname{-word}$ representing $\gamma\,.$

(i) If $W' = E S^p Y^{\varepsilon} S^q E'$ is a subword of W with $E, E' \in \{X^{\pm}, T^{\pm}\}\$, then

$$
-1 \le (p+q)\varepsilon \le 0.
$$

Moreover, $p \le 0$ and $q \ge 0$ when $\gamma \in \mathscr{G}_S^+$, and $p \ge 0$ and $q \le 0$ when $\gamma \in \mathscr{G}_S^-$. (ii) If $W' = E T^p X^{\varepsilon} T^q E'$ is a subword of W with $E, E' \in \{Y^{\pm}, S^{\pm}\}\$, then

$$
-1 \le (p+q)\varepsilon \le 0.
$$

Moreover, $p \ge 0$ and $q \le 0$ when $\gamma \in \mathscr{G}_T^+$, and $p \le 0$ and $q \ge 0$ when $\gamma \in \mathscr{G}_T^-$.

Proof. For the proof of (i), we may assume that $\varepsilon = 1$ and $\gamma \in \mathscr{G}_{S}^{+}$. By the definition of \mathscr{G}_{S}^{+} , we have $p \leq 0$ and $q \geq 0$.

We rewrite W' as $W' = ES^{-p}Y^{\varepsilon}S^{q}E' = ES^{-p}YS^{q}E'$, where $p \geq 0$ and $q \geq 0$. If $q > p$, then $\mathcal{T}_1^{-2p}(W') = EYS^{q-p}E'$ is a subword of $\mathcal{T}_1^{-2p}(W)$, and $\mathscr{T}_1^{-2p}(\gamma)$ is not simple. Contradiction!

If $p > q+1$, then $\mathscr{T}_1^{-2q}(W') = ES^{-p+q}YE'$. This implies that $\mathscr{T}_1^{-2q}(\gamma)$ has a strand joining the S-side to the S^{-1} -side, and has a strand joining the Y^{-1} -side to the E'-side with $E' \in \{T^{\pm}, X^{\pm}\}\.$ This is impossible. Therefore, $q \leq p \leq q+1$. By considering \mathcal{T}_2 , the statement (ii) will follow by a similar argument.

Proposition 2.7. Let $\gamma \in \hat{\mathscr{G}}$ be a geodesic, and let W be a cyclic semireduced Γ -word representing γ .

(i) If W is of the form given in equation (5), then $N_S(\gamma) = \sum_{i=1}^n (q_i - p_i)$. (ii) If W is of the form given in equation (6), then $N_T(\gamma) = \sum_{i=1}^{n} (p_i - q_i)$.

Proof. From Proposition 2.3, the statement (ii) follows from the statement (i). On the other hand, since $N_S(\Theta_1(\gamma)) = -N_S(\gamma)$, we may assume that $\gamma \in \mathscr{G}_S^+$. Thus $p_i \leq 0$ and $q_i \geq 0$ for all i by Lemma 2.6.

For every *i*, let γ_i be the admissible subarc of γ represented by $\vec{E}_i W_i E'_i$, where

$$
E_i = \begin{cases} S & \text{if } q_i > 0, \\ Y^{\varepsilon_i} & \text{if } q_i = 0, \end{cases} \quad \text{and} \quad E'_i = \begin{cases} S^{-1} & \text{if } p_i < 0, \\ Y^{\varepsilon_{i+1}} & \text{if } p_i = 0. \end{cases}
$$

From the definition of W_i , we know that each γ_i neither has strands connecting the S-side to the Y-side, nor has strands connecting the S-side to the Y^{-1} -side. From Proposition 1.1, each γ_i has no strands joining the S-side and the S^{-1} -side. Thus $N_S(\gamma)$ is completely determined by the subwords $S^{p_i}Y^{\varepsilon_i}S^{q_i}$, $1 \leq i \leq n$.

Using notation given in equation (5), for every i let γ_i' be the admissible subarc represented by $\vec{E}_{(i-1)m_{i-1}}S^{p_i}Y^{\varepsilon_i}S^{q_i}$, and let

$$
N_i^{(1)} = #(\text{strands of }\gamma_i'\text{ connecting the }S\text{-side and the }S^{-1}\text{-side}),
$$

$$
N_i^{(2)} = #(\text{strands of }\gamma_i' \text{ connecting the } S\text{-side and the } Y\text{-side})
$$

+ #(strands of γ_i' connecting the S-side and the Y⁻¹-side).

Since $-1 \leq (p_i + q_i)\varepsilon_i \leq 0$ for every *i*, then

$$
(N_i^{(1)}, N_i^{(2)}) = \begin{cases} (q_i - p_i - 2, 2) & \text{if } q_i - p_i > 2, \\ (0, q_i - p_i) & \text{if } q_i - p_i \le 2. \end{cases}
$$

Thus

$$
N_S(\gamma) = \sum_{i=1}^n (N_i^{(1)} + N_i^{(2)}) = \sum_{i=1}^n (q_i - p_i).
$$

At the end of this section, we shall investigate how the integers $N_S(\mathcal{I}_j^k(\gamma))$ and $N_T(\mathcal{I}^k_j(\gamma))$ relate to the integers $N_S(\gamma)$ and $N_T(\gamma)$ for $j=1$ or 2, where $k \neq 0$ is an integer.

Proposition 2.8. Let $\gamma \in \mathcal{G}$, and let k be an arbitrary integer. Then (i) $N_S(\mathcal{I}_1^k(\gamma)) = N_S(\gamma) + kI_Y(\gamma)$ and $N_S(\mathcal{I}_2^k(\gamma)) = N_S(\gamma)$; (ii) $N_T(\mathcal{F}_1^k(\gamma)) = N_T(\gamma)$ and $N_T(\mathcal{F}_2^k(\gamma)) = N_T(\gamma) - kI_X(\gamma)$.

Proof. The proposition holds trivially for $\gamma = \gamma_T$ and for $\gamma = \gamma_S$. In the following, we assume that $\gamma \in \mathscr{G}$.

Since $\Theta_2 \mathcal{I}_1 \Theta_2 = \mathcal{I}_2$, then the equations in (ii) follow from that given in (i) by Proposition 2.1 and Proposition 2.3.

Now, we shall only prove the equations given in (i) for $k = \pm 1$. Then the proof of the proposition is completed by applying mathematical induction to $|k|$.

If $I_Y(\gamma) = 0$, then $N_S(\gamma) = 0$. From Proposition 2.2, we have $I_Y(\mathscr{T}_j^k(\gamma)) = 0$ for $j = 1, 2$. Thus $N_S(\mathcal{I}_j^k(\gamma)) = 0$, and the equations in (i) hold.

Let $I_Y(\gamma) = n > 0$. Assume that $\gamma \in \mathscr{G}_S^+$. Then γ is represented by a cyclic semi-reduced Γ-word W of the form

$$
W = \prod_{i=1}^{n} S^{-p_i} Y^{\varepsilon_i} S^{q_i} W_i,
$$

where $\varepsilon = \pm 1$, $p_i \ge 0$, $q_i \ge 0$ are integers, and where each W_i is a semi-reduced Γ-word as given in equation (5). Since

$$
\mathcal{F}_1(W) = \prod_{i=1}^n S^{-p'_i} Y^{-\varepsilon_i} S^{q'_i} W_i \quad \text{and} \quad \mathcal{F}_1^{-1}(W) = \prod_{i=1}^n S^{-p''_i} Y^{-\varepsilon_i} S^{q''_i} W_i,
$$

with $p'_{i} + q'_{i} = p_{i} + q_{i} + 1$ and $p''_{i} + q''_{i} = p_{i} + q_{i} - 1$, from Proposition 2.7 we have

$$
N_S(\mathcal{T}_1(\gamma)) = \sum_{i=1}^n (p'_i + q'_i) = n + \sum_{i=1}^n (p_i + q_i) = N_S(\gamma) + I_Y(\gamma) \text{ and}
$$

$$
N_S(\mathcal{T}_1^{-1}(\gamma)) = \sum_{i=1}^n (p''_i + q''_i) = -n + \sum_{i=1}^n (p_i + q_i) = N_S(\gamma) - I_Y(\gamma).
$$

Let $W_i' = \mathcal{F}_2(W_i)$ and $W_i'' = \mathcal{F}_2^{-1}(W_i)$ for every *i*. By the definition of W_i and that of \mathcal{I}_2 , we easily see that W_i' and W_i'' have the same form as W_i has. Since

$$
\mathscr{T}_2(W) = \prod_{i=1}^n S^{-p_i} Y^{\varepsilon_i} S^{q_i} W_i' \quad \text{and} \quad \mathscr{T}_2^{-1}(W) = \prod_{i=1}^n S^{-p_i} Y^{\varepsilon_i} S^{q_i} W_i'',
$$

then

$$
N_S(\mathcal{T}_2(\gamma)) = N_S(\mathcal{T}_2^{-1}(\gamma)) = \sum_{i=1}^n (p_i + q_i) = N_S(\gamma).
$$

If $\gamma \in \mathscr{G}_S^-$, then $\Theta_1(\gamma) \in \mathscr{G}_S^+$, and

$$
N_S(\mathcal{T}_1(\gamma)) = -N_S(\Theta_1 \mathcal{T}_1(\gamma)) = -N_S(\mathcal{T}_1^{-1}\Theta_1(\gamma))
$$

\n
$$
= -\{N_S(\Theta_1(\gamma)) - I_Y(\Theta_1(\gamma))\} = N_S(\gamma) + I_Y(\gamma);
$$

\n
$$
N_S(\mathcal{T}_1^{-1}(\gamma)) = -N_S(\Theta_1 \mathcal{T}_1^{-1}(\gamma)) = -N_S(\mathcal{T}_1\Theta_1(\gamma))
$$

\n
$$
= -\{N_S(\Theta_1(\gamma)) + I_Y(\Theta_1(\gamma))\} = N_S(\gamma) - I_Y(\gamma);
$$

\n
$$
N_S(\mathcal{T}_2^k(\gamma)) = -N_S(\Theta_1 \mathcal{T}_2^k(\gamma)) = -N_S(\mathcal{T}_2^{-k}\Theta_1(\gamma))
$$

\n
$$
= -N_S(\Theta_1(\gamma)) = N_S(\gamma) \text{ for } k = \pm 1.
$$

3. Geometric intersection numbers

In this section, we shall prove the geometric intersection formula (see Theorem 3.1). The geometric intersection formula will be used to prove the injectivity of a homeomorphism Ψ of $\pi \mathcal{I}(\mathcal{GL})$ onto a 3-sphere. The homeomorphism Ψ will be constructed with elementary intersection numbers. From the geometric intersection formula, we obtain the elementary intersection numbers of geodesics in $\mathscr G$. Then we will get elementary intersection numbers of $\alpha \in \mathscr{GL}$.

3.1. The geometric intersection formula. The main work of this subsection is to prove the following theorem:

Theorem 3.1 (Geometric intersection formula). If γ_1 and γ_2 are two simple closed geodesics on Σ_5 , then

$$
i(\gamma_1, \gamma_2) = 2|I_X(\gamma_1)N_T(\gamma_2) - I_X(\gamma_2)N_T(\gamma_1)| + 2|I_Y(\gamma_1)N_S(\gamma_2) - I_Y(\gamma_2)N_S(\gamma_1)|
$$

+ |I_{XY}(\gamma_1, \gamma_2)| - I_{XY}(\gamma_1, \gamma_2),

where $I_{XY}(\gamma_1, \gamma_2) = \{I_X(\gamma_1) - I_Y(\gamma_1)\} \cdot \{I_X(\gamma_2) - I_Y(\gamma_2)\}.$

As a consequence of the geometric intersection formula, we obtain the elementary intersection numbers of geodesics in $\mathscr G$ as follows.

Corollary 3.2. If $\gamma \in \mathscr{G}$, then

$$
i(\gamma, \gamma_{12}) = 2|N_T(\gamma)| + |I_Y(\gamma) - I_X(\gamma)| + I_Y(\gamma) - I_X(\gamma),
$$

\n
$$
i(\gamma, \gamma_{13}) = 2|N_T(\gamma) - I_X(\gamma)| + |I_Y(\gamma) - I_X(\gamma)| + I_Y(\gamma) - I_X(\gamma),
$$

\n
$$
i(\gamma, \gamma_{22}) = 2|N_S(\gamma)| + |I_X(\gamma) - I_Y(\gamma)| + I_X(\gamma) - I_Y(\gamma),
$$
 and
\n
$$
i(\gamma, \gamma_{23}) = 2|N_S(\gamma) - I_Y(\gamma)| + |I_X(\gamma) - I_Y(\gamma)| + I_X(\gamma) - I_Y(\gamma).
$$

Proof of the geometric intersection formula. It is easy to see that the geometric intersection formula is valid if γ_1 or γ_2 is in $\{\gamma_T, \gamma_S\}$. It remains to prove the formula for $\gamma_1, \gamma_2 \in \widehat{\mathscr{G}}$.

For every integer k, write $F_k = \mathcal{I}_2^{-k} \mathcal{I}_1^k$. From Proposition 2.8, we obtain

$$
I_{XY}(\gamma_1, \gamma_2) = I_{XY}(F_k(\gamma_1), F_k(\gamma_2)),
$$

\n
$$
I_X(\gamma_1)N_T(\gamma_2) - I_X(\gamma_2)N_T(\gamma_1) = I_X(F_k(\gamma_1))N_T(F_k(\gamma_2)) - I_X(F_k(\gamma_2))N_T(F_k(\gamma_1)),
$$

\n
$$
I_Y(\gamma_1)N_S(\gamma_2) - I_Y(\gamma_2)N_S(\gamma_1) = I_Y(F_k(\gamma_1))N_S(F_k(\gamma_2)) - I_Y(F_k(\gamma_2))N_S(F_k(\gamma_1))
$$

for all integers k . From Proposition 2.2 and Proposition 2.8, there is an integer $k > 0$ such that

$$
N_T(F_k(\gamma_j)) \ge 2I_X(\gamma_j) = 2I_X(F_k(\gamma_j)) \text{ and } N_S(F_k(\gamma_j)) \ge 2I_Y(\gamma_j) = 2I_Y(F_k(\gamma_j))
$$

for $j = 1, 2$; thus we may assume that

$$
N_T(\gamma_j) \ge 2I_X(\gamma_j)
$$
 and $N_S(\gamma_j) \ge 2I_Y(\gamma_j)$.

Figure 5. From the left to the right: τ_1 , τ_2 , τ_3 .

If $\beta \in \hat{\mathscr{G}}$ is a geodesic with $N_T(\beta) \geq 2I_X(\beta)$ and $N_S(\beta) \geq 2I_Y(\beta)$, then β lies in $\mathscr{G}_S^+ \cap \mathscr{G}_T^+$, and β can be written as

$$
\beta = p\gamma_S + q\gamma_T + r\tau_1 + s\tau_2 \quad \text{or} \quad \beta = p\gamma_S + q\gamma_T + r\tau_1 + s\tau_3,
$$

where p, q, r and s are non-negative integers with $p + q + r + s > 0$, and where $τ_1$, $τ_2$ and $τ_3$ are geodesics represented by the following cyclic reduced Γ-words (see Figure 5):

$$
W(\tau_1) = S^{-1}Y^{-1}STXT^{-1}, \quad W(\tau_2) = S^{-1}TXT^{-1} \quad \text{and} \quad W(\tau_3) = S^{-1}Y^{-1}ST.
$$

Let \mathscr{GL}_1 be the set of all elements of \mathscr{GL} of the form $p\gamma_S + q\gamma_T + r\tau_1 + s\tau_2$, and let \mathscr{GL}_2 be the set of all elements of \mathscr{GL} of the form $p\gamma_S + q\gamma_T + r\tau_1 + s\tau_3$, where p, q, r and s are non-negative integers with $p + q + r + s > 0$.

Let $\mathscr D$ be the fundamental domain for G given in Section 1.2. Let $\mathscr R$ denote the reflection in the imaginary axis. Let l^* be the semi-circle contained in \mathscr{D}

joining the fixed point of $S^{-1}T$ to the fixed point of TS^{-1} . Note that l^* is invariant under \mathscr{R} . Let

 P^* be the point of intersection of l^* with the imaginary axis,

 \mathscr{D}^+ be the connected component of $\mathscr{D} - l^*$ lying above l^* ,

 \mathscr{D}^- be the connected component of $\mathscr{D} - l^*$ lying below l^* ,

 Σ_5^+ and Σ_5^- be the projections of \mathscr{D}^+ and \mathscr{D}^- to Σ_5 , respectively,

 \mathscr{S}_4^+ be the four-punctured sphere obtained from $\mathscr{D}^+ - \{P^*\}$ by identifying the boundary points of $\mathscr{D}^+ - \{P^*\}$ via X, T and \mathscr{R} ,

 \mathscr{S}_4^- be the four-punctured sphere obtained from $\mathscr{D}^- - \{P^*\}\;$ by identifying the boundary points of $\mathscr{D}^- - \{P^*\}$ via Y, S and \mathscr{R} , and

 γ^* be the projection of l^* to Σ_5 , which is the common boundary of Σ_5^+ and Σ_5^- . The free homotopy class containing γ^* is also denoted by γ^* .

The fixed point ζ of $S^{-1}T$ projects to a puncture ζ^+ on \mathscr{S}_4^+ , and projects to a puncture ζ^- on \mathscr{S}_4^- . Let $[\zeta^+]$ denote the free homotopy class of simple loops on \mathscr{S}_4^+ enclosing ζ^+ , and let $[\zeta^-]$ denote the free homotopy class of simple loops on \mathscr{S}_4^- enclosing ζ^- . It is obvious that $i([\zeta^+], \alpha) = 0$ for all free homotopy classes α of multiple simple loops on \mathscr{S}_4^+ , and that $i([\zeta^-], \beta) = 0$ for all free homotopy classes β of multiple simple loops on \mathscr{S}_4^- .

For any reduced simple loop α in the free homotopy class $\gamma \in \mathscr{G}$, let

$$
\alpha^+ = \alpha \cap \Sigma_5^+
$$
 and $\alpha^- = \alpha \cap \Sigma_5^-.$

We shall call a connected component of the lift of α^+ to $\mathscr D$ a strand of α^+ , and call a connected component of the lift of α^- to $\mathscr D$ a strand of α^- . Let

 $\gamma^+ = \{ \alpha^+ : \alpha \text{ is a reduced simple loop in the free homotopy class } \gamma \}$ and $\gamma^- = {\alpha^- : \alpha$ is a reduced simple loop in the free homotopy class γ .

See Figure 6 for examples of γ^+ and γ^- . When there is no risk of confusion, we shall also use γ^+ and γ^- to represent any curve in them. Since the geodesic γ_T is disjoint from Σ_5^- , we shall also write $\gamma_T^+ = \gamma_T$. Similarly, write $\gamma_S^- = \gamma_S$.

If $\gamma = a\gamma_T + b\gamma_S + c\tau_1 + d\tau_2$ is an arbitrary geodesic in $\mathscr{G} \cap \mathscr{GL}_1$, then $\gamma^$ has 2d strands whose union is homotopic to d copies of τ_2^- . We shall call such strands τ_2^- -type strands of γ^- .

If $\gamma = a\gamma_T + b\gamma_S + c\tau_1 + d\tau_3$ is an arbitrary geodesic in $\mathscr{G} \cap \mathscr{GL}_2$, then γ^+ has 2d strands whose union is homotopic to d copies of τ_3^+ . We shall call such strands τ_3^+ -type strands of γ^+ .

Let $\gamma \in \widehat{\mathscr{G}} \cap (\mathscr{GL}_1 \cup \mathscr{GL}_2)$ be a geodesic, and write

$$
\gamma = a\gamma_T + b\gamma_S + c\tau_1 + d\tau_2 \quad \text{or} \quad \gamma = a\gamma_T + b\gamma_S + c\tau_1 + d\tau_3.
$$

Then $i(\gamma, \gamma^*) = 2(c+d)$ since

$$
i(a\gamma_T + b\gamma_S + c\tau_1 + d\tau_2, \gamma^*) = 2(c+d) = i(a\gamma_T + b\gamma_S + c\tau_1 + d\tau_3, \gamma^*).
$$

Set $k = c + d$. Every simple closed curve α in the homotopy class γ is homotopic to a simple loop $\hat{\alpha}$ with the following properties:

(i) The lift of $\hat{\alpha}$ to \mathscr{D} intersects $l^* - \{P^*\}\$ at $P_1, \ldots, P_k, P'_1, \ldots, P'_k$ with $P'_j = \mathscr{R}(P_j).$

(ii) The endpoints of strands of $\hat{\alpha}$ coincide with that of α . Then $\hat{\alpha}^+$ projects to \mathscr{S}_4^+ a multiple simple loop $\tilde{\alpha}^+$, and $\hat{\alpha}^-$ projects to \mathscr{S}_4^- a multiple simple loop $\tilde{\alpha}^-$. Let $\tilde{\gamma}^+$ denote the free homotopy class of multiple simple loops on \mathscr{S}_4^+ represented by $\tilde{\alpha}^+$, and let $\tilde{\gamma}^-$ denote the free homotopy class of multiple simple loops on \mathscr{S}_4^- represented by $\tilde{\alpha}^-$.

If $\gamma = a\gamma_T + b\gamma_S + c\tau_1 + d\tau_2$ with $c + d > 0$, then

$$
\tilde{\gamma}^+ = a\gamma_T + (c+d)\tilde{\tau}_1^+ \quad \text{and} \quad \tilde{\gamma}^- = \{b\gamma_S + c\tilde{\tau}_1^-\} \oplus d[\zeta^-].
$$

If $\gamma = a\gamma_T + b\gamma_S + c\tau_1 + d\tau_3$ with $c + d > 0$, then

$$
\tilde{\gamma}^+ = \{a\gamma_T + c\tilde{\tau}_1^+\} \oplus d[\zeta^+] \quad \text{and} \quad \tilde{\gamma}^- = b\gamma_S + (c+d)\tilde{\tau}_1^-.
$$

Now we are in the position to compute $i(\gamma_1, \gamma_2)$ for $\gamma_1, \gamma_2 \in \hat{\mathscr{G}} \cap (\mathscr{GL}_1 \cup$ \mathscr{GL}_2). Without loss of generality, we may assume that all points of intersection of γ_1 and γ_2 are not on γ^* .

Case 1. Assume that $\gamma_1, \gamma_2 \in \hat{\mathscr{G}} \cap \mathscr{GL}_1$. Clearly, $I_{XY}(\gamma_1, \gamma_2) \geq 0$ and $|I_{XY}(\gamma_1, \gamma_2)| - I_{XY}(\gamma_1, \gamma_2) = 0$. By applying suitable homotopy maps to γ_1 and γ_2 , we may assume that τ_2^- -type strands of γ_1^- are disjoint from γ_2 , and that τ_2^- -type strands of γ_2^- are disjoint from γ_1 . Then by Theorem 2.6 of [4] we obtain

$$
i(\gamma_1, \gamma_2) = i(\gamma_1^+, \gamma_2^+) + i(\gamma_1^-, \gamma_2^-) = i(\tilde{\gamma}_1^+, \tilde{\gamma}_2^+) + i\tilde{\gamma}_1^-, \tilde{\gamma}_2^-)
$$

\n
$$
= 2|I_X(\gamma_1)N_T(\gamma_2) - I_X(\gamma_2)N_T(\gamma_1)| + 2|I_Y(\gamma_1)N_S(\gamma_2) - I_Y(\gamma_2)N_S(\gamma_1)|
$$

\n
$$
= 2|I_X(\gamma_1)N_T(\gamma_2) - I_X(\gamma_2)N_T(\gamma_1)| + 2|I_Y(\gamma_1)N_S(\gamma_2) - I_Y(\gamma_2)N_S(\gamma_1)|
$$

\n
$$
+ |I_{XY}(\gamma_1, \gamma_2)| - I_{XY}(\gamma_1, \gamma_2).
$$

Case 2. If $\gamma_1, \gamma_2 \in \hat{\mathscr{G}} \cap \mathscr{GL}_2$, then $\Theta_1 \Theta_2(\gamma_1)$ and $\Theta_1 \Theta_2(\gamma_2)$ are both in $\widehat{\mathscr{G}} \cap \mathscr{GL}_1$, and the geometric intersection formula is valid for this case by Proposition 2.1.

Case 3. Assume that $\gamma_1 \in \widehat{\mathscr{G}} \cap \mathscr{GL}_1$ and $\gamma_2 \in \widehat{\mathscr{G}} \cap \mathscr{GL}_2$. Write

 $\gamma_1 = a\gamma_T + b\gamma_S + c\tau_1 + d\tau_2$ and $\gamma_2 = a'\gamma_T + b'\gamma_S + c'\tau_1 + d'\tau_3$,

where $dd' > 0$. Clearly, $I_{XY}(\gamma_1, \gamma_2) < 0$ and

 $|I_{XY}(\gamma_1, \gamma_2)| - I_{XY}(\gamma_1, \gamma_2) = 2dd'.$

Write the union of τ_2^- -type strands of γ_1^- as $d\tau_2^-$, and write the union of τ_3^+ -type strands of γ_2^+ as $d'\tau_3^+$.

To compute $i(d\tau_2^-,\gamma_2^-)+i(\gamma_1^+,d'\tau_3^+)$, we need the orientation on the S-side and that on the S^{-1} -side (see the proof of Proposition 1.1). Also, we need an orientation to the T -side and an orientation to the T^{-1} -side.

Recall that ζ is the fixed point of the transformation $S^{-1}T$. If P and P' are two distinct points on the T^{-1} -side, and if P lies between ζ and P', then we write $P \prec P'$. For any two distinct points Q and Q' on the T-side, if $T^{-1}(Q) \prec T^{-1}(Q')$, then we write $Q \prec Q'$.

Let $m = a' + 2c' + d'$ and $n = b' + 2c' + 2d'$. Let

 $P_1 \prec \cdots \prec P_m$ be the endpoints of strands of γ_2 on the T-side,

 $Q_1 \prec \cdots \prec Q_n$ be the endpoints of the strands of γ_2 on the S-side,

 $L^{(2)}_i$ ⁽²⁾ be the strand of γ_2 with P_j an endpoint, $1 \leq j \leq d'$,

 $l_i^{(2)}$ $j^{(2)}$ be the strand of γ_2 with Q_j an endpoint, $1 \leq j \leq d'$,

 $A_1 \prec \cdots \prec A_d$ be the first d points on the S-side where the lift of γ_1 meets, A'_{j} be the point on the S^{-1} -side identified with A_{j} by S^{-1} , $1 \leq j \leq d$,

 $L^{(1)}_i$ $j_j^{(1)}$ be the strand of γ_1 with A'_j an endpoint, $1 \leq j \leq d$, and

 $l_i^{(1)}$ $j_j^{(1)}$ be the strand of γ_1 with A_j an endpoint, $1 \leq j \leq d$.

Note that $L_i^{(1)}$ $j_j^{(1)}$ connects the S^{-1} -side to the T-side, and each $l_j^{(1)}$ $j^{(1)}$ connects the S-side to the T-side. Let B_j be the endpoint of $l_j^{(1)}$ $j^{(1)}$ on the T-side. It is clear that $B_1 \prec \cdots \prec B_d$.

Figure 7.

Without loss of generality, we assume that $i(\gamma_1^+, d'\tau_3^+) = 0$, and that the union L of all $L_i^{(1)}$ $j_j^{(1)}$ is disjoint from γ_2 (see Figure 7). Then

$$
P_{d'} \prec B_1 \prec \cdots \prec B_d \prec P_{d'+1}
$$
 and $Q_{d'} \prec A_1 \prec \cdots \prec A_d \prec Q_{d'+1}$.

This implies that each $l_i^{(1)}$ $j^{(1)}$ intersects all $L_i^{(2)}$ $i^{(2)}$ and all $l^{(2)}_i$ $i^{(2)}$ transversally. Then

$$
i(d\tau_2^-,\gamma_2^-)=2dd'.
$$

By Theorem 2.6 of [4] again, we complete the proof of Theorem 3.1 as follows:

$$
i(\gamma_1, \gamma_2) = i(\gamma_1^+, \gamma_2^+) + i(\gamma_1^-, \gamma_2^-)
$$

= $i(\tilde{\gamma}_1^+, \tilde{\gamma}_2^+) + i(\tilde{\gamma}_1^-, \tilde{\gamma}_2^-) + i(d\tau_2^-, \gamma_2^-) + i(\gamma_1^+, d'\tau_3^+)$
= $i(a\gamma_T + (c + d)\tilde{\tau}_1^+, a'\gamma_T + c'\tilde{\tau}_1^+)$
+ $i(b\gamma_S + c\tilde{\tau}_1^-, b'\gamma_S + (c' + d')\tilde{\tau}_1^-) + 2dd'$
= $2|I_X(\gamma_1)N_T(\gamma_2) - I_X(\gamma_2)N_T(\gamma_1)| + 2|I_Y(\gamma_1)N_S(\gamma_2) - I_Y(\gamma_2)N_S(\gamma_1)|$
+ $|I_{XY}(\gamma_1, \gamma_2)| - I_{XY}(\gamma_1, \gamma_2).$

3.2. Elementary intersection numbers of multiple simple loops. In the rest of this section, we shall prove the following proposition.

Proposition 3.3. If $\alpha \in \mathscr{GL}$, and if k is an integer, then

$$
i(\mathcal{F}_j^k(\alpha), \gamma_{11}) = i(\alpha, \gamma_{11}), \quad i(\mathcal{F}_j^k(\alpha), \gamma_{21}) = i(\alpha, \gamma_{21}) \quad \text{for } j = 1, 2,
$$

\n
$$
i(\mathcal{F}_1^k(\alpha), \gamma_{1j}) = i(\alpha, \gamma_{1j}), \quad i(\mathcal{F}_2^k(\alpha), \gamma_{2j}) = i(\alpha, \gamma_{2j}) \quad \text{for } j = 2, 3,
$$

\n
$$
i(\mathcal{F}_2^k(\alpha), \gamma_{12}) = 2|N_T(\alpha) - kI_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha),
$$

\n
$$
i(\mathcal{F}_2^k(\alpha), \gamma_{13}) = 2|N_T(\alpha) - (k+1)I_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha),
$$

\n
$$
i(\mathcal{F}_1^k(\alpha), \gamma_{22}) = 2|N_S(\alpha) + kI_Y(\alpha)| + |I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha),
$$
 and
\n
$$
i(\mathcal{F}_1^k(\alpha), \gamma_{23}) = 2|N_S(\alpha) + (k-1)I_Y(\alpha)| + |I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha).
$$

By letting $k = 0$ in the last four equations of the above proposition, we have **Corollary 3.4** (Elementary intersection numbers). If $\alpha \in \mathscr{GL}$, then

$$
i(\alpha, \gamma_{12}) = 2|N_T(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha),
$$

\n
$$
i(\alpha, \gamma_{13}) = 2|N_T(\alpha) - I_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha),
$$

\n
$$
i(\alpha, \gamma_{22}) = 2|N_S(\alpha)| + |I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha),
$$
 and
\n
$$
i(\alpha, \gamma_{23}) = 2|N_S(\alpha) - I_Y(\alpha)| + |I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha).
$$

Lemma 3.5. Let γ and $\gamma' \in \mathscr{G}$ be disjoint geodesics, and let $\alpha = a\gamma \oplus b\gamma'$, where $a \geq 0$ and $b \geq 0$ are integers with $a + b > 0$. Then for all integers k

$$
N_T(\mathcal{I}_1^k(\alpha)) = N_T(\alpha), \quad N_T(\mathcal{I}_2^k(\alpha)) = N_T(\alpha) - kI_X(\alpha),
$$

$$
N_S(\mathcal{I}_2^k(\alpha)) = N_S(\alpha), \quad N_S(\mathcal{I}_1^k(\alpha)) = N_S(\alpha) + kI_Y(\alpha).
$$

Proof. Since $N_E(\alpha) = aN_E(\gamma) + bN_E(\gamma')$ for $E = S$ or T, from Proposition 2.8 we obtain

$$
N_T(\mathcal{F}_1^k(\alpha)) = aN_T(\mathcal{F}_1^k(\gamma)) + bN_T(\mathcal{F}_1^k(\gamma'))
$$

= $aN_T(\gamma) + bN_T(\gamma') = N_T(\alpha)$ and

$$
N_T(\mathcal{F}_2^k(\alpha)) = aN_T(\mathcal{F}_2^k(\gamma)) + bN_T(\mathcal{F}_2^k(\gamma'))
$$

= $a\{N_T(\gamma) - kI_X(\gamma)\} + b\{N_T(\gamma') - kI_X(\gamma')\} = N_T(\alpha) - kI_X(\alpha).$

Similarly, $N_S(\mathcal{I}_2^k(\alpha)) = N_S(\alpha)$ and $N_S(\mathcal{I}_1^k(\alpha)) = N_S(\alpha) + kI_Y(\alpha)$.

Lemma 3.5. If γ and γ' are two disjoint geodesics in \mathscr{G} , then

$$
(N_T(\gamma) - I_X(\gamma))(N_T(\gamma') - I_X(\gamma')) \ge 0,
$$

\n
$$
(N_T(\gamma) + I_X(\gamma))(N_T(\gamma') + I_X(\gamma')) \ge 0,
$$

\n
$$
(N_S(\gamma) - I_Y(\gamma))(N_S(\gamma') - I_Y(\gamma')) \ge 0,
$$

\n
$$
(N_S(\gamma) + I_Y(\gamma))(N_S(\gamma') + I_Y(\gamma')) \ge 0.
$$

Proof. We shall prove that $(N_T(\gamma) - I_X(\gamma)) (N_T(\gamma') - I_X(\gamma')) \geq 0$. The other three inequalities will follow by a similar argument.

From Lemma 2.4, we have $N_T(\gamma)N_T(\gamma')\geq 0$, then

$$
(N_T(\gamma) - I_X(\gamma)) (N_T(\gamma') - I_X(\gamma')) \ge 0 \text{ when } N_T(\gamma) \le 0.
$$

Now, consider the case where $N_T(\gamma) \geq 0$, and suppose that

$$
(N_T(\gamma) - I_X(\gamma))\big(N_T(\gamma') - I_X(\gamma')\big) < 0.
$$

Without loss of generality, we assume that

$$
N_T(\gamma) > I_X(\gamma)
$$
 and $0 \le N_T(\gamma') < I_X(\gamma').$

There is a strand l_1 of γ joining the X-side to the T^{-1} -side, and there is a strand l_2 of γ joining the X^{-1} -side to the T^{-1} -side.

Let $m = I_X(\gamma') > 0$. There exist m strands L_1, \ldots, L_m of γ' with endpoints on the X^{-1} -side.

If every L_j connects the X^{-1} -side to the T^{-1} -side, then $N_T(\gamma') \geq m =$ $I_X(\gamma')$. This is a contradiction to the assumption. Therefore, there is an integer j such that L_j connects the X^{-1} -side to the E-side with $E \neq T^{-1}$. This implies $L_j \cap (l_1 \cup l_2) \neq \emptyset$. This is impossible since γ and γ' are disjoint.

Lemma 3.7. Let $\gamma, \gamma' \in \mathscr{G}$ be two disjoint geodesics, and let $\alpha = a\gamma \oplus b\gamma'$, where $a \ge 0$ and $b \ge 0$ are integers with $a + b > 0$. Then

$$
\{I_X(\gamma) - I_Y(\gamma)\} \cdot \{I_X(\gamma') - I_Y(\gamma')\} \ge 0,
$$

and thus

$$
|I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha) = a\{|I_X(\gamma) - I_Y(\gamma)| + I_X(\gamma) - I_Y(\gamma)\}\n+ b\{|I_X(\gamma') - I_Y(\gamma')| + I_X(\gamma') - I_Y(\gamma')\};
$$

\n
$$
|I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha) = a\{|I_Y(\gamma) - I_X(\gamma)| + I_Y(\gamma) - I_X(\gamma)\}\n+ b\{|I_Y(\gamma') - I_X(\gamma')| + I_Y(\gamma') - I_X(\gamma')\}.
$$

Proof. If $\gamma \in \{\gamma_T, \gamma_S\}$ or $\gamma' \in \{\gamma_T, \gamma_S\}$, then

$$
\{I_X(\gamma) - I_Y(\gamma)\} \cdot \{I_X(\gamma') - I_Y(\gamma')\} = 0.
$$

In the following, we assume that $\gamma, \gamma' \in \mathscr{G}$.

Now, choose an integer $k > 0$ such that

$$
N_T(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\gamma)) \ge 2I_X(\gamma) = 2I_X(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\gamma)),
$$

\n
$$
N_S(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\gamma)) \ge 2I_Y(\gamma) = 2I_Y(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\gamma)),
$$

\n
$$
N_T(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\gamma')) \ge 2I_X(\gamma') = 2I_X(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\gamma')),
$$

\n
$$
N_S(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\gamma')) \ge 2I_Y(\gamma') = 2I_Y(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\gamma')).
$$

Since for $E = X$ or Y

$$
I_E(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\alpha)) = aI_E(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\gamma)) + bI_E(\mathcal{I}_2^{-k}\mathcal{I}_1^k(\gamma'))
$$

= $aI_E(\gamma) + bI_E(\gamma') = I_E(\alpha),$

we may assume that

$$
N_T(\gamma) \ge 2I_X(\gamma)
$$
, $N_S(\gamma) \ge 2I_Y(\gamma)$, $N_T(\gamma') \ge 2I_X(\gamma')$, $N_S(\gamma') \ge 2I_Y(\gamma')$.

Let \mathscr{GL}_1 and \mathscr{GL}_2 be the subsets of \mathscr{GL} given in the proof of Theorem 3.1. If γ and γ' both are in \mathscr{GL}_1 , write

$$
\gamma = p\gamma_S + q\gamma_T + r\tau_1 + s\tau_2
$$
 and $\gamma' = p'\gamma_S + q'\gamma_T + r'\tau_1 + s'\tau_2$.

Then

$$
\{I_X(\gamma) - I_Y(\gamma)\} \cdot \{I_X(\gamma') - I_Y(\gamma')\} = ss' \ge 0.
$$

Similarly,

$$
\{I_X(\gamma) - I_Y(\gamma)\} \cdot \{I_X(\gamma') - I_Y(\gamma')\} \ge 0
$$

if γ and γ' both are in \mathscr{GL}_2 .

Finally, assume that $\gamma \in \mathscr{GL}_1$ and $\gamma' \in \mathscr{GL}_2$, and write

 $\gamma = p\gamma_S + q\gamma_T + r\tau_1 + s\tau_2 \quad \text{and} \quad \gamma' = p'\gamma_S + q'\gamma_T + r'\tau_1 + s'\tau_3.$

If $ss' > 0$, then $i(\gamma, \gamma') > 0$. This is impossible. Thus $ss' = 0$. This implies that both γ and γ' are either in \mathscr{GL}_1 or in \mathscr{GL}_2 , and completes the proof.

Proof of Proposition 3.3. It follows from equation (3) and Proposition 2.2, we have

$$
i(\mathcal{I}_j^k(\alpha), \gamma_{11}) = i(\alpha, \gamma_{11}), \quad i(\mathcal{I}_j^k(\alpha), \gamma_{21}) = i(\alpha, \gamma_{21}) \quad \text{for } j = 1, 2.
$$

Since γ_{1j} is invariant under \mathcal{T}_1 , and since γ_{2j} is invariant under \mathcal{T}_2 for $j = 2, 3$, then

$$
i(\mathcal{F}_1^k(\alpha), \gamma_{1j}) = i(\alpha, \mathcal{F}_1^{-k}(\gamma_{1j})) = i(\alpha, \gamma_{1j}), \text{ and}
$$

$$
i(\mathcal{F}_2^k(\alpha), \gamma_{2j}) = i(\alpha, \mathcal{F}_2^{-k}(\gamma_{2j})) = i(\alpha, \gamma_{2j}).
$$

It remains to prove the last four equations given in the proposition. In the following, a and b are assumed to be non-negative integers with $a + b > 0$.

If $\alpha = a\gamma_S \oplus b\gamma_T$, then α is invariant under \mathscr{T}_j for $j = 1, 2$, and $I_E(\alpha) = 0$ for $E = X$, Y . Thus the equations hold trivially.

Let $\gamma \in \widehat{\mathscr{G}}$ be a geodesic disjoint from γ_S . If $\alpha = a\gamma \oplus b\gamma_S$, then

$$
I_Y(\gamma) = 0 = I_Y(\alpha)
$$
, $N_S(\gamma) = 0$ and $N_S(\alpha) = b$.

Since $I_Y(\gamma) = 0$, then γ is invariant under \mathcal{T}_1 , and so is α . From Corollary 3.2 and Lemma 3.7, we have

$$
|I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha) = 2aI_X(\gamma)
$$

and

$$
i(\mathcal{F}_1^k(\alpha), \gamma_{22}) = ai(\gamma, \gamma_{22}) + bi(\gamma_S, \gamma_{22}) = 2aI_X(\gamma) + 2b
$$

= 2|N_S(\alpha) + kI_Y(\alpha)| + |I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha);

$$
i(\mathcal{F}_1^k(\alpha), \gamma_{23}) = ai(\gamma, \gamma_{23}) + bi(\gamma_S, \gamma_{23}) = 2aI_X(\gamma) + 2b
$$

= 2|N_S(\alpha) + (k - 1)I_Y(\alpha)| + |I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha).

Since γ_S is invariant under \mathcal{T}_2 , and $i(\gamma_S, \gamma_{1j}) = 0$ for $j = 1, 2$, then

$$
i(\mathcal{I}_2^k(\alpha), \gamma_{1j}) = ai(\mathcal{I}_2^k(\gamma), \gamma_{1j}).
$$

Since $I_X(\alpha) = aI_X(\gamma)$, and since $N_T(\alpha) = aN_T(\gamma)$, from Corollary 3.2 and Lemma 3.5 we have

$$
i(\mathcal{I}_2^k(\alpha), \gamma_{12}) = 2|N_T(\alpha) - kI_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha);
$$

$$
i(\mathcal{I}_2^k(\alpha), \gamma_{13}) = 2|N_T(\alpha) - (k+1)I_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha).
$$

By a similar argument as above, one proves that the last four equations hold for $\alpha = a\gamma \oplus b\gamma_T$, where $\gamma \in \widehat{\mathscr{G}}$ is a geodesic disjoint from γ_T .

Finally, we consider the free homotopy classes $\alpha = a\gamma \oplus b\gamma'$, where γ and γ' are disjoint geodesics in $\hat{\mathscr{G}}$. If $ab = 0$, the equations hold trivially by Corollary 3.2.

Assume that $a > 0$ and $b > 0$. Then $I_X(\alpha)I_Y(\alpha) > 0$. Otherwise, say $I_Y(\alpha) = 0$, we have $I_Y(\gamma) = I_Y(\gamma') = 0$. This is impossible since any two distinct simple closed geodesics on a four-punctured sphere must meet (see [4, Theorem 2.5] and [4, Theorem 2.6]).

Note that the last three equations given in the proposition follow from the equation

$$
i(\mathcal{I}_2^k(\alpha), \gamma_{12}) = 2|N_T(\alpha) - kI_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha).
$$

Since

$$
i(\mathcal{I}_2^k(\alpha), \gamma_{13}) = i(\mathcal{I}_2^k(\alpha), \mathcal{I}_2^{-1}(\gamma_{12})) = i(\mathcal{I}_2^{k+1}(\alpha), \gamma_{12}),
$$

then

$$
i(\mathcal{I}_2^k(\alpha), \gamma_{13}) = 2|N_T(\alpha) - (k+1)I_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha).
$$

Because $\mathcal{I}_1^k = \Theta_2 \mathcal{I}_2^k \Theta_2$, from Propositions 2.1 and 2.4 we obtain

$$
i(\mathcal{I}_1^k(\alpha), \gamma_{22}) = i(\Theta_2 \mathcal{I}_2^k \Theta_2(\alpha), \gamma_{22}) = i(\mathcal{I}_2^k \Theta_2(\alpha), \Theta_2(\gamma_{22})) = i(\mathcal{I}_2^k \Theta_2(\alpha), \gamma_{12})
$$

$$
= 2|N_T(\Theta_2(\alpha)) - kI_X(\Theta_2(\alpha))| + |I_Y(\Theta_2(\alpha)) - I_X(\Theta_2(\alpha))|
$$

$$
+ I_Y(\Theta_2(\alpha)) - I_X(\Theta_2(\alpha))
$$

$$
= 2| - N_S(\alpha) - kI_Y(\alpha)| + |I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha)
$$

$$
= 2|N_S(\alpha) + kI_Y(\alpha)| + |I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha)
$$

and

$$
i(\mathcal{F}_1^k(\alpha), \gamma_{23}) = i(\mathcal{F}_1^k(\alpha), \mathcal{F}_1(\gamma_{22})) = i(\mathcal{F}_1^{k-1}(\alpha), \gamma_{22})
$$

= 2|N_S(\alpha) + (k - 1)I_Y(\alpha)| + |I_X(\alpha) - I_Y(\alpha)| + I_X(\alpha) - I_Y(\alpha).

Now, we shall prove the equation

$$
i(\mathscr{T}_2^k(\alpha), \gamma_{12}) = 2|N_T(\alpha) - kI_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha).
$$

From Proposition 2.8, Lemma 3.5 and Lemma 3.7, we obtain

$$
i(\mathcal{I}_2(\alpha), \gamma_{12}) = ai(\mathcal{I}_2(\gamma), \gamma_{12}) + bi(\mathcal{I}_2(\gamma'), \gamma_{12})
$$

\n
$$
= 2a|N_T(\mathcal{I}_2(\gamma))| + 2b|N_T(\mathcal{I}_2(\gamma'))|
$$

\n
$$
+ a\{|I_Y(\mathcal{I}_2(\gamma)) - I_X(\mathcal{I}_2(\gamma))| + I_Y(\mathcal{I}_2(\gamma)) - I_X(\mathcal{I}_2(\gamma))\}
$$

\n
$$
+ b\{|I_Y(\mathcal{I}_2(\gamma')) - I_X(\mathcal{I}_2(\gamma'))| + I_Y(\mathcal{I}_2(\gamma')) - I_X(\mathcal{I}_2(\gamma'))\}
$$

\n
$$
= 2a|N_T(\gamma) - I_X(\gamma)| + 2b|N_T(\gamma') - I_X(\gamma')|
$$

\n
$$
+ a\{|I_Y(\gamma) - I_X(\gamma)| + I_Y(\gamma) - I_X(\gamma)\}
$$

\n
$$
+ b\{|I_Y(\gamma') - I_X(\gamma')| + I_Y(\gamma') - I_X(\gamma')\}
$$

\n
$$
= 2|a\{N_T(\gamma) - I_X(\gamma)\} + b\{N_T(\gamma') - I_X(\gamma')\}|
$$

\n
$$
+ |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha)
$$

\n
$$
= 2|N_T(\alpha) - I_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha).
$$

If $k > 1$, by Lemma 3.5 we have

$$
i(\mathcal{I}_{2}^{k}(\alpha), \gamma_{12}) = 2|N_{T}(\mathcal{I}_{2}^{k-1}(\alpha)) - I_{X}(\mathcal{I}_{2}^{k-1}(\alpha))| + |I_{Y}(\mathcal{I}_{2}^{k-1}(\alpha)) - I_{X}(\mathcal{I}_{2}^{k-1}(\alpha))| + I_{Y}(\mathcal{I}_{2}^{k-1}(\alpha)) - I_{X}(\mathcal{I}_{2}^{k-1}(\alpha)) = 2|N_{T}(\alpha) - kI_{X}(\alpha)| + |I_{Y}(\alpha) - I_{X}(\alpha)| + I_{Y}(\alpha) - I_{X}(\alpha).
$$

By the same reasoning as above, one shows

$$
i(\mathcal{T}_2^{-1}(\alpha), \gamma_{12}) = 2|N_T(\alpha) + I_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha).
$$

Thus for $k > 1$

$$
i(\mathcal{I}_2^{-k}(\alpha), \gamma_{12}) = 2|N_T(\mathcal{I}_2^{-k+1}(\alpha)) - I_X(\mathcal{I}_2^{-k+1}(\alpha))| + |I_Y(\mathcal{I}_2^{-k+1}(\alpha)) + I_X(\mathcal{I}_2^{-k+1}(\alpha))| + I_Y(\mathcal{I}_2^{-k+1}(\alpha)) - I_X(\mathcal{I}_2^{-k+1}(\alpha)) = 2|N_T(\alpha) + kI_X(\alpha)| + |I_Y(\alpha) - I_X(\alpha)| + I_Y(\alpha) - I_X(\alpha).
$$

4. A homeomorphism of $\overline{\pi\mathcal{I}(\mathcal{G})}$ onto a 3-sphere

Now, we are ready to construct a homeomorphism of $\overline{\pi\mathscr{I}(\mathscr{G})}$ onto a 3-sphere. Let $\Pi = \{ (r_1, r_2, \ldots, r_6) \in \mathbb{R}_+^6 : r_1 + r_2 + \cdots + r_6 = 1 \}$, and let $\mathscr{C} = \Pi_1 \cup \Pi_2 \cup \Pi_3$, where

$$
\Pi_1 = \{ (r_1, r_2, r_3) \in \mathbf{R}_+^3 : r_2 + r_3 = r_1 \},
$$

\n
$$
\Pi_2 = \{ (r_1, r_2, r_3) \in \mathbf{R}_+^3 : r_1 + r_3 = r_2 \},
$$

\n
$$
\Pi_3 = \{ (r_1, r_2, r_3) \in \mathbf{R}_+^3 : r_1 + r_2 = r_3 \}.
$$

Following Poénaru ([5], Exposé 4), we shall first construct a function Ψ of $\mathcal{I}(\mathcal{GL})$ into $(\mathcal{C} \times \mathcal{C}) \cap \Pi$ so that its extension to $\pi^{-1}\pi\mathcal{I}(\mathcal{GL})$ satisfies

$$
\Psi(t I_{\alpha}) = \Psi(I_{\alpha}) \quad \text{for } \alpha \in \mathscr{GL} \text{ and for } t > 0.
$$

Thus Ψ induces a function on $\pi \mathcal{I}(\mathcal{GL})$, also denoted by Ψ .

By using a continuity argument, we extend Ψ to $\overline{\pi\mathscr{I}(\mathscr{G})}$, and prove that Ψ is a homeomorphism of $\overline{\pi\mathscr{I}(\mathscr{G})}$ onto a 3-sphere lying in \mathbb{R}^6 (Theorem 4.3). Finally, by postcomposing Ψ by a function from \mathbf{R}^6 into \mathbf{R}^4 , we will get a homeomorphism of $\overline{\pi\mathscr{I}(\mathscr{G})}$ into a 3-sphere lying in \mathbb{R}^4 (Theorem 4.4).

4.1. The definition of Ψ on \mathscr{GL} . For integers $i \in \{1,2\}$ and $j \in \{1,2,3\}$, and for $\alpha \in \mathscr{GL}$, let

$$
x_{ij}(\alpha) = \frac{i(\alpha, \gamma_{ij})}{\lambda(\alpha)},
$$
 where $\lambda(\alpha) = \sum_{i=1}^{2} \sum_{j=1}^{3} i(\alpha, \gamma_{ij}),$

and let $\psi_1: \mathscr{GL} \longrightarrow \mathbf{R}^6_+$ be defined by

$$
\psi_1(\alpha) = (x_{11}(\alpha), x_{12}(\alpha), x_{13}(\alpha), x_{21}(\alpha), x_{22}(\alpha), x_{23}(\alpha)).
$$

Note that the image of ψ_1 lies in Π since $\sum_{i=1}^2 \sum_{j=1}^3 x_{ij}(\alpha) = 1$ for all $\alpha \in \mathscr{GL}$. To construct a function of \mathscr{GL} into $(\mathscr{C} \times \mathscr{C}) \cap \Pi$, we form the sum

$$
\rho(\alpha) = 2\{I_X(\alpha) + I_Y(\alpha) + |N_T(\alpha)| + |N_T(\alpha) - I_X(\alpha)| + |N_S(\alpha)| + |N_S(\alpha) - I_Y(\alpha)|\}.
$$

From Corollary 3.4, we have $0 < \rho(\alpha) \leq \lambda(\alpha)$ for all $\alpha \in \mathscr{GL}$, and

$$
\frac{\rho(\alpha)}{\lambda(\alpha)} = 1 - \frac{4|I_X(\alpha) - I_Y(\alpha)|}{\lambda(\alpha)} = 1 - 2|x_{11}(\alpha) - X_{21}(\alpha)|.
$$

Thus $|x_{11}(\alpha) - x_{21}(\alpha)| < \frac{1}{2}$ $\frac{1}{2}$ for all $\alpha \in \mathscr{GL}$, and the image of ψ_1 is contained in the set $\mathscr{E} = \{(r_1, r_2, r_3, r_4, r_5, r_6) \in \Pi : |r_1 - r_4| < \frac{1}{2}\}$ $\frac{1}{2}$. Let

$$
\mathcal{E}^+ = \{ (r_1, r_2, r_3, r_4, r_5, r_6) \in \Pi : 0 \le r_1 - r_4 < \frac{1}{2} \} \n\mathcal{E}^- = \{ (r_1, r_2, r_3, r_4, r_5, r_6) \in \Pi : 0 \le r_4 - r_1 < \frac{1}{2} \}.
$$

Let ψ_2 : $\mathscr{E} \longrightarrow \mathbf{R}^6$ be defined by $\psi_2(r_1, r_2, r_3, r_4, r_5, r_6) = (t_1, t_2, t_3, t_4, t_5, t_6),$ where

$$
t_j = \begin{cases} \frac{r_j}{1 - 2(r_1 - r_4)} & \text{for } j = 1, 2, 3, 4 \text{ and } (r_1, r_2, r_3, r_4, r_5, r_6) \in \mathcal{E}^+, \\ \frac{r_j - r_1 + r_4}{1 - 2(r_1 - r_4)} & \text{for } j = 5, 6 \text{ and } (r_1, r_2, r_3, r_4, r_5, r_6) \in \mathcal{E}^+, \\ \frac{r_j}{1 - 2(r_4 - r_1)} & \text{for } j = 1, 4, 5, 6 \text{ and } (r_1, r_2, r_3, r_4, r_5, r_6) \in \mathcal{E}^-, \\ \frac{r_j + r_1 - r_4}{1 - 2(r_4 - r_1)} & \text{for } j = 2, 3 \text{ and } (r_1, r_2, r_3, r_4, r_5, r_6) \in \mathcal{E}^-. \end{cases}
$$

It is clear that ψ_2 is continuous on $\mathscr E$ with

$$
\psi_2(\mathscr{E}^+) \subset \Pi^+ = \{(t_1, t_2, t_3, t_4, t_5, t_6) \in \Pi : t_1 \ge t_4\} \text{ and}
$$

$$
\psi_2(\mathscr{E}^-) \subset \Pi^- = \{(t_1, t_2, t_3, t_4, t_5, t_6) \in \Pi : t_1 \le t_4\}.
$$

A direct computation proves that ψ_2 is an injective function onto Π with the inverse $\psi_2^{-1}(t_1, t_2, t_3, t_4, t_5, t_6) = (r_1, r_2, r_3, r_4, r_5, r_6) \in \mathscr{E}$, where

$$
r_j = \begin{cases} \frac{t_j}{1+2(t_1-t_4)} & \text{for } j = 1, 2, 3, 4, \text{ and } (t_1, t_2, t_3, t_4, t_5, t_6) \in \Pi^+, \\ \frac{t_j+t_1-t_4}{1+2(t_1-t_4)} & \text{for } j = 5, 6, \text{ and } (t_1, t_2, t_3, t_4, t_5, t_6) \in \Pi^+, \\ \frac{t_j}{1+2(t_4-t_1)} & \text{for } j = 1, 4, 5, 6, \text{ and } (t_1, t_2, t_3, t_4, t_5, t_6) \in \Pi^-, \\ \frac{t_j-t_1+t_4}{1+2(t_4-t_1)} & \text{for } j = 2, 3, \text{ and } (t_1, t_2, t_3, t_4, t_5, t_6) \in \Pi^-. \end{cases}
$$

and

This proves that ψ_2 is a homeomorphism of $\mathscr E$ onto Π .

Let Ψ be the composition of ψ_1 followed by ψ_2 . We shall prove that Ψ maps \mathscr{GL} into $\Delta = (\mathscr{C} \times \mathscr{C}) \cap \Pi$. For $\alpha \in \mathscr{GL}$, write

$$
\begin{aligned} \big(\xi_{11}(\alpha),\xi_{12}(\alpha),\xi_{13}(\alpha),\xi_{21}(\alpha),\xi_{22}(\alpha),\xi_{23}(\alpha)\big) \\ &= \psi_2\big(x_{11}(\alpha),x_{12}(\alpha),x_{13}(\alpha),x_{21}(\alpha),x_{22}(\alpha),x_{23}(\alpha)\big). \end{aligned}
$$

From the definition of $\rho(\alpha)$, we have

$$
\xi_{11}(\alpha) = \frac{2I_X(\alpha)}{\rho(\alpha)}, \qquad \xi_{12}(\alpha) = \frac{2|N_T(\alpha)|}{\rho(\alpha)}, \qquad \xi_{13}(\alpha) = \frac{2|N_T(\alpha) - I_X(\alpha)|}{\rho(\alpha)}, \n\xi_{21}(\alpha) = \frac{2I_Y(\alpha)}{\rho(\alpha)}, \qquad \xi_{22}(\alpha) = \frac{2|N_S(\alpha)|}{\rho(\alpha)}, \qquad \xi_{23}(\alpha) = \frac{2|N_S(\alpha) - I_Y(\alpha)|}{\rho(\alpha)}.
$$

For simplicity, write $N_T = N_T(\alpha)$, $N_S = N_S(\alpha)$, $I_X = I_X(\alpha)$, $I_Y = I_Y(\alpha)$, and $\xi_{ij} = \xi_{ij}(\alpha)$ for all $\alpha \in \mathscr{GL}$. Then

$$
N_T \le 0 \implies \xi_{11} + \xi_{12} = \xi_{13}, \qquad N_S \le 0 \implies \xi_{21} + \xi_{22} = \xi_{23},
$$

\n
$$
0 \le N_T \le I_X \implies \xi_{11} - \xi_{12} = \xi_{13}, \qquad 0 \le N_S \le I_Y \implies \xi_{21} - \xi_{22} = \xi_{23},
$$

\n
$$
N_T \ge I_X \implies -\xi_{11} + \xi_{12} = \xi_{13}, \qquad N_S \ge I_Y \implies -\xi_{21} + \xi_{22} = \xi_{23}.
$$

Therefore, $\Psi(\mathscr{GL}) \subset \Delta$.

4.2. A homeomorphism of Δ onto a 3-sphere. In this subsection, we shall prove that $\Delta = (\mathscr{C} \times \mathscr{C}) \cap \Pi$ is homeomorphic to a 3-sphere.

Let A be the invertible linear transformation of \mathbb{R}^3 onto itself carrying the vectors $(1,0,1)$, $(1,1,0)$ and $(0,1,1)$ to the vectors $(1,0,1)$, $\left(-\frac{1}{2}\right)$ $\frac{1}{2}, \frac{1}{2}$ 2 $\sqrt{3}, 1$ and $\left(-\frac{1}{2}\right)$ $\frac{1}{2}, -\frac{1}{2}$ 2 $\sqrt{3}$, 1) in this order. The matrix representation of A is

$$
A = \begin{pmatrix} \frac{1}{2} & -1 & \frac{1}{2} \\ \frac{1}{2}\sqrt{3} & 0 & -\frac{1}{2}\sqrt{3} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} \text{ with the inverse } A^{-1} = \begin{pmatrix} \frac{1}{3} & \sqrt{3}^{-1} & \frac{2}{3} \\ \frac{-2}{3} & 0 & \frac{3}{3} \\ \frac{1}{3} & -\sqrt{3}^{-1} & \frac{2}{3} \end{pmatrix}.
$$

Let $\mathscr{C}' = A(\mathscr{C})$. Note that if $(x_1, x_2, x_3) = A(r_1, r_2, r_3) \in \mathscr{C}'$, then $x_3 \geq 0$. Let

$$
L_1 = \{ (t, 0, t) \in \mathbf{R}^3 : t \ge 0 \},
$$

\n
$$
L_2 = \{ (-\frac{1}{2}t, \frac{1}{2}\sqrt{3}t, t) \in \mathbf{R}^3 : t \ge 0 \} \text{ and}
$$

\n
$$
L_3 = \{ (-\frac{1}{2}t, -\frac{1}{2}\sqrt{3}t, t) \in \mathbf{R}^3 : t \ge 0 \}.
$$

By a direct computation, one proves easily that $\Pi_1' = A(\Pi_1)$ lies on the plane $x_1 + \sqrt{3} x_2 = x_3$ bounded by L_1 and L_2 , $\Pi'_2 = A(\Pi_2)$ lies on the plane $2x_1 + x_3 = 0$

bounded by L_2 and L_3 , and $\Pi_3' = A(\Pi_3)$ lies on the plane $\sqrt{3}x_2 + x_3 = x_1$ bounded by L_1 and L_3 . By the definition, $\mathscr{C}' = \Pi'_1 \cup \Pi'_2 \cup \Pi'_3$. Let J be the linear transformation of \mathbb{R}^6 onto itself represented by the following matrix

$$
\begin{pmatrix} A & 0 \\ 0 & A \end{pmatrix}.
$$

Then J is a homeomorphism of \mathbb{R}^6 onto itself with

$$
\Pi' = J(\Pi) = \{ (x_1, x_2, x_3, x_4, x_5, x_6) \in \mathbf{R}^6 : x_3 + x_6 = \frac{1}{2} \},
$$

and $J(\Delta) = (\mathscr{C}' \times \mathscr{C}') \cap \Pi' = \Delta'.$

It is clear that the orthogonal projection $\eta: \mathbb{R}^3 \longrightarrow \mathbb{R}^2$ defined by

$$
\eta(x_1, x_2, x_3) = (x_1, x_2)
$$

restricted to \mathscr{C}' is a homeomorphism onto \mathbf{R}^2 . Then the projection $\phi: \mathbf{R}^6 \longrightarrow \mathbf{R}^4$ defined by

$$
\phi(x_1,x_2,x_3,x_4,x_5,x_6)=\bigl(\eta(x_1,x_2,x_3),\eta(x_4,x_5,x_6)\bigr)
$$

restricted to $\mathscr{C}' \times \mathscr{C}'$ is a homeomorphism onto $\mathbb{R}^2 \times \mathbb{R}^2 \cong \mathbb{R}^4$. Let

$$
\mathbf{B} = (\mathscr{C}' \times \mathscr{C}') \cap \{(x_1, x_2, x_3, x_4, x_5, x_6) \in \mathbf{R}^6 : x_3 + x_6 \le \frac{1}{2}\}.
$$

Now, we shall prove that $\phi(\mathbf{B})$ is bounded and convex, and has non-empty interior. This implies that $\phi(\mathbf{B})$ is homeomorphic to the closed unit ball

$$
\{(x_1, x_2, x_3, x_4) \in \mathbf{R}^4 : x_1^2 + x_2^2 + x_3^2 + x_4^2 \le 1\}.
$$

By the definition of **B**, as a subspace of $\mathscr{C}' \times \mathscr{C}'$, the boundary of **B** is Δ' , then $\phi(\Delta')$ is homeomorphic to a 3-sphere, and so is Δ .

Let R be the rotation in \mathbb{R}^3 with the matrix representation

$$
\begin{pmatrix}\n\cos\frac{2}{3}\pi & -\sin\frac{2}{3}\pi & 0 \\
\sin\frac{2}{3}\pi & \cos\frac{2}{3}\pi & 0 \\
0 & 0 & 1\n\end{pmatrix} = \begin{pmatrix}\n-\frac{1}{2} & -\frac{1}{2}\sqrt{3} & 0 \\
\frac{1}{2}\sqrt{3} & -\frac{1}{2} & 0 \\
0 & 0 & 1\n\end{pmatrix}.
$$

Then

$$
\Pi'_j \times \Pi'_k = R^{j-1}(\Pi'_1) \times R^{k-1}(\Pi'_1) = (R^{j-1} \times R^{k-1})(\Pi'_1 \times \Pi'_1)
$$

for $j, k \in \{1, 2, 3\}$, where $R^{j-1} \times R^{k-1}$ is the linear transformation of \mathbb{R}^6 onto itself represented by the following matrix

$$
\begin{pmatrix} R^{j-1} & 0 \\ 0 & R^{k-1} \end{pmatrix}.
$$

It easy to see that

$$
(R^{j-1} \times R^{k-1})(0,0,r,0,0,s) = (0,0,r,0,0,s)
$$

for any two real numbers r and s. Since the normal vector $(0, 0, 1, 0, 0, 1)$ of Π' is invariant under $R^{j-1} \times R^{k-1}$, and since the point $(0,0,\frac{1}{4})$ $\frac{1}{4}$, 0, 0, $\frac{1}{4}$ $(\frac{1}{4})$ of Π' is fixed by $R^{j-1} \times R^{k-1}$, then Π' is invariant under $R^{j-1} \times R^{k-1}$, and thus

$$
\phi(\mathbf{B}) = \bigcup_{j=1}^{3} \bigcup_{k=1}^{3} \phi((R^{j-1} \times R^{k-1})(V)),
$$

where

$$
V = \{(x_1, x_2, x_3, x_4, x_5, x_6) \in \Pi'_1 \times \Pi'_1 : x_3 + x_6 \le \frac{1}{2}\}
$$

= $\{(x_1, x_2, x_3, x_4, x_5, x_6) \in \Pi'_1 \times \Pi'_1 : x_1 + \sqrt{3}x_2 + x_4 + \sqrt{3}x_5 \le \frac{1}{2}\}.$

Clearly, V is bounded. This proves that $\phi(\mathbf{B})$ is bounded since $R^{j-1} \times R^{k-1}$ is a Euclidean isometry.

To prove the convexity of $\phi(\mathbf{B})$, we consider any two distinct points Q and Q' of **B** with coordinates $(x_1, x_2, x_3, x_4, x_5, x_6)$ and $(x'_1, x'_2, x'_3, x'_4, x'_5, x'_6)$ respectively. Let

$$
P_1 = (x_1, x_2, x_3),
$$
 $P_2 = (x_4, x_5, x_6),$ $P'_1 = (x'_1, x'_2, x'_3)$ and $P'_2 = (x'_4, x'_5, x'_6),$

and let $P_j P'_j$ denote the line segment connecting P_j to P'_j for $j = 1, 2$. The vertical plane in \mathbb{R}^3 containing $\overline{P_j P'_j}$ intersects \mathscr{C}' in a polygonal curve σ_j with parametric equation $f_j(t)$, $0 \le t \le 1$, so that $f_j(0) = P_j$ and $f_j(1) = P'_j$. Note that $\eta(\sigma_j) = \eta(P_j P'_j)$. The curve

$$
L = \{ (f_1(t), f_2(t)) \in \mathbf{R}^3 \times \mathbf{R}^3 : 0 \le t \le 1 \}
$$

lies on $\mathscr{C}' \times \mathscr{C}'$ connecting Q to Q' , and $\phi(L)$ is a line segment in $\phi(\mathbf{B})$ with $\phi(Q)$ and $\phi(Q')$ as its endpoints. Therefore, $\phi(\mathbf{B})$ is convex.

Note that $(\Pi'_1 \times \Pi'_1) \cap \Pi'$ is contained in the hyperplane in \mathbb{R}^6 of equation

$$
x_1 + \sqrt{3}x_2 + x_4 + \sqrt{3}x_5 = \frac{1}{2},
$$

then the distance from the origin to $(\Pi'_1 \times \Pi'_1) \cap \Pi'$ is at least $1/4\sqrt{2}$. This implies that $\phi(\mathbf{B})$ contains the closed ball centered at the origin with radius $1/4\sqrt{2}$, and $\phi(\mathbf{B})$ has non-empty interior. The proof is complete.

4.3. The extension of Ψ to $\pi \mathcal{I}(\mathcal{G})$. Now, we are going to extend the map Ψ to $\pi \mathcal{I}(\mathcal{G}) = \pi \mathcal{I}(\mathcal{G}\mathcal{L})$.

For every $\alpha \in \mathscr{GL}$, we define $x_{ij}(\mathbf{I}_{\alpha}) = x_{ij}(\alpha)$. Since each x_{ij} is homogeneous, then x_{ij} extends naturally to $\pi^{-1}\pi\mathscr{I}(\mathscr{G}\mathscr{L})$ defined by $x_{ij}(t\mathrm{I}_{\alpha})=x_{ij}(\mathrm{I}_{\alpha})$ for all $t > 0$ and for all $\alpha \in \mathscr{GL}$. Thus each x_{ij} induces a well-defined map, also denoted by x_{ij} , on $\pi \mathcal{I}(\mathscr{GL})$ defined by $x_{ij}(\pi(\mathbf{I}_{\alpha})) = x_{ij}(\mathbf{I}_{\alpha})$.

For an arbitrary $\mathscr{L} \in \pi^{-1} \overline{\pi \mathscr{I}(\mathscr{G})}$, there is a sequence $\{t_n\}_{n=1}^{\infty}$ of positive numbers, and there is a sequence $\{\gamma_n\}_{n=1}^{\infty}$ in $\mathscr G$ such that $\{t_n I_{\gamma_n}\}_{n=1}^{\infty}$ converges to \mathscr{L} . Thus

$$
t_n i(\gamma_n, \gamma_{ij}) = t_n \operatorname{I}_{\gamma_n}(\gamma_{ij}) \to \mathscr{L}(\gamma_{ij})
$$

as $n \to \infty$ for $i = 1, 2$ and for $j = 1, 2, 3$. This implies

$$
\lim_{n \to \infty} x_{ij}(t_n \mathbf{I}_{\gamma_n}) = \frac{\mathscr{L}(\gamma_{ij})}{\sum_{k=1}^2 \sum_{l=1}^3 \mathscr{L}(\gamma_{kl})}
$$

for $i = 1, 2$ and for $j = 1, 2, 3$. Let $\lambda: \pi^{-1} \overline{\pi \mathscr{I}(\mathscr{G})} \longrightarrow \mathbf{R}_{+}$ be defined by

$$
\lambda(\mathscr{L}) = \sum_{k=1}^{2} \sum_{l=1}^{3} \mathscr{L}(\gamma_{kl}) \text{ for all } \mathscr{L} \in \pi^{-1} \overline{\pi \mathscr{I}(\mathscr{G})},
$$

and let x_{ij} : $\pi^{-1} \overline{\pi \mathscr{I}(\mathscr{G})} \longrightarrow \mathbf{R}_{+}$ be defined by

$$
x_{ij}(\mathscr{L}) = \frac{\mathscr{L}(\gamma_{ij})}{\sum_{k=1}^2 \sum_{l=1}^3 \mathscr{L}(\gamma_{kl})}
$$
 for all $\mathscr{L} \in \pi^{-1} \overline{\pi \mathscr{I}(\mathscr{G})}$.

It is easy to see that each x_{ij} is continuous on $\pi^{-1}\overline{\pi\mathscr{I}(\mathscr{G})}$ with $x_{ij}(t\mathscr{L})=x_{ij}(\mathscr{L})$ for all $t > 0$ and for all $\mathscr{L} \in \pi^{-1} \overline{\pi \mathscr{I}(\mathscr{G})}$.

Since the restriction of π to π^{-1} $\overline{\pi\mathscr{I}\mathscr{G}}$ is a quotient map onto $\overline{\pi\mathscr{I}(\mathscr{G})}$, then each x_{ij} extends to $\overline{\pi\mathscr{I}(\mathscr{G})}$ a continuos map given by $x_{ij}(\pi(\mathscr{L})) = x_{ij}(\mathscr{L})$ for \mathscr{L} in $\pi^{-1}\overline{\pi\mathscr{I}(\mathscr{G})}$. This gives a continuous map of $\overline{\pi\mathscr{I}(\mathscr{G})}$ into \mathbb{R}^6_+ whose restriction to \mathscr{GL} is ψ_1 . We also use ψ_1 for this continuous map on $\overline{\pi\mathscr{I}(\mathscr{G})}$, and let $\Psi = \psi_2 \psi_1$ as before.

Proposition 4.1. The function Ψ maps $\overline{\pi\mathcal{I}(\mathcal{G})}$ continuously onto Δ .

Clearly, Ψ is a continuous map of $\overline{\pi\mathscr{I}(\mathscr{G})}$ into Π . Since $\Psi(\mathscr{G}) \subset \Delta$, and since Δ is closed in \mathbf{R}^6 , then $\Psi(\overline{\pi\mathscr{I}(\mathscr{G})}) \subset \Delta$.

To complete the proof of Proposition 4.1, we have to show that $\Psi(\pi \mathcal{I}(\mathcal{GL}))$ is dense in Δ since Ψ is continuous and $\overline{\pi\mathscr{I}(\mathscr{G})} = \overline{\pi\mathscr{I}(\mathscr{G}\mathscr{L})}$ is compact.

A point $(r_1, r_2, r_3, r_4, r_5, r_6)$ of \mathbf{Q}^6 will be called a *rational point*, where **Q** is the set of all rational numbers.

Lemma 4.2. Every rational point of $\Pi \cap (\Pi_2 \times \Pi_2)$ lies in $\Psi(\pi \mathcal{I}(\mathcal{G}\mathcal{L}))$.

Proof. Let $(v_1/u, v_2/u, v_3/u, v_4/u, v_5/u, v_6/u)$ be any rational point of $(\Pi_2 \times$ Π_2) \cap Π , where $u > 0$ and all $v_j \geq 0$ are even integers. Note that

 $2(v_2 + v_5) = u$, $v_1 + v_3 = v_2$ and $v_4 + v_6 = v_5$.

We want to show that there are non-negative integers a, b, c and d with $a + b +$ $c + d > 0$ such that

$$
\left(\frac{v_1}{u},\frac{v_2}{u},\frac{v_3}{u},\frac{v_4}{u},\frac{v_5}{u},\frac{v_6}{u}\right)=\left\{\begin{matrix}\Psi\big(\mathcal{T}_1^{-1}\mathcal{T}_2(a\gamma_T+b\gamma_S+c\tau_1+d\tau_2)\big) & \text{if } v_1 \geq v_4, \\ \Psi\big(\mathcal{T}_1^{-1}\mathcal{T}_2(a\gamma_T+b\gamma_S+c\tau_1+d\tau_3)\big) & \text{if } v_1 \leq v_4,\end{matrix}\right.
$$

where τ_1 , τ_2 and τ_3 are the geodesics given in the proof of Theorem 3.1.

Let $\alpha = \mathcal{T}_1^{-1} \mathcal{T}_2(a\gamma_T + b\gamma_S + c\tau_1 + d\tau_2)$. From Proposition 3.3 and Corollary 3.4, we have

$$
I_X(\alpha) = c + d,
$$

\n
$$
N_T(\alpha) = a + c + d,
$$

\n
$$
I_Y(\alpha) = c,
$$

\n
$$
N_S(\alpha) = b + c,
$$
 and
\n
$$
\rho(\alpha) = 2(2a + 2b + 4c + 2d).
$$

If $v_1 \geq v_4$, by solving the following equations for a, b, c and d

$$
2(c+d) = 2I_X(\alpha) = v_1,
$$

\n
$$
2(a+c+d) = 2N_T(\alpha) = v_2,
$$

\n
$$
2c = 2I_Y(\alpha) = v_4,
$$

\n
$$
2(b+c) = 2N_S(\alpha) = v_5,
$$

we have

$$
a = \frac{1}{2}(v_2 - v_1),
$$
 $b = \frac{1}{2}(v_5 - v_4),$ $c = \frac{1}{2}v_4$ and $d = \frac{1}{2}(v_1 - v_4).$

A direct computation gives $\rho(\alpha) = 2(v_2 + v_5) = u$,

 $2|N_T(\alpha) - I_X(\alpha)| = v_2 - v_1 = v_3$ and $2|N_S(\alpha) - I_Y(\alpha)| = v_5 - v_4 = v_6$.

This proves

$$
\Psi(\alpha) = \left(\frac{v_1}{u}, \frac{v_2}{u}, \frac{v_3}{u}, \frac{v_4}{u}, \frac{v_5}{u}, \frac{v_6}{u}\right).
$$

Next, assume that $v_1 \leq v_4$. Let α be given as above such that

$$
\Psi(\alpha) = \left(\frac{v_4}{u}, \frac{v_5}{u}, \frac{v_6}{u}, \frac{v_1}{u}, \frac{v_2}{u}, \frac{v_3}{u}\right).
$$

Since $\mathcal{I}_2 \Theta_2 = \Theta_2 \mathcal{I}_1$, $\Theta_1 \mathcal{I}_1^{-1} = \mathcal{I}_1 \Theta_1$ and $\Theta_1 \mathcal{I}_2^{-1} = \mathcal{I}_2 \Theta_1$, then $\mathcal{I}_1^{-1} \mathcal{I}_2(a\gamma_T + b\gamma_S + c\tau_1 + d\tau_3) = \mathcal{I}_1^{-1} \mathcal{I}_2 \Theta_1 \Theta_2(a\gamma_T + b\gamma_S + c\tau_1 + d\tau_2)$

$$
= \Theta_1 \Theta_2 \mathcal{I}_2 \mathcal{I}_1^{-1} (a\gamma_T + b\gamma_S + c\tau_1 + d\tau_2)
$$

=
$$
\Theta_1 \Theta_2 \mathcal{I}_1^{-1} \mathcal{I}_2 (a\gamma_T + b\gamma_S + c\tau_1 + d\tau_3)
$$

=
$$
\Theta_1 \Theta_2(\alpha).
$$

Let $\beta = \Theta_1 \Theta_2(\alpha)$. It follows immediately from Proposition 2.1 that

$$
I_X(\beta) = I_Y(\alpha), \quad I_Y(\beta) = I_X \alpha), \quad N_T(\beta) = N_S(\alpha) \quad \text{and} \quad N_S(\beta) = N_T(\alpha)
$$

and

$$
\Psi(\beta) = (\xi_{21}(\alpha), \xi_{22}(\alpha), \xi_{23}(\alpha), \xi_{11}(\alpha), \xi_{12}(\alpha), \xi_{13}(\alpha)) = \left(\frac{v_1}{u}, \frac{v_2}{u}, \frac{v_3}{u}, \frac{v_4}{u}, \frac{v_5}{u}, \frac{v_6}{u}\right).
$$

Proof of Proposition 4.1. We shall prove that $\Psi(\pi \mathcal{I}(\mathcal{GL}))$ is dense in Δ by showing that every rational point of Δ is in $\Psi(\pi \mathcal{I}(\mathscr{G}\mathcal{L}))$, and this completes the proof.

Let $\zeta = (v_1/u, v_2/u, v_3/u, v_4/u, v_5/u, v_6/u)$ be an arbitrary rational point of Δ , where $u > 0$ and all $v_j \geq 0$ are even integers. There are non-negative integers m and n such that

$$
mv_1 \le v_2 < (m+1)v_1
$$
 and $nv_4 \le v_5 < (n+1)v_4$.

Let

$$
\zeta_1 = \left(\frac{v_1}{u}, \frac{v_2}{u}, \frac{v_3}{u}\right) \quad \text{and} \quad \zeta_2 = \left(\frac{v_4}{u}, \frac{v_5}{u}, \frac{v_6}{u}\right).
$$

Set $v_j' = v_j$ for $j = 1, 4$, set

$$
v'_2 = \begin{cases} v_2 + (m+1)v_1 & \text{if } \zeta_1 \in \Pi_1 \cup \Pi_2, \\ -v_2 + (m+1)v_1 & \text{if } \zeta_1 \in \Pi_3, \end{cases}
$$

$$
v'_3 = \begin{cases} v_2 + mv_1 & \text{if } \zeta_1 \in \Pi_1 \cup \Pi_2, \\ -v_2 + mv_1 & \text{if } \zeta_1 \in \Pi_3, \end{cases}
$$

$$
v'_5 = \begin{cases} v_5 + (n+1)v_4 & \text{if } \zeta_2 \in \Pi_1 \cup \Pi_2, \\ -v_5 + (n+1)v_4 & \text{if } \zeta_2 \in \Pi_3, \end{cases}
$$

$$
v'_6 = \begin{cases} v_5 + nv_4 & \text{if } \zeta_2 \in \Pi_1 \cup \Pi_2, \\ -v_5 + nv_4 & \text{if } \zeta_2 \in \Pi_3, \end{cases}
$$

and set $w = \sum_{j=1}^{6} v'_j$. Then $w > 0$ and all $v'_j \ge 0$ are even integers,

$$
|v_2' - (m+1)v_1| = v_2, \quad |v_5' - (n+1)v_4| = v_5,
$$

and

$$
|v'_2 - (m+2)v_1| = \begin{cases} |v_2 - v_1| = v_3 & \text{if } \zeta_1 \in \Pi_1 \cup \Pi_2, \\ | -v_2 - v_1| = v_3 & \text{if } \zeta_1 \in \Pi_3, \end{cases}
$$

$$
|v'_5 - (n+2)v_4| = \begin{cases} |v_5 - v_4| = v_6 & \text{if } \zeta_2 \in \Pi_1 \cup \Pi_2, \\ | -v_5 - v_4| = v_6 & \text{if } \zeta_2 \in \Pi_3. \end{cases}
$$

As $v_2' = v_1' + v_3'$ and $v_5' = v_4' + v_6'$, the point $(v_1'/w, v_2'/w, v_3'/w, v_4'/w, v_5'/w, v_6'/w)$ is a rational point in $\Pi \cap (\Pi_2 \times \Pi_2)$.

From the proof Lemma 4.2 we know that there is an $\alpha \in \mathscr{GL}$ with $N_T(\alpha) \geq$ $I_X(\alpha)$ and $N_S(\alpha) \geq I_Y(\alpha)$ such that

$$
2I_X(\alpha) = v'_1,
$$

\n
$$
2N_T(\alpha) = v'_2,
$$

\n
$$
2\{N_T(\alpha) - I_X(\alpha)\} = v'_3,
$$

\n
$$
2I_Y(\alpha) = v'_4,
$$

\n
$$
2N_S(\alpha) = v'_5,
$$

\n
$$
2\{N_S(\alpha) - I_Y(\alpha)\} = v'_6.
$$

Let $\alpha' = \mathcal{I}_2^{m+1} \mathcal{I}_1^{-n-1}(\alpha)$. From Lemma 3.5,

$$
2I_X(\alpha') = 2I_X(\alpha) = v_1,
$$

\n
$$
2I_Y(\alpha') = 2I_Y(\alpha) = v_4,
$$

\n
$$
2|N_T(\alpha')| = |2\{N_T(\alpha) - (m+1)I_X(\alpha)\}| = |v'_2 - (m+1)v_1| = v_2,
$$

\n
$$
2|N_T(\alpha') - I_X(\alpha')| = |2\{N_T(\alpha) - (m+2)I_X(\alpha)\}| = |v'_2 - (m+2)v_1| = v_3,
$$

\n
$$
2|N_S(\alpha')| = |2\{N_S(\alpha) - (n+1)I_Y(\alpha)\}| = |v'_5 - (n+1)v_4| = v_5,
$$

\n
$$
2|N_S(\alpha') - I_Y(\alpha')| = |2\{N_S(\alpha) - (n+2)I_Y(\alpha)\}| = |v'_5 - (n+2)v_4| = v_6.
$$

Thus $\Psi(\alpha') = \zeta$.

4.4. The injectivity of Ψ. So far, we have proved that Ψ maps $\overline{\pi \mathscr{I}(\mathscr{G})}$ onto the 3-sphere Δ . Next, we shall prove that Ψ is injective on $\overline{\pi\mathscr{I}(\mathscr{G})}$. This proves the following theorem.

Theorem 4.3. The map Ψ is a homeomorphism of $\overline{\pi\mathscr{I}(\mathscr{G})}$ onto Δ , and then $\overline{\pi\mathscr{I}(\mathscr{G})}$ is homeomorphic to a 3-sphere.

Since ψ_2 is a homeomorphism of $\mathscr E$ onto Π , it remains to show that ψ_1 is injective on $\overline{\pi\mathscr{I}(\mathscr{G})}$.

Let $\mathscr{L}_1, \mathscr{L}_2 \in \pi^{-1} \overline{\pi \mathscr{I}(\mathscr{G})}$ with $\psi_1(\pi(\mathscr{L}_1)) = \psi_1(\pi(\mathscr{L}_2))$. There exist sequences $\{t_n\}$ and $\{s_n\}$ of positive numbers, and there exist sequences $\{\alpha_n\}$ and $\{\beta_n\}$ of elements in $\mathscr G$ such that

$$
\lim_{n \to \infty} t_n \mathbb{I}_{\alpha_n} = \mathscr{L}_1 \quad \text{and} \quad \lim_{n \to \infty} s_n \mathbb{I}_{\beta_n} = \mathscr{L}_2.
$$

Set $p = \lambda(\mathcal{L}_1)/\lambda(\mathcal{L}_2)$. By assumption, for $i = 1, 2$ and for $j = 1, 2, 3$, we have $\mathscr{L}_1(\gamma_{ij}) = p\mathscr{L}_2(\gamma_{ij}), \quad \text{or, equivalently,} \quad \lim_{n \to \infty} t_n \mathbb{I}_{\alpha_n}(\gamma_{ij}) = \lim_{n \to \infty} ps_n \mathbb{I}_{\beta_n}(\gamma_{ij}).$

We shall complete the proof by showing that

$$
\lim_{n \to \infty} t_n \mathbb{I}_{\alpha_n}(\gamma) = \lim_{n \to \infty} ps_n \mathbb{I}_{\beta_n}(\gamma) \text{ for all } \gamma \in \mathscr{G}.
$$

Since

$$
\lim_{n \to \infty} t_n I_X(\alpha_n) = \lim_{n \to \infty} t_n I_{\alpha_n}(\gamma_{11}) = \lim_{n \to \infty} ps_n I_{\beta_n}(\gamma_{11}) = \lim_{n \to \infty} ps_n I_X(\beta_n), \text{ and}
$$

$$
\lim_{n \to \infty} t_n I_Y(\alpha_n) = \lim_{n \to \infty} t_n I_{\alpha_n}(\gamma_{21}) = \lim_{n \to \infty} ps_n I_{\beta_n}(\gamma_{21}) = \lim_{n \to \infty} ps_n I_Y(\beta_n),
$$

then, by using the geometric intersection formula, we only have to show that $\lim_{n \to \infty} t_n |I_X(\alpha_n) N_T(\gamma) - I_X(\gamma) N_T(\alpha_n)| = \lim_{n \to \infty} ps_n |I_X(\beta_n) N_T(\gamma) - I_X(\gamma) N_T(\beta_n)|$ and

$$
\lim_{n \to \infty} t_n |I_Y(\alpha_n)N_S(\gamma) - I_Y(\gamma)N_S(\alpha_n)| = \lim_{n \to \infty} ps_n |I_Y(\beta_n)N_S(\gamma) - I_Y(\gamma)N_S(\beta_n)|.
$$

To simplify notation, set $A_n = t_n I_X(\alpha_n)$, $B_n = ps_n I_X(\beta_n)$, $C_n = t_n N_T(\alpha_n)$, $D_n = ps_n N_T(\beta_n), I = I_X(\gamma)$ and $N = N_T(\gamma)$. Thus

$$
\lim_{n \to \infty} A_n = \lim_{n \to \infty} B_n \text{ and } \lim_{n \to \infty} |C_n| = \lim_{n \to \infty} |D_n|.
$$

It is clear that

$$
\lim_{n \to \infty} C_n = \lim_{n \to \infty} D_n \quad \text{if} \quad \lim_{n \to \infty} |C_n| = \lim_{n \to \infty} |D_n| = 0.
$$

If

$$
\lim_{n \to \infty} |C_n| = \lim_{n \to \infty} |D_n| \neq 0,
$$

by the continuity of Ψ we may choose α_n and β_n so that $C_nD_n > 0$, and then we also have

$$
\lim_{n \to \infty} C_n = \lim_{n \to \infty} D_n.
$$

The inequality

$$
||A_nN - C_nI| - |B_nN - D_nI|| \le |A_n - B_n| \cdot |N| + |C_n - D_n| \cdot I
$$

proves that

$$
\lim_{n \to \infty} \{ |A_n N - C_n I| - |B_n N - D_n I| \} = 0,
$$

or equivalently,

$$
\lim_{n \to \infty} t_n |I_X(\alpha_n) N_T(\gamma) - I_X(\gamma) N_T(\alpha_n)| = \lim_{n \to \infty} ps_n |I_X(\beta_n) N_T(\gamma) - I_X(\gamma) N_T(\beta_n)|.
$$

By the same reasoning, one shows that

 $\lim_{n\to\infty} t_n|I_Y(\alpha_n)N_S(\gamma) - I_Y(\gamma)N_S(\alpha_n)| = \lim_{n\to\infty} ps_n|I_Y(\beta_n)N_S(\gamma) - I_Y(\gamma)N_S(\beta_n)|.$ The proof is complete.

4.5. An embedding of h $\overline{\pi\mathscr{I}(\mathscr{G})}$ into \mathbb{R}^4 . Let $\mathscr{C} = \Pi_1 \cup \Pi_2 \cup \Pi_3$ be the set given at the beginning of this section, and let $\varphi: \mathscr{C} \longrightarrow \mathbb{R}^2$ be defined by

$$
\varphi(r_1, r_2, r_3) = \begin{cases} (r_1, r_2) & \text{if } (r_1, r_2, r_3) \in \Pi_1 \cup \Pi_2, \\ (r_1, -r_2) & \text{if } (r_1, r_2, r_3) \in \Pi_3. \end{cases}
$$

It is easy to see that $(r_1, r_2, r_3) \in (\Pi_1 \cup \Pi_2) \cap \Pi_3$ if and only if $r_2 = 0$. This implies that φ is continuous on $\mathscr C$. Moreover, φ is injective as proved below.

Let (r_1, r_2, r_3) and (t_1, t_2, t_3) be two points of \mathscr{C} , $\varphi(r_1, r_2, r_3) = \varphi(t_1, t_2, t_3)$. By the definition, we have $r_1 = t_1$. Also, we see easily that $r_2 = 0$ if and only if $t_2 = 0$. If $r_2 = 0$, then $(r_1, r_2, r_3), (t_1, t_2, t_3) \in \Pi_3$, and thus $(r_1, r_2, r_3) =$ (t_1,t_2,t_3) . Assume that $r_2t_2 \neq 0$, i.e. $r_2 > 0$ and $t_2 > 0$. Then either

$$
(r_1, r_2) = \varphi(r_1, r_2, r_3) = \varphi(t_1, t_2, t_3) = (t_1, t_2),
$$
 or
\n $(r_1, -r_2) = \varphi(r_1, r_2, r_3) = \varphi(t_1, t_2, t_3) = (t_1, -t_2),$

and thus $(r_1, r_2, r_3) = (t_1, t_2, t_3)$. Therefore, φ is injective.

By the definition of Π_1 , Π_2 and Π_3 , we obtain the inverse of φ immediately given by $\varphi^{-1}(t_1, t_2) = (t_1, |t_2|, |t_1 - t_2|)$ for all $(t_1, t_2) \in \varphi(\mathscr{C})$.

Since $r_1 + r_2 + r_4 + r_5 > 0$ whenever $(r_1, r_2, r_3, r_4, r_5, r_6) \in \Delta$, then the function $\psi_3: \Delta \longrightarrow \mathbf{R}^4$ defined by

$$
\psi_3(r_1, r_2, r_3, r_4, r_5, r_6) = \left(\frac{\varphi(r_1, r_2, r_3)}{r_1 + r_2 + r_4 + r_5}, \frac{\varphi(r_4, r_5, r_6)}{r_1 + r_2 + r_4 + r_5}\right)
$$

is continuous on Δ . We shall prove that ψ_3 is injective.

Let $(r_1, r_2, r_3, r_4, r_5, r_6)$ and $(t_1, t_2, t_3, t_4, t_5, t_6)$ be any two points of Δ with $\psi_3(r_1, r_2, r_3, r_4, r_5, r_6) = \psi_3(t_1, t_2, t_3, t_4, t_5, t_6).$

Write

$$
\varphi(r_1, r_2, r_3) = (r'_1, r'_2),
$$

\n
$$
\varphi(r_4, r_5, r_6) = (r'_4, r'_5),
$$

\n
$$
\varphi(t_1, t_2, t_3) = (t'_1, t'_2) \text{ and}
$$

\n
$$
\varphi(t_4, t_5, t_6) = (t'_4, t'_5).
$$

Then $r_j = r'_j$ and $t_j = t'_j$ for $j = 1, 4$; $r_j = |r'_j|$ and $t_j = |t'_j|$ for $j = 2, 5$; $r_3 = |r'_1 - r'_2|, \quad r_6 = |r'_4 - r'_5|, \quad t_3 = |t'_1 - t'_2|, \quad t_6 = |t'_4 - t'_5|.$

Let

$$
p = \frac{r_1 + r_2 + r_4 + r_5}{t_1 + t_2 + t_4 + t_5} = \frac{r'_1 + |r'_2| + r'_4 + |r'_5|}{t'_1 + |t'_2| + t'_4 + |t'_5|}.
$$

By assumption, $r'_{j} = pt'_{j}$ for $j = 1, 2, 4, 5$. Since $\sum_{j=1}^{6} r_{j} = \sum_{j=1}^{6} t_{j} = 1$, then

$$
1 = r'_1 + |r'_2| + |r'_1 - r'_2| + r'_4 + |r'_5| + |r'_4 - r'_5|
$$

= $p\{t'_1 + |t'_2| + |t'_1 - t'_2| + t'_4 + |t'_5| + |t'_4 - t'_5|\} = p.$

Therefore, $(r_1, r_2, r_3, r_4, r_5, r_6) = (t_1, t_2, t_3, t_4, t_5, t_6)$.

From Theorem 4.3 together with the above discussion, we have shown the following theorem.

Theorem 4.4. The composition Φ of Ψ followed by ψ_3 is a homeomorphism of $\overline{\pi\mathscr{I}(\mathscr{G})}$ onto a 3-sphere lying in \mathbb{R}^4 . Moreover,

$$
\Phi(\alpha) = \left(\frac{I_X(\alpha)}{\sigma(\alpha)}, \frac{N_T(\alpha)}{\sigma(\alpha)}, \frac{I_Y(\alpha)}{\sigma(\alpha)}, \frac{N_S(\alpha)}{\sigma(\alpha)}\right) \text{ for all } \alpha \in \mathscr{GL},
$$

where $\sigma(\alpha) = I_X(\alpha) + |N_T(\alpha)| + I_Y(\alpha) + |N_S(\alpha)|$.

5. Words for geodesics in $\hat{\mathscr{G}}$ and their traces

In this section, we consider the Maskit embedding \mathcal{M}_5 of the Teichmüller space of Σ_5 , which is a family of regular B-groups $G(\mu, \nu)$ parametrized by complex numbers μ and ν . Each $G(\mu, \nu)$ representing a five-punctured sphere and three thrice-punctured spheres. The regular set $\Omega(\mu, \nu)$ of $G(\mu, \nu)$ has a unique simply connected component $\Omega_0(\mu, \nu)$ invariant under $G(\mu, \nu)$ such that $\Omega_0(\mu, \nu)/G(\mu, \nu)$ is a five-punctured sphere. Every geodesic $\gamma \in \hat{\mathscr{G}}$ corresponds to a cyclic semi-reduced Γ-word $W(\gamma;\mu,\nu)$ in $G(\mu,\nu)$. The trace tr $W(\gamma;\mu,\nu)$ is a polynomial in μ and ν . The main work of this section is to compute the high order terms of the trace polynomials tr $W(\gamma;\mu,\nu)$. This section is a part of the author's Ph.D. thesis [3].

5.1. Cyclic semi-reduced Γ-words for geodesics in $\hat{\mathscr{G}}$. In this subsection, we shall give a complete description of cyclic semi-reduced Γ-words representing geodesics in $\hat{\mathscr{G}}$. Furthermore, we shall write them in exactly two canonical forms. This reduces the difficulty of computing the high-order terms of the trace polynomials tr $W(\gamma;\mu,\nu)$.

From Proposition 2.7 and [4, Theorem 3.2], we have

Theorem 5.1. Let $\gamma \in \hat{\mathscr{G}}$. If $I_Y(\gamma) = 0$, then γ is represented by a cyclic semi-reduced Γ-word of the form

$$
\prod_{i=1}^m T^{r_i} X^{\omega_i} T^{t_i} S^{\delta_i},
$$

where $\delta_i, \omega_i \in \{1, -1\}$, $m = I_X(\gamma) = I_S(\gamma)$, and r_i and t_i are integers satisfying the following conditions:

- (i) $-1 \le (r_i + t_i)\omega_i \le 0$ and $-1 \le (r_{i+1} + t_i)\delta_i \le 0$, where $r_{m+1} = r_1$.
- (ii) $|r_i|, |t_i| \in \{r, r+1\}$, where $r = \min\{|r_i|, |t_i| : i = 1, ..., m\}$.
- (iii) $r_i \geq 0$, $t_i \leq 0$ whenever $\gamma \in \mathscr{G}_T^+$, and $r_i \leq 0$, $t_i \geq 0$ whenever $\gamma \in \mathscr{G}_T^-$.
- (iv) $\sum_{i=1}^{m} (r_i t_i) = N_T(\gamma)$.

By considering the function Θ_2 , we have

Corollary 5.2. Let $\gamma \in \hat{\mathscr{G}}$. If $I_X(\gamma) = 0$, then γ is represented by a cyclic semi-reduced Γ-word of the form

$$
\prod_{i=1}^n S^{p_i}Y^{\varepsilon_i}S^{q_i}T^{\delta_i},
$$

where $\delta_i, \varepsilon_i \in \{1, -1\}$, $n = I_Y(\gamma) = I_T(\gamma)$, and p_i and q_i are integers satisfying the following conditions:

- (i) $-1 \leq (p_i + q_i)\varepsilon_i \leq 0$ and $-1 \leq (p_{i+1} + q_i)\delta_i \leq 0$, where $p_{n+1} = p_1$.
- (ii) $|p_i|, |q_i| \in \{p, p + 1\}$, where $p = \min\{|p_i|, |q_i| : i = 1, \ldots, n\}$.
- (iii) $p_i \leq 0$, $q_i \geq 0$ whenever $\gamma \in \mathscr{G}_S^+$, and $p_i \geq 0$, $q_i \leq 0$ whenever $\gamma \in \mathscr{G}_S^-$. (iv) $\sum_{i=1}^{n} (q_i - p_i) = N_S(\gamma)$.

In the following, we assume that $\gamma \in \widehat{\mathscr{G}}$ with $I_X(\gamma)I_Y(\gamma) > 0$. From Proposition 2.1, we may assume that $\gamma \in \mathscr{G}_S^+$ with $I_X(\gamma) \geq I_Y(\gamma)$. Let $I_Y(\gamma) = n$. Then γ is represented by a cyclic semi-reduced Γ-word W of the form

$$
W = \prod_{i=1}^{n} S^{-p_i} Y^{\varepsilon_i} S^{q_i} W_i,
$$

where $\varepsilon_i = \pm 1$, where $p_i \geq 0$ and $q_i \geq 0$ are integers, and where each W_i is a semi-reduced Γ -word as given in equation (5). Since

$$
\mathcal{F}_1^2(W) = \prod_{i=1}^n S^{-p_i - 1} Y^{\varepsilon_i} S^{q_i + 1} W_i,
$$

by considering the geodesic $\mathcal{I}_1^2(\gamma)$ we may assume that $p_i > 0$ and $q_i > 0$ for all i .

Now, we shall determine the subwords W_i . Note that each W_i is always followed by S^{-1} since $p_{i+1} > 0$ for each i, where $p_{n+1} = p_1$. Consider the admissible subarc γ_i represented by the reduced word $\widetilde{W}_i = \vec{S} W_i S^{-1}$. Note that

$$
I_X(\gamma_i) = I_{X^{-1}}(\gamma_i) > 0
$$
, $I_Y(\gamma_i) = I_{Y^{-1}}(\gamma_i) = 0$ and $I_{S^{-1}}(\gamma_i) = 2 + I_S(\gamma_i)$,

for every i, and that

$$
I_X(\gamma) = \sum_{i=1}^n I_X(\gamma_i).
$$

To simplify notation, for every fixed i we write $a = m_i$ and write

$$
\widetilde{W}_i = \vec{S} E_1 \cdots E_a S^{-1}.
$$

Let l be the strand of γ_i joining the S^{-1} -side to the E_1 -side, and let l' be the strand of γ_i joining the E_a^{-1} -side to the S^{-1} -side. Let P_0 and P'_0 be the endpoints of l and l' on the S^{-1} -side respectively, and let Q_0 be the point on the S-side such that $Q_0 = S(P_0)$.

Claim. If P is the endpoint of a strand of γ_i on the S^{-1} -side, and if $P \neq P_0$ and $P \neq P'_0$, then $P \prec P_0$ and $P \prec P'_0$.

Proof of the claim. Note that such a point P exists only when $I_{S^{-1}}(\gamma_i) > 2$. Let $Q = S(P)$. Then Q is an endpoint of a strand L of γ_i connecting the S-side to the E-side for some $E \in \{X^{\pm 1}, T^{\pm 1}\}.$

If $P_0 \prec P$, then $Q_0 \prec Q$. By the definition of W_i and that of Q_0 , the point Q_0 is an endpoint of a strand L_0 of γ connecting the S-side and the E'-side with $E' \in \{S^{-1}, Y^{\pm 1}\}\.$ This implies that L_0 intersects L. This is impossible since γ is simple. Hence, $P \prec P_0$. Similarly, $P \prec P'_0$. The proof of the claim is complete.

Figure 8.

Let $P_k \prec \cdots \prec P_1$ be all the points where the lift of γ_i to $\mathscr D$ meets the S^{-1} . side, where $k = I_{S^{-1}}(\gamma_i) \ge 2$. From the above claim, we have $\{P_1, P_2\} = \{P_0, P'_0\}$.

Let l_1 be the strand of γ_i with P_1 an endpoint, and let A_1 be the other endpoint of l_1 . Note that A_1 lies on the E-side for some $E \in \{X^{\pm 1}, T^{\pm 1}\}$. Let $Q_2 = S(P_2)$. Since $I_Y(\gamma_i) = I_{Y^{-1}}(\gamma_i) = 0$, there is a simple arc $l \subset \mathscr{D}$ joining Q_2 to A_1 which is disjoint from all strands of γ_i except possibly l_1 (see Figure 8).

Let $\hat{\gamma}_i$ be the curve on Σ_5 obtained from γ_i by replacing l_1 by \hat{l} . Clearly, $\hat{\gamma}_i$ is a simple loop in \mathscr{G} with $I_Y(\hat{\gamma}_i) = 0$ and $I_X(\hat{\gamma}_i) = I_X(\gamma_i)$.

By Theorem 5.1, the free homotopy class $[\hat{\gamma}_i]$ is represented by a cyclic semireduced Γ-word \widehat{W}_i of the form

$$
\widehat{W}_i = \prod_{j=1}^{m'_i} T^{r_{ij}} X^{\omega_{ij}} T^{t_{ij}} S^{\delta_{ij}},
$$

where $m'_i = I_X([\hat{\gamma}_i]) = I_X(\gamma_i)$, and r_{ij} , t_{ij} , ω_{ij} and δ_{ij} are integers satisfying the conditions given in Theorem 5.1.

Let $\hat{\gamma}_i$ be oriented so that the initial point of the projection of \hat{l} to Σ_5 is the projection of A_1 , and the terminal point is the projection of Q_2 . We write W_i so that W_i represents the oriented closed curve $\hat{\gamma}_i$. Then $\delta_{im'_i} = 1$, and

$$
\widetilde{W}_i = \vec{S} \bigg(\prod_{j=1}^{m'_i} T^{r_{ij}} X^{\omega_{ij}} T^{t_{ij}} S^{\delta'_{ij}} \bigg) S^{-1},
$$

where $\delta'_{im'_i} = 0$ and $\delta'_{ij} \in \{1, -1\}$ for $1 \leq j < m'_i$, and thus

(7)
$$
W = \prod_{i=1}^n S^{-p_i} Y^{\varepsilon_i} S^{q_i} \bigg(\prod_{j=1}^{m'_i} T^{r_{ij}} X^{\omega_{ij}} T^{t_{ij}} S^{\delta'_{ij}} \bigg).
$$

Theorem 5.3. Let $\gamma \in \widehat{\mathscr{G}}$ with $m = I_X(\gamma) > 0$ and $n = I_Y(\gamma) > 0$.

(A) If $m \geq n$, then γ is represented by a cyclic semi-reduced Γ -word $W(\gamma)$ of the form

$$
W(\gamma) = \prod_{i=1}^n S^{p_i} Y^{\varepsilon_i} S^{q_i} \left(\prod_{j=1}^{m_i} T^{r_{ij}} X^{\omega_{ij}} T^{t_{ij}} S^{\delta_{ij}} \right),
$$

where $\varepsilon_i, \omega_{ij} \in \{1, -1\}$, $m_i > 0$, and p_i , q_i , r_{ij} , t_{ij} and δ_{ij} are integers satisfying the following conditions:

- (i) $\sum_{i=1}^{n} m_i = m$.
- (ii) For $1 \leq i \leq n$, $\delta_{im_i} = 0$, and if $m_i > 1$, then $|\delta_{ij}| = 1$ for $1 \leq j < m_i$. (iii) For $1 \leq i \leq n$,

$$
-1 \le (p_i + q_i)\varepsilon_i \le 0 \text{ and } |p_i|, |q_i| \in \{p, p + 1\},\
$$

where $p = \min\{|p_i|, |q_i| : 1 \le i \le n\}$. Moreover, $p_i \le 0$, $q_i \ge 0$ for all i when $\gamma \in \mathscr{G}_S^+$, and $p_i \geq 0$, $q_i \leq 0$ for all i when $\gamma \in \mathscr{G}_S^-$. (iv) For $1 \leq i \leq n$ and $1 \leq j \leq m_i$,

$$
-1 \le (r_{ij} + t_{ij})\omega_{ij} \le 0 \quad \text{and} \quad |r_{ij}|, |t_{ij}| \in \{r, r+1\},\,
$$

where $r = \min\{|r_{ij}|, |t_{ij}| : 1 \le i \le n, 1 \le j \le m_i\}$. Moreover, $r_{ij} \le 0, t_{ij} \ge 0$ when $\gamma \in \mathscr{G}_T^-$, and $r_{ij} \geq 0$, $t_{ij} \leq 0$ when $\gamma \in \mathscr{G}_T^+$.

(v)
$$
N_S(\gamma) = \sum_{i=1}^{n} (q_i - p_i)
$$
 and $N_T(\gamma) = \sum_{i=1}^{n} \sum_{j=1}^{m_i} (r_{ij} - t_{ij}).$

(B) If $n \geq m$, then γ is represented by a cyclic semi-reduced Γ -word $W(\gamma)$ of the form

$$
W(\gamma) = \prod_{i=1}^m T^{r_i} X^{\omega_i} T^{t_i} \left(\prod_{j=1}^{n_i} S^{p_{ij}} Y^{\varepsilon_{ij}} S^{q_{ij}} T^{\delta_{ij}} \right),
$$

where ε_{ij} , $\omega_i \in \{1, -1\}$, $n_i > 0$, and r_i , t_i , p_{ij} , q_{ij} and δ_{ij} are integers satisfying the following conditions:

- (i) $\sum_{i=1}^{m} n_i = n$.
- (ii) For $1 \leq i \leq m$, $\delta_{in_i} = 0$, and if $n_i > 1$, then $\delta_{ij} = \pm 1$ for $1 \leq j < n_i$. (iii) For $1 \leq i \leq m$,

$$
-1 \le (r_i + t_i)\omega_i \le 0 \text{ and } |r_i|, |t_i| \in \{r, r+1\},\
$$

where $r = \min\{|r_i|, |t_i| : 1 \le i \le m\}$. Moreover, $r_i \le 0$, $t_i \ge 0$ for all i when $\gamma \in \mathscr{G}_T^-$, and $r_i \geq 0$, $t_i \leq 0$ for all i when $\gamma \in \mathscr{G}_T^+$.

(iv) For $1 \leq i \leq m$ and $1 \leq j \leq n_i$,

$$
-1 \le (p_{ij} + q_{ij})\varepsilon_{ij} \le 0 \quad \text{and} \quad |p_{ij}|, |q_{ij}| \in \{p, p+1\},\,
$$

where $p = \min\{|p_{ij}|, |q_{ij}| : 1 \le i \le m, 1 \le j \le n_i\}$. Moreover, $p_{ij} \le 0, q_{ij} \ge 0$ when $\gamma \in \mathscr{G}_S^+$, and $p_{ij} \geq 0$, $q_{ij} \leq 0$ when $\gamma \in \mathscr{G}_S^-$. (v) $N_T(\gamma) = \sum_{i=1}^m (r_i - t_i)$ and $N_S(\gamma) = \sum_{i=1}^m \sum_{j=1}^{n_i} (q_{ij} - p_{ij}).$

Remark 5.1. If $I_X(\gamma) = I_Y(\gamma) = n$, then

$$
W(\gamma) = \prod_{i=1}^n S^{p_i} Y^{\varepsilon_i} S^{q_i} T^{r_i} X^{\omega_i} T^{t_i}.
$$

Proof of Theorem 5.3. From Propositions 2.1 and 2.3, the assertion (B) will follow from (A) by considering the geodesic $\Theta_2(\gamma)$. Thus, we shall assume that $m \geq n$. On the other hand, since $I_E(\Theta_1(\gamma)) = I_E(\gamma)$ for $E \in \{X, Y\}$, we may assume that $\gamma \in \mathscr{G}_S^+$.

Let W be a cyclic semi-reduced Γ -word representing γ . Then $\mathcal{I}_1^2(W)$ is of the form as given in equation (7):

$$
\mathcal{F}_1^2(W) = \prod_{i=1}^n S^{-p_i} Y^{\varepsilon_i} S^{q_i} \left(\prod_{j=1}^{m_i} T^{r_{ij}} X^{\omega_{ij}} T^{t_{ij}} S^{\delta_{ij}} \right)
$$

with $p_i > 0$ and $q_i > 0$ for all i, and thus

$$
W = \prod_{i=1}^n S^{-p'_i} Y^{\varepsilon_i} S^{q'_i} \left(\prod_{j=1}^{m_i} T^{r_{ij}} X^{\omega_{ij}} T^{t_{ij}} S^{\delta_{ij}} \right),
$$

where $p'_i = p_i - 1 \ge 0$ and $q'_i = q_i - 1 \ge 0$ for $i = 1, ..., n$. It follows from Proposition 2.7 that

$$
N_S(\gamma) = \sum_{i=1}^n (q'_i - p'_i)
$$
 and $N_T(\gamma) = \sum_{i=1}^n \sum_{j=1}^{m_i} (r_{ij} - t_{ij}).$

This proves condition (v).

It remains to prove that if γ is represented by the word W given in (A), then (iii)' $|p_i|, |q_i| \in \{p, p+1\}$ for $1 \le i \le n$, and $(iv)' |r_{ij}|, |t_{ij}| \in \{r, r+1\}$ for $1 \le i \le n$ and $1 \le j \le m_i$,

where

$$
p = \min\{|p_i|, |q_i| : 1 \le i \le n\}
$$
 and $r = \min\{|r_{ij}|, |t_{ij}| : 1 \le i \le n, 1 \le j \le m_i\}.$

Note that the other conditions follow from Lemma 2.6.

We shall prove condition $(iii)'$. Condition $(iv)'$ will follow by a similar argument. By applying a cyclic permutation to the word W , we may assume that $p = \min\{|p_1|, |q_1|\}.$ By considering W^{-1} , we may assume that $\varepsilon_1 = 1$.

Without loss of generality, we assume that $\gamma \in \mathscr{G}_S^+$, and write

$$
W = \prod_{i=1}^n S^{-p_i} Y^{\varepsilon_i} S^{q_i} \left(\prod_{j=1}^{m_i} T^{r_{ij}} X^{\omega_{ij}} T^{t_{ij}} S^{\delta_{ij}} \right), \quad p_i, q_i \ge 0 \text{ for all } i.
$$

Since $q_1 - p_1 = (q_1 - p_1)\varepsilon_1 \leq 0$, then $p = q_1$.

There is nothing to prove if $n = 1$. Assume that $n > 1$. Suppose that there is an $i_0 > 1$ such that $\max\{p_{i_0}, q_{i_0}\} > p + 1$.

$$
\mathcal{T}_1^{-2p}(W) = \prod_{i=1}^n S^{-p'_i} Y^{\varepsilon_i} S^{q'_i} \bigg(\prod_{j=1}^{m_i} T^{r_{ij}} X^{\omega_{ij}} T^{t_{ij}} S^{\delta_{ij}} \bigg),
$$

where $p'_i = p_i - p$ and $q'_i = q_i - p$ for all i.

Let $\gamma' = \overline{\mathscr{T}}_1^{-2p}(\gamma)$. Since $q'_1 = q_1 - p = 0$, then γ' has a strand joining the Y⁻¹-side to the E-side for some $E \in \{X^{\pm}, T^{\pm}\}\.$ On the other hand, $\max\{p'_{i_0}, q'_{i_0}\} > 1$, then γ' has a strand joining the S-side to the S^{-1} -side. This is impossible! The proof is complete.

5.2. Trace polynomials. In what follows, let G be the subgroup of $PSL(2, \mathbb{C})$ generated by the following four parabolic transformations:

$$
S = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}, \qquad T = \begin{pmatrix} 1 & 4 \\ 0 & 1 \end{pmatrix},
$$

$$
X = \begin{pmatrix} 1+4i & 16 \\ 1 & 1-4i \end{pmatrix} \text{ and } Y = \begin{pmatrix} 1+4i & 4 \\ 4 & 1-4i \end{pmatrix}.
$$

By using Maskit's first combination theorem ([8, Theorem VII.C.2]), one can prove that G is a regular B -group representing a five-punctured sphere and three thrice punctured spheres. The regular set of G has a simply connected component Ω_0 invariant under G such that $\Omega_0/G = \Sigma_5$. Such a Kleinian group G will be called a Maskit five-punctured group.

There is a connected and simply connected fundamental domain $\mathscr D$ for G acting on Ω_0 (see Figure 9) with $\Gamma = \{S^{\pm 1}, T^{\pm 1}, X^{\pm 1}, Y^{\pm 1}\}\$ the set of side pairings. The domain $\mathscr D$ may be schematically drawed as in Figure 1 with sides labelled as before. Thus every geodesic in $\mathscr G$ is represented by a cyclic semi-reduced Γ -word given in Theorem 5.1, Corollary 5.2 or Theorem 5.3.

Now, we consider the quasiconformal conjugates of G . Let f be a quasiconformal automorphism of \widehat{C} such that fGf^{-1} is a Kleinian group. If f is normalized

Figure 9. The fundamental domain \mathscr{D} .

to fix 0, 1 and ∞ , then fGf^{-1} is the subgroup of PSL(2, C) generated by S, T, X_{μ} and Y_{ν} , where

$$
X_{\mu} = \begin{pmatrix} 1 + \mu & -\mu^2 \\ 1 & 1 - \mu \end{pmatrix} \quad \text{and} \quad Y_{\nu} = \begin{pmatrix} 1 + 2\nu & 4 \\ -\nu^2 & 1 - 2\nu \end{pmatrix}
$$

with complex numbers μ and ν satisfying $|\mu| \geq 1$, $|\nu| \geq \frac{1}{2}$ $\frac{1}{2}$ and $|\mu\nu + 2| \ge 1$.

For any two non-zero complex numbers μ and ν , let $\tilde{G}(\mu, \nu)$ be the subgroup of PSL(2, C) generated by S, T, X_{μ} and Y_{ν} . We refer to the set \mathscr{M}_5 of all $(\mu, \nu) \in \mathbb{C}^{2}$ with $\text{Im}\,\mu > 0$ and $\text{Im}\,\nu > 0$ such that $G(\mu, \nu)$ is a Maskit fivepunctured group as the Maskit embedding of the Teichmüller space of Σ_5 .

For every $(\mu, \nu) \in M_5$, let $\rho_{(\mu,\nu)}: G \longrightarrow G(\mu, \nu)$ be the isomorphism defined by

$$
\rho_{(\mu,\nu)}(S) = S
$$
, $\rho_{(\mu,\nu)}(T) = T$, $\rho_{(\mu,\nu)}(X) = X_{\mu}$ and $\rho_{(\mu,\nu)}(Y) = Y_{\nu}$.

For every $\gamma \in \hat{\mathscr{G}}$, let $W(\gamma) \in G$ be a cyclic semi-reduced Γ -word representing γ , and let $W(\gamma;\mu,\nu) = \rho_{(\mu,\nu)}(W(\gamma))$. Write the trace polynomial tr $W(\gamma;\mu,\nu)$ as

$$
F(\gamma; \mu, \nu) = \text{tr} \, W(\gamma; \mu, \nu) = a_1 \mu^r \nu^s + a_2 \mu^{r-1} \nu^s + a_3 \mu^r \nu^{s-1} + O(r+s-2),
$$

where $a_1 \neq 0$, a_2 and a_3 are integers, and where $O(r + s - 2)$ is a polynomial in μ and ν of degree $\leq r + s - 2$. We call $a_1 \mu^r \nu^s + a_2 \mu^{r-1} \nu^s + a_3 \mu^r \nu^{s-1}$ the high order terms of $F(\gamma; \mu, \nu)$.

If $I_Y(\gamma) = 0$ and $I_X(\gamma) = m > 0$, then from [4, Theorem 3.4] we have

(8)
$$
F(\gamma; \mu, \nu) = \pm \{ \mu^{2m} + 4N_T(\gamma)\mu^{2m-1} \} + O(\mu^{2m-2}),
$$

where $O(\mu^{2m-2})$ is a polynomial in μ of degree $\leq 2m-2$.

If $I_X(\gamma) = 0$ and $I_Y(\gamma) = n > 0$, then from Lemma 5.4(ii) given below we have

(9)
$$
F(\gamma; \mu, \nu) = \pm 4^n \{ \nu^{2n} + 2N_S(\gamma) \nu^{2n-1} \} + O(\nu^{2n-2}),
$$

where $O(\nu^{2n-2})$ is a polynomial in ν of degree $\leq 2n-2$.

Lemma 5.4. If
$$
\gamma \in \mathcal{G}
$$
 with $I_X(\gamma) = m$ and $I_Y(\gamma) = n$, then
\n(i) $F(\Theta_1(\gamma); \mu, \nu) = F(\gamma; -\mu, -\nu)$,
\n(ii) $F(\Theta_2(\gamma); \mu, \nu) = F(\gamma; -2\nu, -\frac{1}{2}\mu)$,
\n(iii) $F(\mathcal{T}_1(\gamma); \mu, \nu) = (-1)^n F(\gamma; \mu, \nu + 1)$,
\n(iv) $F(\mathcal{T}_1^{-1}(\gamma); \mu, \nu) = (-1)^n F(\gamma; \mu, \nu - 1)$,
\n(v) $F(\mathcal{T}_2(\gamma); \mu, \nu) = (-1)^m F(\gamma; \mu - 2, \nu)$, and
\n(vi) $F(\mathcal{T}_2^{-1}(\gamma); \mu, \nu) = (-1)^m F(\gamma; \mu + 2, \nu)$.

Proof. Let

$$
C_1 = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} \quad \text{and} \quad C_2 = \begin{pmatrix} 0 & -2i \\ 1/2i & 0 \end{pmatrix},
$$

and let $\chi_j(A) = C_j A C_j^{-1}$ for all $A \in \text{PSL}(2, \mathbb{C})$. Set $\rho_j = \chi_j \Theta_j$. A direct computation gives

$$
\rho_j(S) = S,
$$
 $\rho_j(T) = T,$ $\rho_1(X_\mu) = X_{-\mu},$
\n $\rho_1(Y_\nu) = Y_{-\nu},$ $\rho_2(X_\mu) = X_{-2\nu},$ $\rho_2(Y_\nu) = Y_{-\mu/2}.$

By a similar argument as that in the proof of Lemma 3.3 of [4], the assertions (i) and (ii) will follow.

Since the transformations S, T and X_{μ} are invariant under \mathscr{T}_1 , and since

$$
\mathscr{T}_1(Y_\nu) = Y_\nu^{-1} S = -Y_{\nu+1}
$$
 and $\mathscr{T}_1^{-1}(Y_\nu) = S Y_\nu^{-1} = -Y_{\nu-1}$,

then (iii) and (iv) are valid. From (ii) and (iii), we have

$$
F(\mathcal{I}_2(\gamma);\mu,\nu) = F(\Theta_2 \mathcal{I}_1 \Theta_2(\gamma);\nu,\mu) = F(\mathcal{I}_1 \Theta_2(\gamma); -2\nu, -\frac{1}{2}\mu)
$$

= $(-1)^{I_Y} (\Theta_2(\gamma)) F(\Theta_2(\gamma); -2\nu, -\frac{1}{2}\mu + 1) = (-1)^m F(\gamma;\mu - 2,\nu).$

This proves (v). Similarly, the equation given in (vi) will follow from (ii) and (iv).

In the rest of this section, we shall compute the high-order terms of $F(\gamma;\mu,\nu)$ for $\gamma \in \widehat{\mathscr{G}}$ with $I_X(\gamma)I_Y(\gamma) > 0$.

Let $I_X(\gamma) = m$ and $I_Y(\gamma) = n$. Assume that $m \geq n$, and that $\gamma \in \mathscr{G}_T^-$. Then γ is represented by a cyclic semi-reduced Γ-word given below:

$$
W = \prod_{i=1}^n S^{p_i} Y^{\varepsilon_i} S^{q_i} \bigg(\prod_{j=1}^{m_i} T^{-r_{ij}} X^{\omega_{ij}} T^{t_{ij}} S^{\delta_{ij}} \bigg),
$$

where $r_{ij}, t_{ij} \geq 0$. Note that

$$
N_T(\gamma) = -\sum_{i=1}^n \sum_{j=1}^{m_i} (r_{ij} + t_{ij})
$$
 and $N_S(\gamma) = \sum_{i=1}^n (q_i - p_i).$

For integers $r \ge 0$, $t \ge 0$, p and q, and for $\omega, \delta, \varepsilon \in \{1, -1\}$, we have:

$$
T^{-r}X^{\omega}T^{t} = \begin{pmatrix} \omega\mu + 1 - 4r\omega & -\omega\mu^{2} + 4(r+t)\omega\mu + \text{const.} \\ \omega & -\omega\mu + 1 + 4t\omega \end{pmatrix},
$$

$$
S^{p}Y^{\varepsilon}S^{q} = \begin{pmatrix} 2\varepsilon\nu + 1 + 4\varepsilon q & 4\varepsilon \\ -\varepsilon\nu^{2} + 2\varepsilon(p-q)\nu + \text{const.} & -2\varepsilon\nu + 1 + 4\varepsilon p \end{pmatrix},
$$

$$
T^{-r}X^{\omega}T^{t}S^{\delta} =
$$

$$
\begin{pmatrix} -\omega \delta \mu^2 + (1 + 4(r + t) \delta) \omega \mu + \text{const.} & -\omega \mu^2 + 4(r + t) \omega \mu + \text{const.} \\ -\omega \delta \mu + \text{const.} & -\omega \mu + 1 + 4t \omega \end{pmatrix}.
$$

For $i = 1, \ldots, n$, let $\xi_i = \omega_{i1}$ when $m_i = 1$, let

$$
\xi_i = \left(\prod_{j=1}^{m_i} \omega_{ij}\right) \left(\prod_{j=1}^{m_i-1} \delta_{ij}\right) \text{ when } m_i > 1, \lambda_i = 4 \sum_{j=1}^{m_i} (r_{ij} + t_{ij}),
$$

and let

$$
W_i = \prod_{j=1}^{m_i} T^{-r_{ij}} X^{\omega_{ij}} T^{t_{ij}} S^{\delta_{ij}} = \begin{pmatrix} a_i(\mu) & b_i(\mu) \\ c_i(\mu) & d_i(\mu) \end{pmatrix}.
$$

If $m_i = 1$, then

$$
a_i(\mu) = \xi_i(\mu + \text{const.}) = \xi_i(\mu^{2m_i - 1} + \cdots),
$$

\n
$$
b_i(\mu) = -\xi_i(\mu^2 - \lambda_i\mu + \text{const.}) = -\xi_i(\mu^{2m_i} - \lambda_i\mu^{2m_i - 1} + \cdots),
$$

\n
$$
c_i(\mu) = \xi_i = \xi_i(\mu^{2m_i - 2} + \cdots), \text{ and}
$$

\n
$$
d_i(\mu) = -\xi_i(\mu + \text{const.}) = -\xi_i(\mu^{2m_i - 1} + \cdots).
$$

By induction, one can show that for $m_i \geq 1$

$$
a_i(\mu) = (-1)^{m_i} \xi_i(-\mu^{2m_i-1} + \cdots),
$$

\n
$$
b_i(\mu) = (-1)^{m_i} \xi_i(\mu^{2m_i} - \lambda_i \mu^{2m_i-1} + \cdots),
$$

\n
$$
c_i(\mu) = (-1)^{m_i} \xi_i(-\mu^{2m_i-2} + \cdots),
$$
 and
\n
$$
d_i(\mu) = (-1)^{m_i} \xi_i(\mu^{2m_i-1} + \cdots).
$$

For every $i = 1, \ldots, n$, let

$$
S^{p_i}Y^{\varepsilon_i}S^{q_i}W_i=\begin{pmatrix}\tilde{a}_i(\mu,\nu)&\tilde{b}_i(\mu,\nu)\\ \tilde{c}_i(\mu,\nu)&\tilde{d}_i(\mu,\nu)\end{pmatrix},\,
$$

and for every $n \text{ let }$

$$
\prod_{i=1}^n S^{p_i} Y^{\varepsilon_i} S^{q_i} W_i = \begin{pmatrix} A_n(\mu, \nu) & B_n(\mu, \nu) \\ C_n(\mu, \nu) & D_n(\mu, \nu) \end{pmatrix}.
$$

A direct computation gives:

$$
\deg \tilde{a}_i = 2m_i, \quad \deg \tilde{b}_i = 2m_i + 1 = \deg \tilde{c}_i, \quad \deg \tilde{d}_i = 2m_i + 2
$$

and

$$
\tilde{d}_i(\mu,\nu) = (-1)^{m_i-1} \xi_i \varepsilon_i (\nu^2 \mu^{2m_i} - \lambda_i \nu^2 \mu^{2m_i-1} + 2(q_i - p_i) \nu \mu^{2m_i} + \cdots).
$$

By applying induction to n , we have

$$
\deg A_n(\mu, \nu) = 2(n - 1) + 2 \sum_{i=1}^n m_i,
$$

$$
\deg B_n(\mu, \nu) = 2n - 1 + 2 \sum_{i=1}^n m_i = \deg C_n(\mu, \nu),
$$

$$
\deg D_n(\mu, \nu) = 2n + 2 \sum_{i=1}^n m_i,
$$

and the high-order terms of $D_n(\mu,\nu)$ are determined by

$$
\prod_{i=1}^n \tilde{d}_i(\mu,\nu) = \prod_{i=1}^n (-1)^{m_i-1} \xi_i \varepsilon_i (\nu^2 \mu^{2m_i} - \lambda_i \nu^2 \mu^{2m_i-1} + 2(q_i - p_i) \nu \mu^{2m_i} + \cdots).
$$

Since $F(\gamma;\mu,\nu) = A_n(\mu,\nu) + D_n(\mu,\nu)$ and $\deg A_n(\mu,\nu) < \deg D_n(\mu,\nu) - 1$, then the high-order terms of $F(\gamma;\mu,\nu)$ are determined by $D_n(\mu,\nu)$.

For any two polynomials

$$
f(\mu, \nu) = a_1 \mu^r \nu^s + a_2 \mu^{r-1} \nu^s + a_3 \mu^r \nu^{s-1} + \cdots \text{ and}
$$

$$
g(\mu, \nu) = b_1 \mu^{r'} \nu^{s'} + b_2 \mu^{r'-1} \nu^{s'} + b_3 \mu^{r'} \nu^{s'-1} + \cdots,
$$

the high-order terms of the polynomial $f(\mu, \nu)g(\mu, \nu)$ is

$$
a_1b_1\mu^{r+r'}\nu^{s+s'} + (a_1b_2 + a_2b_1)\mu^{r+r'-1}\nu^{s+s'} + (a_1b_3 + a_3b_1)\mu^{r+r'}\nu^{s+s'-1}.
$$

Thus, we have

$$
F(\gamma; \mu, \nu) = \pm \left\{ \nu^{2n} \mu^{2m} - \left(\sum_{i=1}^n \lambda_i \right) \nu^{2n} \mu^{2m-1} + 2 \left(\sum_{i=1}^n (q_i - p_i) \right) \mu^{2m} \nu^{2n-1} + \cdots \right\}
$$

= $\pm \{ \mu^{2m} \nu^{2n} + 4N_T(\gamma) \mu^{2m-1} \nu^{2n} + 2N_S(\gamma) \mu^{2m} \nu^{2n-1} + \cdots \}.$

From Proposition 2.1 and Lemma 5.4, the above equations are also valid for $\gamma \in \mathscr{G}_T^+$ with $I_X(\gamma) \geq I_Y(\gamma)$.

If $n = I_Y(\gamma) \ge I_X(\gamma) = m$, then, by Proposition 2.1 and Lemma 5.4 again, we have

$$
F(\gamma; \mu, \nu) = F(\Theta_2(\gamma); -2\nu, -\frac{1}{2}\mu)
$$

= $\pm 4^{n-m} \{ \mu^{2m} \nu^{2n} + 4N_T(\gamma) \mu^{2m-1} \nu^{2n} + 2N_S(\gamma) \mu^{2m} \nu^{2n-1} + \cdots \}.$

Summing up above discussion together with equations (8) and (9), we have proved the following theorem.

Theorem 5.5 (trace formula). Let $\gamma \in \widehat{\mathscr{G}}$ with $I_X(\gamma) = m$ and $I_Y(\gamma) = n$. If $m \geq n$, then

$$
F(\gamma; \mu, \nu) = \pm \{ \mu^{2m} \nu^{2n} + 4N_T(\gamma) \mu^{2m-1} \nu^{2n} + 2N_S(\gamma) \mu^{2m} \nu^{2n-1} + \cdots \}.
$$

If $m \leq n$, then

$$
F(\gamma; \mu, \nu) = \pm 4^{n-m} \{ \mu^{2m} \nu^{2n} + 4N_T(\gamma) \mu^{2m-1} \nu^{2n} + 2N_S(\gamma) \mu^{2m} \nu^{2n-1} + \cdots \}.
$$

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