# Further properties of accretive matrices 

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#### Abstract

To better understand the algebra $\mathcal{M}_{n}$ of all $n \times n$ complex matrices, we explore the class of accretive matrices. This class has received renowned attention in recent years due to its role in complementing those results known for positive definite matrices. Among many results, we present order-preserving results, Choi-Davis-type inequalities, mean-convex inequalities, submultiplicative results for the real part, and new bounds of the absolute value of accretive matrices. These results will be compared with the existing literature. In the end, we quickly pass through related entropy results for accretive matrices.


## Lisää kasvattavien matriisien ominaisuuksia

Tiivistelmä. Kompleksikertoimisten $n \times n$-matriisien algebran $\mathcal{M}_{n}$ paremmaksi ymmärtämiseksi tutkitaan tässä työssä ns. kasvattavien matriisien luokkaa. Tämä positiivisia matriiseja yleistävä luokka näiden teoriaa täydentävine tuloksineen on saanut paljon huomiota viime vuosina. Muiden muassa esitämme järjestyksen säilyttämistä koskevia tuloksia, Choin-Davisin-tyyppisiä epäyhtälöitä, keskikonveksisuusepäyhtälöitä, reaaliosan alitulomuotoisuustuloksia sekä uusia rajoja kasvattavien matriisien itseisarvolle. Näitä tuloksia verrataan aiempaan kirjallisuuteen. Lopuksi käydään lyhyesti läpi kasvattavia matriiseja koskevia entropiatuloksia.

## 1. Introduction

Let $\mathcal{M}_{n}$ be the class of all $n \times n$ complex matrices, with identity $I$. Inequalities among elements of $\mathcal{M}_{n}$ has been an active research area due to its applications in various fields, not to mention its role in understanding the algebra $\mathcal{M}_{n}$.

However, order among elements in $\mathcal{M}_{n}$ is restricted to the so-called Hermitian matrices. A matrix $A \in \mathcal{M}_{n}$ is said to be Hermitian if $A^{*}=A$, where $A$ is the conjugate transpose of $A$. A special class of the Hermitian matrices is the positive ones. We recall that a matrix $A \in \mathcal{M}_{n}$ is said to be positive semi-definite, and we write $A \geq 0$, if it satisfies $\langle A x, x\rangle \geq 0$, for all $x \in \mathbb{C}^{n}$, where $\langle\cdot, \cdot\rangle$ denotes the usual inner product in $\mathbb{C}^{n}$. The notation $\mathcal{M}_{n}^{+}$will denote the class of positive semidefinite matrices in $\mathcal{M}_{n}$. Further, if $A \in \mathcal{M}_{n}^{+}$is invertible, we say that $A$ is positive definite, and we write $A \in \mathcal{P}_{n}$ or $A>0$. Having defined $\mathcal{M}_{n}^{+}$, a partial order on $\mathcal{H}_{n}$, the class of all Hermitian matrices in $\mathcal{M}_{n}$, can be defined. For $A, B \in \mathcal{H}_{n}$, we say that $A \leq B$ if $B-A \geq 0$. If $B-A>0$, then we write $B>A$.

Defining this order on $\mathcal{H}_{n}$ then proposes the question about possible functional ordering in a way that simulates the field of real numbers. For example, if $f: J \rightarrow \mathbb{R}$ is an increasing function on the interval $J$ then $f(a) \leq f(b)$ for any $a, b \in J$ satisfying $a \leq b$. The natural question then arises about the validity of the conclusion $f(A) \leq$ $f(B)$ when $A, B \in \mathcal{H}_{n}$ are such that $A \leq B$. This turns out to be much more complicated.

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For $A \in \mathcal{H}_{n}$, let $\sigma(A)$ denote the spectrum of $A$. An interval $J$ containing $\sigma(A)$ will be denoted as $J_{A}$. If $f: J_{A} \rightarrow \mathbb{R}$ is a given function, then $f(A)$ is defined via the simple identity $f(A)=U \operatorname{diag}\left(f\left(\lambda_{i}\right)\right) U j$, where $U \operatorname{diag}\left(\lambda_{i}\right) U^{*}$ is a spectral decomposition of $A$, in which $U$ is unitary and $\left\{\lambda_{i}: i=1, \cdots, n\right\}=\sigma(A)$.

It is unfortunate that a monotone increasing function $f: J_{A, B} \rightarrow \mathbb{R}$ does not satisfy $f(A) \leq f(B)$ even when $A, B \in \mathcal{H}_{n}$ are such that $A \leq B$. This unpleasant scenario can be also said about convex functions.

This urges the search for possible classes of functions or matrices that could satisfy matrix inequalities as in the scalar case. For this, operator monotone functions were defined as those functions preserving order among Hermitian matrices. That is, a function $f: J \rightarrow \mathbb{R}$ is said to be operator monotone if $f(A) \leq f(B)$ for any $A, B \in \mathcal{H}_{n}$ are such that $A \leq B$ and $\sigma(A), \sigma(B) \subset J$. Further, $f$ will be called operator convex if $f((1-t) A+t B) \leq(1-t) f(A)+t f(B)$ for all $t \in[0,1]$, where $A, B \in \mathcal{H}_{n}$ are such that $\sigma(A), \sigma(B) \subset J$. If $-f$ is operator monotone, it is said to be operator monotone decreasing, and if $-f$ is operator convex it is said to be operator concave.

We refer the reader to [10, Chapter V] for an excellent discussion of operator monotone and operator convex functions. We also refer the reader to $[6,12,13,20$, $24,26,23,32,33,37,42,41]$ for a good list of references treating matrix orders.

In recent years, more interest has grown in studying inequalities among the socalled accretive matrices. Recall that a matrix $A \in \mathcal{M}_{n}$ is said to be accretive if $\mathfrak{R}(A)>0$, where $\mathfrak{R}(A)$ is the real part of $A$ defined by $\mathfrak{R}(A)=\frac{A+A^{*}}{2}$. The class of accretive matrices in $\mathcal{M}_{n}$ will be denoted by $\Pi_{n}$. It is clear that $\mathcal{P}_{n} \subset \Pi_{n}$. Since elements of $\Pi_{n}$ are not necessarily Hermitian, the predefined order does not apply to $\Pi_{n}$. This is why inequalities among accretive matrices are usually stated in terms of their real parts. We must introduce sectorial matrices to deal with inequalities in $\Pi_{n}$. If $0 \leq \alpha<\frac{\pi}{2}$, and if $A \in \mathcal{M}_{n}$ is such that

$$
\left\{\langle A x, x\rangle: x \in \mathbb{C}^{n},\|x\|=1\right\} \subset\{z \in \mathbb{C}: \mathfrak{R}(z)>0,|\Im(z)| \leq(\tan \alpha) \mathfrak{R}(z)\}
$$

then $A$ will be called a sectorial matrix and we simply write $A \in \Pi_{n}^{\alpha}$, where $\mathfrak{I}(z)$ denotes the imaginary part of $z$. We refer the reader to $[6,7,8,9,14,25,30,31,40$, $44,45]$ for an almost comprehensive overview of the progress that has been made in studying inequalities in $\Pi_{n}$. We emphasize here that whenever we use the notation $\Pi_{n}^{\alpha}$ in this paper, we implicitly understand that $0 \leq \alpha<\frac{\pi}{2}$. We also remark that a matrix is accretive if and only if it is sectorial [9].

The study of accretive matrices differs from that of Hermitian matrices because a partial order among members of $\Pi_{n}$ is not as well established as that in $\mathcal{H}_{n}$. So, in studying inequalities among members of $\Pi_{n}$, we usually refer to the real parts of these elements, noting that the real part of any matrix is in $\mathcal{H}_{n}$.

Our target in this paper is to study further possible inequalities among matrices in $\Pi_{n}$, where we extend some of the well-established inequalities in $\mathcal{P}_{n}$ or $\mathcal{M}_{n}^{+}$to the class $\Pi_{n}$. For this to be done, we first need to define $f(A)$ where $A \in \Pi_{n}$ and $f: J_{A} \rightarrow \mathbb{R}$.

Given $A \in \mathcal{M}_{n}$, let $f: \mathcal{D} \rightarrow \mathbb{C}$ be a complex-valued function defined on a domain that contains $\sigma(A)$ in its interior. If $f$ is analytic in $\mathcal{D}$, we define

$$
\begin{equation*}
f(A)=\frac{1}{2 \pi i} \int_{C} f(z)(z I-A)^{-1} d z \tag{1.1}
\end{equation*}
$$

where $C$ is any simple closed curve in $\mathcal{D}$ that surrounds $\sigma(A)$. Practically, this generalizes the well-known complex Cauchy integral formula.

Now if $A \in \Pi_{n}$, then $\sigma(A) \cap(-\infty, 0]=\varnothing$. Therefore, if $f$ is analytic in any domain that avoids the negative $x$-axis, then $f(A)$ can be defined via (1.1). For simplicity, we will use the notation
$\mathfrak{m}=\{f:(0, \infty) \rightarrow(0, \infty) ; f$ is an operator monotone function with $f(1)=1\}$.
The following lemmas deserve mentioning here.
Lemma 1.1. [22, Theorem 4.9] Let $f \in \mathfrak{m}$. Then

$$
f(x)=\int_{0}^{1}\left(1!_{t} x\right) d \nu_{f}(t)
$$

where $\nu_{f}$ is a probability measure on $[0,1]$ and $1!_{t} x=\left(1-t+t x^{-1}\right)^{-1}$.
Lemma 1.2. [10, Theorem V.4.7] Let $f \in \mathfrak{m}$. Then $f$ has an analytic continuation to $\mathbb{C} \backslash(-\infty, 0]$.

Thus, if $f \in \mathfrak{m}$, we may deal with its analytic continuation to find $f(A)$ for any matrix $A$ whose spectrum avoids the negative $x$-axis, where we can use (1.1). Operator monotone functions and operator concave functions are strongly related, as follows [47, Theorem 2.4] and [5, Theorems 2.1, 2.3, 3.1, 3.7].

Proposition 1.1. Let $f:(0, \infty) \rightarrow[0, \infty)$ be continuous. Then
(i) $f$ is operator monotone decreasing if and only if $f$ is operator convex and $f(\infty)<\infty$,
(ii) $f$ is operator monotone increasing if and only if $f$ is operator concave.

Consequently, $f \in \mathfrak{m}$ means that $f$ is operator monotone and operator concave.
On the other hand, the following two lemmas from [6] will be needed in the sequel.

Lemma 1.3. Let $f \in \mathfrak{m}$ and $A \in \Pi_{n}$. Then

$$
\mathfrak{R}(f(A)) \geq f(\Re A) .
$$

Consequently, if $A$ is accretive, then so is $f(A)$.
Lemma 1.4. Let $f \in \mathfrak{m}$ and $A \in \Pi_{n}^{\alpha}$. Then

$$
\mathfrak{R}(f(A)) \leq \sec ^{2}(\alpha) f(\Re A) .
$$

We recall that a linear mapping $\Phi: \mathcal{M}_{n} \rightarrow \mathcal{M}_{n}$ is said to be positive if $\Phi(A) \in$ $\mathcal{M}_{n}^{+}$whenever $A \in \mathcal{M}_{n}^{+}$. Further, if $\Phi(I)=I$, then $\Phi$ is said to be a unital positive linear mapping. The celebrated Choi-Davis inequality states that $[4,12]$

$$
\Phi(f(A)) \leq f(\Phi(A))
$$

for $f \in \mathfrak{m}$ and $A \in \mathcal{M}_{n}^{+}$, where $\Phi$ is a unital positive linear mapping. When $A$ is accretive, we have the following version of this inequality [6, Theorem 7.1].

Lemma 1.5. Let $f \in \mathfrak{m}$, $\Phi$ be a unital positive linear map and $A \in \Pi_{n}^{\alpha}$. Then

$$
\mathfrak{R} f(\Phi(A)) \geq \cos ^{2}(\alpha) \Re \Phi(f(A)) .
$$

Related to these lemmas, we cite the following lemma from [29].
Lemma 1.6. Let $A \in \Pi_{n}$. Then $\mathfrak{R}\left(A^{-1}\right) \leq(\Re A)^{-1}$.
The so-called operator mean is strongly related to the class $\mathfrak{m}$. Given $A, B \in \mathcal{P}_{n}$ and $f \in \mathfrak{m}$, we define $\sigma_{f}: \mathcal{P}_{n} \times \mathcal{P}_{n} \rightarrow \mathcal{P}_{n}$ by

$$
\begin{equation*}
A \sigma_{f} B=A^{\frac{1}{2}} f\left(A^{-\frac{1}{2}} B A^{-\frac{1}{2}}\right) A^{\frac{1}{2}} \tag{1.2}
\end{equation*}
$$

This binary operation is usually called operator mean, associated with $f$. If no confusion arises, we use $\sigma$ instead of $\sigma_{f}$. The theory of operator means has received considerable attention in the literature, as seen in [3, 28, 35, 39]. The theory of operator means has been extended to accretive matrices in [6], using the same identity as in (1.2). We refer the reader to [6] for a detailed discussion of this topic. We also refer the reader to $[14,40,44]$ for interesting related discussion.

Extending some results from [14, 40], the following inequality was shown in [6] for any $A, B \in \Pi_{n}^{\alpha}$ and any operator mean $\sigma$ (or $\sigma_{f}$ for some $f \in \mathfrak{m}$ ):

$$
\begin{equation*}
\mathfrak{R} A \sigma \mathfrak{R} B \leq \mathfrak{R}(A \sigma B) \leq \sec ^{2} \alpha \mathfrak{R} A \sigma \mathfrak{R} B . \tag{1.3}
\end{equation*}
$$

The following lemma has also been shown in [6].
Lemma 1.7. Let $A, B \in \Pi_{n}^{\alpha}$ for some $0 \leq \alpha<\frac{\pi}{2}$. If $f \in \mathfrak{m}$ is such that $f^{\prime}(1)=t$ for some $t \in(0,1)$, then

$$
\cos ^{2}(\alpha) \mathfrak{R}\left(A!_{t} B\right) \leq \mathfrak{R}\left(A \sigma_{f} B\right) \leq \sec ^{2}(\alpha) \mathfrak{R}\left(A \nabla_{t} B\right),
$$

where $A!{ }_{t} B=\left((1-t) A^{-1}+t B^{-1}\right)^{-1}$ and $A \nabla_{t} B=(1-t) A+t B$ are the weighted harmonic and arithmetic means, respectively.

The next section presents several new relations and inequalities for elements in $\Pi_{n}$ and $\Pi_{n}^{\alpha}$. To make it easier for the reader to follow, we will emphasize the significance of each result by presenting the existing related result in the literature. Our discussion will include order-preserving inequalities, Choi-Davis-type inequalities, mean inequalities, entropy results, and other characterizations.

Among the most interesting findings in this paper, we show that if $A>0$, then

$$
\mathfrak{R}\left(Y A^{-1} Y\right) \leq \mathfrak{R} Y A^{-1} \mathfrak{R} Y
$$

for any $Y \in \mathcal{M}_{n}$. We also show that if $T \in \Pi_{n}^{\alpha}$, then

$$
|T| \leq \sec \alpha\left|(\Re T)^{\frac{1}{2}} U(\Re T)^{\frac{1}{2}}\right|
$$

for some unitary $U$, where $|X|=\left(X^{*} X\right)^{1 / 2}$, when $X \in \mathcal{M}_{n}$.
Discussion of entropy-like results for accretive matrices will be presented, as a new track in this field.

## 2. Main results

In this section, we present our results. To make it easier and more accessible for the reader, we present these results in consequent subsections.
2.1. Order preserving results. In the next theorem, we show a LöwnerHeinz theorem for accretive matrices. More precisely, if $f \in \mathfrak{m}$ and $0<A \leq B$, then $f(A) \leq f(B)$. This is indeed the definition of operator monotony. The following result extends this to the class of sectorial matrices by appealing to the real parts.

Theorem 2.1. Let $f \in \mathfrak{m}$ and $A, B \in \Pi_{n}^{\alpha}$. Then

$$
\Re A \leq \Re B \Rightarrow \Re f(A) \leq \sec ^{2} \alpha \Re f(B) .
$$

In particular,

$$
\begin{equation*}
\Re A \leq \Re B \Rightarrow \Re A^{r} \leq \sec ^{2} \alpha \Re B^{r} ; 0 \leq r \leq 1 . \tag{2.1}
\end{equation*}
$$

Proof. We have

$$
\begin{array}{rlrl}
\mathfrak{\Re} f(A) & \leq \sec ^{2} \alpha f(\Re A) & & \text { (by Lemma 1.4) } \\
& \leq \sec ^{2} \alpha f(\Re B) & & \text { (since } f \text { is operator monotone and } \mathfrak{R A \leq \mathfrak { R } B )} \\
& \leq \sec ^{2} \alpha \Re f(B) & \text { (by Lemma 1.3). }
\end{array}
$$

This completes the proof.
We know that if $A \in \Pi_{n}^{\alpha}$, then [15]

$$
\begin{equation*}
(\Re A)^{-1} \leq \sec ^{2} \alpha \Re A^{-1} . \tag{2.2}
\end{equation*}
$$

The following result is an application of the inequality (2.2),

$$
\mathfrak{R A \sharp \Re A ^ { - 1 } \geq \frac { 1 } { \operatorname { s e c } \alpha } ( \mathfrak { R } A \sharp ( \Re A ) ^ { - 1 } ) = \frac { 1 } { \operatorname { s e c } \alpha } I . . . . . . .}
$$

Therefore,

$$
\mathfrak{R} A \sharp \Re A^{-1} \geq \frac{1}{\sec \alpha} I .
$$

Here the notation $\sharp$ refers to the geometric mean, which is defined for any $A, B \in \Pi_{n}$ as follows

$$
A \sharp B=A^{\frac{1}{2}}\left(A^{-\frac{1}{2}} B A^{-\frac{1}{2}}\right)^{\frac{1}{2}} A^{\frac{1}{2}} .
$$

Remark 2.1. Notice that when $A, B \in \Pi_{n}^{\alpha}$, we have, for $0 \leq r \leq 1$,

$$
\mathfrak{R} A \leq \mathfrak{R} B \Rightarrow \mathfrak{R} B^{-r} \leq \sec ^{4} \alpha \Re A^{-r},
$$

since

$$
\begin{aligned}
\mathfrak{R} B^{-r} & \leq\left(\Re B^{r}\right)^{-1} \quad(\text { by Lemma } 1.6) \\
& \leq \sec ^{2} \alpha\left(\mathfrak{R} A^{r}\right)^{-1} \quad(\text { by }(2.1)) \\
& \leq \sec ^{4} \alpha \Re A^{-r} \quad(\text { by }(2.2)) .
\end{aligned}
$$

2.2. Choi-Davis type inequalities. It is known that if $f \in \mathfrak{m}, A_{i} \in \mathcal{M}_{n}^{+}$and $C_{i} \in \mathcal{M}_{n}$ are such that $\sum_{i=1}^{k} C_{i}^{*} C_{i}=I$, then [20, Theorem 1.9]

$$
\begin{equation*}
f\left(\sum_{i=1}^{k} C_{i}^{*} A_{i} C_{i}\right) \geq \sum_{i=1}^{k} C_{i}^{*} f\left(A_{i}\right) C_{i} . \tag{2.3}
\end{equation*}
$$

At this point, we show the accretive version of this inequality. We notice that when $A \in \Pi_{n}^{\alpha}$, then $C^{*} A C \in \Pi_{n}^{\alpha}$ for any $C \in \mathcal{M}_{n}$. In order to show the accretive version of (2.3), we first present the following simple lemma.

Lemma 2.1. Let $A, B \in \Pi_{n}^{\alpha}$. Then $A+B \in \Pi_{n}^{\alpha}$.
Proof. By definition of $\Pi_{n}^{\alpha}$, we have

$$
|\Im\langle A x, x\rangle| \leq \tan \alpha \Re\langle A x, x\rangle \quad \text { and } \quad|\Im\langle B x, x\rangle| \leq \tan \alpha \Re\langle B x, x\rangle, \quad x \in \mathbb{C}^{n} .
$$

Adding these two inequalities, we get

$$
\begin{aligned}
\tan \alpha \mathfrak{R}\langle(A+B) x, x\rangle & \geq|\mathfrak{I}\langle A x, x\rangle|+|\mathfrak{I}\langle B x, x\rangle| \\
& \geq|\mathfrak{I}\langle A x, x\rangle+\mathfrak{I}\langle B x, x\rangle| \\
& =|\mathfrak{I}\langle(A+B) x, x\rangle| .
\end{aligned}
$$

This completes the proof.
Consequently, if $A_{i} \in \Pi_{n}^{\alpha}$ and $C_{i} \in \mathcal{M}_{n},(i=1, \cdots, k)$, then $\sum_{i=1}^{k} C_{i}^{*} A_{i} C_{i} \in \Pi_{n}^{\alpha}$. We are ready to show the sectorial version of (2.3).

Proposition 2.1. Let $A_{i} \in \Pi_{n}^{\alpha}$ and $C_{i} \in \mathcal{M}_{n},(i=1, \cdots, k)$ be such that $\sum_{i=1}^{k} C_{i}^{*} C_{i}=I$. Then

$$
\begin{equation*}
\mathfrak{R}\left(\sum_{i=1}^{n} C_{i}^{*} f\left(A_{i}\right) C_{i}\right) \leq \sec ^{2} \alpha \Re f\left(\sum_{i=1}^{n} C_{i}^{*} A_{i} C_{i}\right), \tag{2.4}
\end{equation*}
$$

where $\sum_{i=1}^{n} C_{i}^{*} C_{i}=I$.
Proof. First, we notice that if $C \in \mathcal{M}_{n}$ is such that $C^{*} C=I$, then the mapping $\Phi: \mathcal{M}_{n} \rightarrow \mathcal{M}_{n}$ defined by $\Phi(X)=C^{*} X C$ is unital positive linear mapping. Therefore, Lemma 1.5 implies

$$
\begin{equation*}
\mathfrak{R}\left(C^{*} f(A) C\right) \leq \sec ^{2} \alpha \Re f\left(C^{*} A C\right) \tag{2.5}
\end{equation*}
$$

where $f \in \mathfrak{m}, C^{*} C=I$ and $A \in \Pi_{n}^{\alpha}$. Let

$$
X=\left[\begin{array}{cccc}
A_{1} & & & O \\
& A_{2} & & \\
& & \ddots & \\
O & & & A_{k}
\end{array}\right] \quad \text { and } \quad \widetilde{C}=\left[\begin{array}{c}
C_{1} \\
C_{2} \\
\vdots \\
C_{k}
\end{array}\right]
$$

It follows, by the same argument preceding the theorem, that $\widetilde{C}^{*} X \widetilde{C} \in \Pi_{n}^{\alpha}$. Now, noting that $\widetilde{C}^{*} \widetilde{C}=I$, we have

$$
\begin{aligned}
\mathfrak{R}\left(\sum_{i=1}^{n} C_{i}^{*} f\left(A_{i}\right) C_{i}\right) & =\mathfrak{R}\left(\widetilde{C}^{*} f(X) \widetilde{C}\right) \\
& \leq \sec ^{2} \alpha \mathfrak{R} f\left(\widetilde{C}^{*} X \widetilde{C}\right) \quad(\text { by }(2.5)) \\
& =\sec ^{2} \alpha \mathfrak{R} f\left(\sum_{i=1}^{n} C_{i}^{*} A_{i} C_{i}\right)
\end{aligned}
$$

This completes the proof.
Extending (2.5), we can state the following result.
Theorem 2.2. Let $f \in \mathfrak{m}$ and let $C \in \mathcal{M}_{n}$ be such that $C^{*} C \leq I$. Then

$$
\mathfrak{R}\left(C^{*} f(A) C\right) \leq \sec ^{2} \alpha \mathfrak{R} f\left(C^{*} A C\right),
$$

for any $A \in \Pi_{n}^{\alpha}$.
Proof. Put $D=\sqrt{I-C^{*} C}$, where $C$ is a contraction (i.e., $C^{*} C \leq I$ ), and let $X_{n}=\frac{1}{n} I$, where $n \in \mathbb{N}$. Notice that $f\left(X_{n}\right) \geq 0$ because $f \in \mathfrak{m}$, and hence $D^{*} f\left(X_{n}\right) D^{2} \geq 0$. Since $C^{*} C+D^{*} D=I$, we can write from (2.4) that

$$
\begin{aligned}
\mathfrak{R}\left(C^{*} f(A) C\right) & \leq \mathfrak{R}\left(C^{*} f(A) C+D^{*} f\left(X_{n}\right) D\right) \\
& \leq \sec ^{2} \alpha \Re f\left(C^{*} A C+D^{*} X_{n} D\right) .
\end{aligned}
$$

Letting $n \rightarrow \infty$ implies the desired result.
2.3. Means inequalities. We have seen in (1.3) that

$$
\mathfrak{R} A \sigma \Re B \leq \mathfrak{R}(A \sigma B) \leq \sec ^{2} \alpha \mathfrak{R} A \sigma \mathfrak{R} B .
$$

In one way or another, this inequality is related to the so-called Callebaut inequality, whose matrix version states that if $A_{i}, B_{i} \in \mathcal{P}_{n}$, and if $\sigma$ is an operator mean, then [34]

$$
\begin{equation*}
\sum_{i=1}^{k}\left(A_{i} \sharp B_{i}\right) \leq\left(\sum_{i=1}^{k} A_{i} \sigma B_{i}\right) \sharp\left(\sum_{i=1}^{k} A_{i} \sigma^{\perp} B_{i}\right) \leq\left(\sum_{i=1}^{k} A_{i}\right) \sharp\left(\sum_{i=1}^{k} B_{i}\right), \tag{2.6}
\end{equation*}
$$

where $\sigma^{\perp}$ is the operator mean associated with the function $\frac{t}{f(t)}$. Here $f \in \mathfrak{m}$ is the function characterizing $\sigma$ as in (1.2).

If $A, B \in \mathcal{P}_{n}$, (2.6) reduces to (for $k=1$ )

$$
\begin{equation*}
A \sharp B=(A \sigma B) \sharp\left(A \sigma^{\perp} B\right) . \tag{2.7}
\end{equation*}
$$

Related to the above inequality and in connection with our argument below, the following inequality is useful [36, Theorem 5.7]

$$
\begin{equation*}
\sum_{i=1}^{k}\left(A_{i} \sigma B_{i}\right) \leq\left(\sum_{i=1}^{k} A_{i}\right) \sigma\left(\sum_{i=1}^{k} B_{i}\right) \tag{2.8}
\end{equation*}
$$

Now we present the sectorial version of Callebaut inequality.
Theorem 2.3. Let $A_{i}, B_{i} \in \Pi_{n}^{\alpha}$ and let $\sigma=\sigma_{f}$ for some $f \in \mathfrak{m}$. Then

$$
\begin{aligned}
\sum_{i=1}^{n} \Re A_{i} \sharp \Re B_{i} & \leq\left(\sum_{i=1}^{k} \mathfrak{R} A_{i} \sigma \mathfrak{R} B_{i}\right) \sharp\left(\sum_{i=1}^{k} \mathfrak{\Re} A_{i} \sigma^{\perp} \mathfrak{R} B_{i}\right) \\
& \leq \sec ^{2} \alpha \mathfrak{R}\left(\sum_{i=1}^{k} A_{i}\right) \sharp \Re\left(\sum_{i=1}^{k} B_{i}\right) .
\end{aligned}
$$

Proof. We have

$$
\begin{aligned}
\sum_{i=1}^{n} \mathfrak{R} A_{i} \sigma \mathfrak{R} B_{i} & \leq\left(\sum_{i=1}^{k} \mathfrak{R} A_{i}\right) \sigma\left(\sum_{i=1}^{k} \mathfrak{R} B_{i}\right) \quad(\text { by }(2.8)) \\
& =\left(\mathfrak{R} \sum_{i=1}^{k} A_{i}\right) \sigma\left(\mathfrak{R} \sum_{i=1}^{k} B_{i}\right) \\
& \leq \mathfrak{R}\left(\left(\sum_{i=1}^{k} A_{i}\right) \sigma\left(\sum_{i=1}^{k} B_{i}\right)\right) \quad(\text { by }(1.3)) .
\end{aligned}
$$

Thus, we have shown that

$$
\begin{equation*}
\sum_{i=1}^{k} \mathfrak{R} A_{i} \sigma \mathfrak{R} B_{i} \leq \mathfrak{R}\left(\left(\sum_{i=1}^{k} A_{i}\right) \sigma\left(\sum_{i=1}^{k} B_{i}\right)\right) \tag{2.9}
\end{equation*}
$$

We also have

$$
\begin{equation*}
\sum_{i=1}^{k} \mathfrak{R} A_{i} \sigma^{\perp} \mathfrak{R} B_{i} \leq \mathfrak{R}\left(\left(\sum_{i=1}^{k} A_{i}\right) \sigma^{\perp}\left(\sum_{i=1}^{k} B_{i}\right)\right) \tag{2.10}
\end{equation*}
$$

Notice that

$$
\begin{align*}
& \left(\sum_{i=1}^{k} \mathfrak{R} A_{i} \sigma \mathfrak{R} B_{i}\right) \sharp\left(\sum_{i=1}^{k} \mathfrak{R} A_{i} \sigma^{\perp} \mathfrak{R} B_{i}\right) \\
& \leq \mathfrak{R}\left(\left(\sum_{i=1}^{k} A_{i}\right) \sigma\left(\sum_{i=1}^{k} B_{i}\right)\right) \sharp \mathfrak{R}\left(\left(\sum_{i=1}^{k} A_{i}\right) \sigma^{\perp}\left(\sum_{i=1}^{k} B_{i}\right)\right)  \tag{2.11}\\
& \leq \sec ^{2} \alpha\left(\mathfrak{R}\left(\sum_{i=1}^{k} A_{i}\right) \sigma \mathfrak{R}\left(\sum_{i=1}^{k} B_{i}\right)\right) \sharp\left(\mathfrak{R}\left(\sum_{i=1}^{k} A_{i}\right) \sigma^{\perp} \mathfrak{R}\left(\sum_{i=1}^{k} B_{i}\right)\right) \\
& =\sec ^{2} \alpha \mathfrak{R}\left(\sum_{i=1}^{k} A_{i}\right) \sharp \mathfrak{R}\left(\sum_{i=1}^{k} B_{i}\right),
\end{align*}
$$

where we have used (2.9) and (2.10) to obtain the first inequality, (1.3) to obtain the second inequality and (2.7) to obtain the last equality. Further,

$$
\begin{aligned}
\sum_{i=1}^{k} \mathfrak{\Re} A_{i} \sharp \mathfrak{R} B_{i} & =\sum_{i=1}^{k}\left(\mathfrak{R} A_{i} \sigma \mathfrak{R} B_{i}\right) \sharp\left(\mathfrak{\Re} A_{i} \sigma^{\perp} \mathfrak{R} B_{i}\right) \quad \text { (by (2.7)) } \\
& \leq\left(\sum_{i=1}^{k} \Re A_{i} \sigma \mathfrak{R} B_{i}\right) \sharp\left(\sum_{i=1}^{k} \Re A_{i} \sigma^{\perp} \mathfrak{R} B_{i}\right) \quad(\text { by }(2.6)) .
\end{aligned}
$$

Thus, using (2.11),

$$
\begin{aligned}
\sum_{i=1}^{k} \Re A_{i} \sharp \Re B_{i} & \leq\left(\sum_{i=1}^{k} \Re A_{i} \sigma \mathfrak{R} B_{i}\right) \sharp\left(\sum_{i=1}^{k} \mathfrak{R} A_{i} \sigma^{\perp} \mathfrak{R} B_{i}\right) \\
& \leq \sec ^{2} \alpha \mathfrak{R}\left(\sum_{i=1}^{k} A_{i}\right) \sharp \Re\left(\sum_{i=1}^{k} B_{i}\right),
\end{aligned}
$$

which completes the proof.
Another mean-convex inequality can be stated as follows.
Theorem 2.4. Let $A, B, C, D \in \Pi_{n}^{\alpha}$. Then

$$
\mathfrak{R}\left(\lambda\left(A \sharp_{t} C\right)+(1-\lambda)\left(B \sharp_{t} D\right)\right) \leq \sec ^{2} \alpha\left(\mathfrak{R}(\lambda A+(1-\lambda) B) \sharp_{t} \mathfrak{R}(\lambda C+(1-\lambda) D)\right)
$$

for any $0 \leq t, \lambda \leq 1$.
Proof. Noting (1.3) and implementing basic properties of means, we have

$$
\begin{aligned}
\lambda \mathfrak{R}\left(A \sharp_{t} C\right)+(1-\lambda) \Re\left(B \sharp_{t} D\right) & \leq \sec ^{2} \alpha\left(\lambda\left(\Re A \sharp_{t} \Re C\right)+(1-\lambda)\left(\mathfrak{R} B \sharp_{t} \Re D\right)\right) \\
& \leq \sec ^{2} \alpha\left((\lambda \mathfrak{R} A+(1-\lambda) \mathfrak{R} B) \not \sharp_{t}(\lambda \Re C+(1-\lambda) \mathfrak{R} D)\right) \\
& =\sec ^{2} \alpha\left(\mathfrak{R}(\lambda A+(1-\lambda) B) \sharp_{t} \Re(\lambda C+(1-\lambda) D)\right) .
\end{aligned}
$$

This completes the proof.
2.4. A sub-multiplicative result for the real part. We have seen that the real part plays a key role in studying accretive matrices. This is due to the ability to compare Hermitian matrices only. Defining $\Phi: \mathcal{M}_{n} \rightarrow \mathcal{M}_{n}$ by $\Phi(X)=\mathfrak{R} X$, we immediately see that $\Phi$ is a unital positive linear mapping. It is well known that for any such $\Phi$ and any $A, B \in \mathcal{P}_{n}$, one has [20, Theorem 1.19]

$$
\Phi(B) \Phi(A)^{-1} \Phi(B) \leq \Phi\left(B A^{-1} B\right)
$$

Notice that when $\Phi=\mathfrak{R}$, this inequality becomes an identity because of $A, B \in \mathcal{P}_{n}$. Interestingly, this inequality can be extended to the following form: one matrix is positive definite, but the other is arbitrary.

Theorem 2.5. Let $A>0$. Then

$$
\mathfrak{R}\left(Y A^{-1} Y\right) \leq \mathfrak{R} Y A^{-1} \mathfrak{R} Y,
$$

for any $Y \in \mathcal{M}_{n}$.
Proof. We can see that for any $X \in \mathcal{M}_{n}$ and positive definite $A$,

$$
\begin{equation*}
\mathfrak{R} X=A^{-\frac{1}{2}} \mathfrak{R}\left(A^{\frac{1}{2}} X A^{\frac{1}{2}}\right) A^{-\frac{1}{2}} \tag{2.12}
\end{equation*}
$$



$$
\mathfrak{R} A^{-\frac{1}{2}} Y A^{-1} Y A^{-\frac{1}{2}} \leq\left(\Re A^{-\frac{1}{2}} Y A^{-\frac{1}{2}}\right)^{2}
$$

Using (2.12) now, we have

$$
\begin{equation*}
A^{-\frac{1}{2}} \mathfrak{R}\left(Y A^{-1} Y\right) A^{-\frac{1}{2}} \leq A^{-\frac{1}{2}} \mathfrak{R} Y A^{-1} \mathfrak{R} Y A^{-\frac{1}{2}} \tag{2.13}
\end{equation*}
$$

Multiplying both sides of (2.13) by $A^{\frac{1}{2}}$, we reach the desired result.
2.5. On the absolute value of accretive matrices. If $X \in \Pi_{n}^{\alpha}$, and $0 \leq r \leq$ 1 , then

$$
\begin{aligned}
\frac{1}{\sec ^{2} \alpha} \mathfrak{\Re} X^{2 r} & \leq\left(\mathfrak{R} X^{2}\right)^{r} \quad(\text { by Lemma 1.4 }) \\
& \leq(\mathfrak{R X})^{2 r}
\end{aligned}
$$

where the second inequality follows from the facts that $\mathfrak{R} X^{2} \leq(\mathfrak{R} X)^{2}$ for any $X \in$ $\mathcal{M}_{n}$ and that $f(t)=t^{r}$ is operator monotone when $0 \leq r \leq 1$.

Thus, we have shown that if $X \in \Pi_{n}^{\alpha}$, one has

$$
\mathfrak{R} X^{2 r} \leq \sec ^{2} \alpha(\mathfrak{R} X)^{2 r} ; \quad 0 \leq r \leq 1
$$

In [48], it has been shown that

$$
\begin{equation*}
\|T\| \leq \sec \alpha\|\Re T\| \tag{2.14}
\end{equation*}
$$

In this subsection, we present refinements and further related results. More precisely, we show better bounds for $|T|$ rather than $\|T\|$. First, we have the following basic lemmas.

Lemma 2.2. [27, Lemma 1] Let $A, B, C \in \mathcal{M}_{n}$ be such that $A, B \geq 0$. Then

$$
\left[\begin{array}{cc}
A & C \\
C^{*} & B
\end{array}\right] \geq 0 \Leftrightarrow|\langle C x, y\rangle|^{2} \leq\langle A x, x\rangle\langle B y, y\rangle, \forall x, y \in \mathbb{C}^{n} .
$$

Lemma 2.3. [11, Proposition 1.3.2] Let $A, B \geq 0$. Then $\left[\begin{array}{cc}A & X \\ X^{*} & B\end{array}\right] \geq 0$ if and only if $X=A^{\frac{1}{2}} K B^{\frac{1}{2}}$ for some contraction $K$.

Lemma 2.4. [43] Let $T \geq 0$. Then for any vectors $x, y \in \mathbb{C}^{n}$,

$$
|\langle T x, y\rangle| \leq \frac{\|T\|}{2}(|\langle x, y\rangle|+\|y\|\|x\|) .
$$

Now we show the following preliminary result, which we will need.

Proposition 2.2. Let $A \in \mathcal{M}_{n}$ with the polar decomposition $A=U|A|$. Then for any vectors $x, y \in \mathbb{C}^{n}$,

$$
|\langle A x, y\rangle| \leq \frac{\|A\|}{2}\left(\left|\left\langle x, U^{*} y\right\rangle\right|+\left\|U^{*} y\right\|\|x\|\right) .
$$

Proof. Lemma 2.4 gives

$$
\begin{equation*}
|\langle | A| x, y\rangle \left\lvert\, \leq \frac{\||A|\|}{2}(|\langle x, y\rangle|+\|y\|\|x\|)=\frac{\|A\|}{2}(|\langle x, y\rangle|+\|y\|\|x\|)\right. \tag{2.15}
\end{equation*}
$$

for any $A \in \mathbb{M}_{n}$. Assume that $A=U|A|$ be the polar decomposition of $A$. If we replace $y$ by $U^{*} y$, in the inequality (2.15), we get

$$
\begin{aligned}
|\langle A x, y\rangle| & =|\langle U| A| x, y\rangle\left|=|\langle | A| x, U^{*} y\right\rangle \mid \\
& \leq \frac{\|A\|}{2}\left(\left|\left\langle x, U^{*} y\right\rangle\right|+\left\|U^{*} y\right\|\|x\|\right),
\end{aligned}
$$

from which the required result follows.
The next lemma will be the key tool to obtain our result about a possible bound of $T$, where $T \in \Pi_{n}^{\alpha}$.

Lemma 2.5. [21] Let $A, X, B \in \mathcal{M}_{n}$. Then $\left[\begin{array}{cc}A & X \\ X^{*} & B\end{array}\right] \geq 0$, if and only if for any vectors $x, y \in \mathbb{C}^{n}$,

$$
|\langle X x, y\rangle| \leq \frac{1}{2}\left(\left|\left\langle A^{\frac{1}{2}} U B^{\frac{1}{2}} x, y\right\rangle\right|+\sqrt{\langle A y, y\rangle\langle B x, x\rangle}\right)
$$

for some unitary $U$.
Lemma 2.5 can be used to obtain the following bound of the inner product of accretive matrices, which entails a refinement of (2.14).

Corollary 2.1. Let $T \in \Pi_{n}^{\alpha}$, and let $x, y \in \mathbb{C}^{n}$ be arbitrary vectors. Then

$$
|\langle T x, y\rangle| \leq \frac{\sec \alpha}{2}\left(\left|\left\langle(\Re T)^{\frac{1}{2}} U(\Re T)^{\frac{1}{2}} x, y\right\rangle\right|+\sqrt{\langle\mathfrak{R} T y, y\rangle\langle\Re T x, x\rangle}\right)
$$

for some unitary matrix $U \in \mathcal{M}_{n}$. In particular,

$$
\begin{equation*}
\|T\| \leq \frac{\sec \alpha}{2}(r(U \Re T)+\|\Re T\|), \tag{2.16}
\end{equation*}
$$

where $r(\cdot)$ is the spectral radius.
Proof. It has been shown in [2, Theorem 2.2] that if $T \in \Pi_{n}^{\alpha}$, then

$$
\left[\begin{array}{cc}
\sec \alpha \Re T & T  \tag{2.17}\\
T & \sec \alpha \Re T
\end{array}\right] \geq 0 .
$$

Now Lemma 2.5 implies the first desired inequality. For the second inequality, take the supremum over all unit vectors $x, y$ in the first inequality to get

$$
\begin{align*}
\|T\| & \leq \frac{\sec \alpha}{2}\left(\left\|(\mathfrak{R} T)^{\frac{1}{2}} U(\Re T)^{\frac{1}{2}}\right\|+\|\Re T\|\right) \\
& =\frac{\sec \alpha}{2}\left(r\left((\Re T)^{\frac{1}{2}} U(\Re T)^{\frac{1}{2}}\right)+\|\Re T\|\right)  \tag{2.18}\\
& =\frac{\sec \alpha}{2}(r(U \Re T)+\|\Re T\|) .
\end{align*}
$$

This completes the proof.

Remark 2.2. The inequality (2.18) is a refinement of (2.14), since

$$
r(U \Re T) \leq\|U \Re T\|=\|\Re T\| .
$$

Now we show the main result in this subsection.
Theorem 2.6. Let $T \in \Pi_{n}^{\alpha}$. Then

$$
|T| \leq \sec \alpha\left|(\Re T)^{\frac{1}{2}} U(\Re T)^{\frac{1}{2}}\right|
$$

for some unitary $U$. More precisely, $U$ is the unitary matrix in the polar decomposition of $T(\mathfrak{R} T)^{-\frac{1}{2}}$.

Proof. We know that if $\left[\begin{array}{cc}A & X \\ X^{*} & B\end{array}\right] \geq 0$, then [23]

$$
X^{*} X \leq B^{\frac{1}{2}} U^{*} A U B^{\frac{1}{2}}, \text { for some unitary } U
$$

Here we present another proof of this result using a different method. It has been shown in [16, Theorem 7] that $\left[\begin{array}{cc}A & X \\ X^{*} & B\end{array}\right] \geq 0$ if and only if there is an operator $C$ such that $X=C^{*} B^{\frac{1}{2}}$ and $C^{*} C \leq A$. We can write

$$
X^{*} X=|X|^{2}=B^{\frac{1}{2}} C C^{*} B^{\frac{1}{2}}=B^{\frac{1}{2}}\left|C^{*}\right|^{2} B^{\frac{1}{2}} .
$$

Thus,

$$
B^{-\frac{1}{2}}|X|^{2} B^{-\frac{1}{2}}=\left|C^{*}\right|^{2}
$$

Let $C=V|C|$ be the polar decomposition of $C$. We have

$$
V^{*}\left(B^{-\frac{1}{2}}|X|^{2} B^{-\frac{1}{2}}\right) V=V^{*}\left|C^{*}\right|^{2} V=|C|^{2}=C^{*} C
$$

Therefore, by the assumption,

$$
V^{*}\left(B^{-\frac{1}{2}}|X|^{2} B^{-\frac{1}{2}}\right) V \leq A
$$

So,

$$
|X|^{2} \leq B^{\frac{1}{2}}\left(V A V^{*}\right) B^{\frac{1}{2}}=\left(B^{\frac{1}{2}} V A^{\frac{1}{2}}\right)\left(A^{\frac{1}{2}} V^{*} B^{\frac{1}{2}}\right)=\left|A^{\frac{1}{2}} V^{*} B^{\frac{1}{2}}\right|^{2}
$$

The proof is complete by assigning $V^{*}$ to new unitary $U$. Consequently, we showed that

$$
|X|^{2} \leq\left|A^{\frac{1}{2}} U B^{\frac{1}{2}}\right|^{2}
$$

Since the function $f(t)=\sqrt{t}$ is operator monotone, we get

$$
|X| \leq\left|A^{\frac{1}{2}} U B^{\frac{1}{2}}\right|
$$

By (2.17),

$$
\left[\begin{array}{cc}
\sec \alpha \mathfrak{R} T & T \\
T^{*} & \sec \alpha \mathfrak{R} T
\end{array}\right] \geq 0 .
$$

Combining the two inequalities above, we get the desired result.
Remark 2.3. In [1], it is shown that if $T \in \Pi_{n}^{\alpha}$, then

$$
\begin{equation*}
|T| \leq \sec (\alpha)\left(\Re T \sharp\left(V^{*} \Re T V\right)\right), \tag{2.19}
\end{equation*}
$$

where $V$ is the unitary matrix in the polar decomposition $T=V|T|$. Simplifying (2.19) we reach

$$
\begin{equation*}
|T| \leq \sec (\alpha)(\Re T)^{\frac{1}{2}}\left|(\Re T)^{\frac{1}{2}} V(\Re T)^{-\frac{1}{2}}\right|(\Re T)^{\frac{1}{2}} . \tag{2.20}
\end{equation*}
$$

We point out that this bound and the bound we found in Theore 2.6 are incomparable. For this purpose, we give the following example. If we let $T=\left(\begin{array}{ll}2+3 i & 1+2 i \\ 1+2 i & 1+2 i\end{array}\right)$, then numerical calculations show that

$$
X_{1}:=\left|(\Re T)^{\frac{1}{2}} U(\Re T)^{\frac{1}{2}}\right| \approx\left(\begin{array}{cc}
1.91617 & 1.01305+0.0955262 i \\
1.01305-0.0955262 i & 1.06222
\end{array}\right)
$$

where $U \approx\left(\begin{array}{cc}0.643783+0.748255 i & -0.0607125+0.148231 i \\ -0.159823+0.0107223 i & 0.506275+0.847365 i\end{array}\right)$ is the unitary part in the polar decomposition of $T(\Re T)^{-\frac{1}{2}}$ as in Theorem 2.6.

On the other hand, the unitary part in the polar decomposition of $T$ is

$$
V=\left(\begin{array}{cc}
0.61125+0.781936 i & -0.0991922+0.0714937 i \\
-0.0991922+0.0714937 i & 0.548515+0.827152 i
\end{array}\right)
$$

which then implies, according to (2.20),

$$
\begin{aligned}
X_{2}: & =(\Re T)^{\frac{1}{2}}\left|(\Re T)^{\frac{1}{2}} V(\Re T)^{-\frac{1}{2}}\right|(\Re T)^{\frac{1}{2}} \\
& \approx\left(\begin{array}{cc}
1.77883+0.0590931 i & 0.195047+0.0393954 i \\
0.199136-0.0590931 i & 0.812152-0.0393954 i
\end{array}\right) .
\end{aligned}
$$

It can be easily seen that neither $X_{1} \geq X_{2}$ nor $X_{2} \geq X_{1}$. This shows that the bounds in theorem 2.6 and in [1] are incomparable, in general.

Remark 2.4. It follows from Theorem 2.6 that

$$
\begin{aligned}
\|T\| & =\||T|\| \leq \sec \alpha\left\|\left|(\Re T)^{\frac{1}{2}} U(\Re T)^{\frac{1}{2}}\right|\right\| \\
& =\sec \alpha\left\|(\mathfrak{R} T)^{\frac{1}{2}} U(\mathfrak{R} T)^{\frac{1}{2}}\right\|=\sec \alpha r(U \Re T) .
\end{aligned}
$$

Therefore,

$$
\|T\| \leq \sec \alpha r(U \Re T)
$$

which is a significant refinement of (2.16) and (2.14).

## 3. On the difference of two perspectives

It is not hard to check that the function $\ln _{t}(x):=\frac{x^{t}-1}{t}$ defined on $x>0$ with $0<t \leq 1$, is operator monotone. Tsallis relative operator entropy is defined as

$$
T_{t}(A \mid B):=A \sigma_{\ln _{t}} B=A^{1 / 2} \ln _{t}\left(A^{-1 / 2} B A^{-1 / 2}\right) A^{1 / 2}=\frac{A \sharp_{t} B-A}{t} .
$$

In [18], the mathematical properties of $T_{t}(A \mid B)$ as the Tsallis relative operator entropy were studied.

We may define a difference between two perspectives as

$$
D_{f, g}(A \mid B)=A \sigma_{f} B-A \sigma_{g} B,
$$

for $f, g \in \mathfrak{m}$. Here we mention some examples.
(i) If we take $f(x):=(1-t)+t x$ and $g(x)=x^{t}$ for $t \in[0,1]$, then $D_{f, g}(A \mid B)=$ $A \nabla_{t} B-A \not \sharp_{t} B$, where $\nabla_{t}$ and $\sharp_{t}$ are the means associated with $f$ and $g$ respectively.
(ii) If we take $f(x):=\frac{x^{t}-1}{t}+1, g(x):=1$, then we get $D_{f, g}(A \mid B)=T_{t}(A \mid B)$ the Tsallis relative operator entropy. In addition, if we take $f(x):=\log x+1$, $g(x):=1$, then we get $D_{f, g}(A \mid B)=S(A \mid B)$ the relative operator entropy.
(iii) If we take $f(x):=\frac{x^{t}-1}{t}+1, g(x):=\log x+1$, then $D_{f, g}(A \mid B)=T_{t}(A \mid B)-$ $S(A \mid B)$, which gives the difference between the Tsallis relative operator entropy and the relative operator entropy. And it is known that $S(A \mid B) \leq$ $T_{t}(A \mid B)$ for $0<t \leq 1$.
In this section, we study $D_{f, g}(A \mid B)$ for accretive matrices $A, B$; as a new track in this research field.

Theorem 3.1. Let $A, B \in \Pi_{n}^{\alpha}$ and $f, g \in \mathfrak{m}$. Then for any invertible $C \in \mathcal{M}_{n}$,

$$
C^{*} D_{f, g}(A \mid B) C=D_{f, g}\left(C^{*} A C \mid C^{*} B C\right) .
$$

Proof. We have

$$
\begin{aligned}
C^{*} D_{f, g}(A \mid B) C & =C^{*}\left(A \sigma_{f} B-A \sigma_{g} B\right) C \\
& =C^{*}\left(A \sigma_{f} B\right) C-C^{*}\left(A \sigma_{g} B\right) C \\
& =C^{*}\left(A \sigma_{f} B\right) C-C^{*}\left(A \sigma_{g} B\right) C \\
& =C^{*} A C \sigma_{f} C^{*} B C-C^{*} A C \sigma_{g} C^{*} B C \\
& =D_{f, g}\left(C^{*} A C \mid C^{*} B C\right)
\end{aligned}
$$

With the inclusion of real parts of sectorial matrices, one may obtain further bounds as follows.

Theorem 3.2. Let $A, B \in \Pi_{n}^{\alpha}$ and $f, g \in \mathfrak{m}$. Then

$$
\begin{aligned}
D_{f, g}(\Re A \mid \Re B)+\left(1-\sec ^{2} \alpha\right)\left(\Re A \sigma_{g} \mathfrak{R} B\right) & \leq \mathfrak{\Re}\left(D_{f, g}(A \mid B)\right) \\
& \leq D_{f, g}(\Re A \mid \Re B)+\left(\sec ^{2} \alpha-1\right)\left(\Re A \sigma_{f} \mathfrak{R} B\right)
\end{aligned}
$$

Proof. We have

$$
\begin{aligned}
\mathfrak{R}\left(D_{f, g}(A \mid B)\right) & =\mathfrak{R}\left(A \sigma_{f} B-A \sigma_{g} B\right) \\
& =\mathfrak{R}\left(A \sigma_{f} B\right)-\mathfrak{R}\left(A \sigma_{g} B\right) \\
& \geq \mathfrak{R} A \sigma_{f} \mathfrak{R} B-\sec ^{2} \alpha\left(\mathfrak{R} A \sigma_{g} \mathfrak{R} B\right) \\
& =\mathfrak{R A \sigma _ { f } \mathfrak { R } B - \mathfrak { R } A \sigma _ { g } \mathfrak { R } B + ( 1 - \operatorname { s e c } ^ { 2 } \alpha ) ( \mathfrak { R } A \sigma _ { g } \mathfrak { R } B )} \\
& =D_{f, g}(\mathfrak{R} A \mid \mathfrak{R} B)+\left(1-\sec ^{2} \alpha\right)\left(\Re A \sigma_{g} \mathfrak{R} B\right),
\end{aligned}
$$

where we have used (1.3) to obtain the first inequality in these computations. Noting (1.3), we also have

$$
\begin{aligned}
\mathfrak{R}\left(D_{f, g}(A \mid B)\right) & =\mathfrak{R}\left(A \sigma_{f} B-A \sigma_{g} B\right) \\
& =\mathfrak{R}\left(A \sigma_{f} B\right)-\mathfrak{R}\left(A \sigma_{g} B\right) \\
& \leq \sec ^{2} \alpha\left(\Re A \sigma_{f} \mathfrak{R} B\right)-\left(\Re A \sigma_{g} \mathfrak{R} B\right) \\
& =\mathfrak{R A \sigma _ { f } \Re B - \Re A \sigma _ { g } \Re B + ( \operatorname { s e c } ^ { 2 } \alpha - 1 ) ( \Re A \sigma _ { f } \mathfrak { R } B )} \\
& =D_{f, g}(\Re A \mid \Re B)+\left(\sec ^{2} \alpha-1\right)\left(\Re A \sigma_{f} \mathfrak{R} B\right),
\end{aligned}
$$

which completes the proof.
We give an example for Theorem 3.2. If we take $f(x):=\frac{x^{t}-1}{t}+1,(0<t \leq 1)$ and $g(x):=1$ in Theorem 3.2, then we have

$$
D_{t}(\Re A \mid \Re B)+\left(1-\sec ^{2} \alpha\right) \Re A \leq \Re\left(D_{t}(A \mid B)\right) \leq \sec ^{2} \alpha D_{t}(\Re A \mid \Re B)+\left(\sec ^{2} \alpha-1\right) \Re A .
$$

Since it is known the relation $D_{t}(\Re A \mid \Re B) \leq \Re\left(D_{t}(A \mid B)\right)$ for accretive matrices $A, B$ and $0<t<1$ in [40], the lower bound of $\mathfrak{R}\left(D_{t}(A \mid B)\right)$ in the inequalities above does not give a refined bound. However, we obtain the upper bound of $\mathfrak{\Re}\left(D_{t}(A \mid B)\right)$.

Finally, we have the following double inequality, which bounds $D_{f, g}(A \mid B)$ between certain differences between the harmonic mean $!_{t}$ and the arithmetic mean $\nabla_{t}$.

Theorem 3.3. Let $A, B \in \Pi_{n}^{\alpha}$ and $f, g \in \mathfrak{m}$ be such that $f^{\prime}(1)=g^{\prime}(1)=t$. Then

$$
\begin{aligned}
\cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right)-\sec ^{2} \alpha \mathfrak{R}\left(A \nabla_{t} B\right) & \leq \mathfrak{R}\left(D_{f, g}(A \mid B)\right) \\
& \leq \sec ^{2} \alpha \mathfrak{R}\left(A \nabla_{t} B\right)-\cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right) .
\end{aligned}
$$

Proof. Noting Lemma 1.7, we have

$$
\begin{aligned}
\mathfrak{R}\left(D_{f, g}(A \mid B)\right) & =\mathfrak{R}\left(A \sigma_{f} B\right)-\mathfrak{R}\left(A \sigma_{g} B\right) \\
& \leq \sec ^{2} \alpha \mathfrak{R}\left(A \nabla_{t} B\right)-\cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right),
\end{aligned}
$$

and

$$
\begin{aligned}
\mathfrak{R}\left(D_{f, g}(A \mid B)\right) & =\mathfrak{R}\left(A \sigma_{f} B\right)-R\left(A \sigma_{g} B\right) \\
& \geq \cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right)-\sec ^{2} \alpha \mathfrak{R}\left(A \nabla_{t} B\right) .
\end{aligned}
$$

This completes the proof.
Taking $f(x):=(1-t)+t x$ and $g(x):=\left\{(1-t)+t x^{-1}\right\}^{-1}$ in Theorem 3.3, then we obtain $\cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right) \leq \mathfrak{R}\left(A \nabla_{t} B\right)$ which is a special case of the inequality in Lemma 1.7. If we take $f(x):=\left\{(1-t)+t x^{-1}\right\}^{-1}$ and $g(x):=(1-t)+t x$ in Theorem 3.3 , then we obtain the same inequality. If we take $f(x):=(1-t)+t x$ and $g(x):=x^{t}$ in Theorem 3.3, then we obtain

$$
\begin{aligned}
\left(1-\sec ^{2} \alpha\right) \mathfrak{R}\left(A \nabla_{t} B\right)+\cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right) & \leq \mathfrak{R}\left(A \sharp_{t} B\right) \\
& \leq\left(1+\sec ^{2} \alpha\right) \mathfrak{R}\left(A \nabla_{t} B\right)-\cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right) .
\end{aligned}
$$

If we take $f(x):=x^{t}$ and $g(x):=\left\{(1-t)+t x^{-1}\right\}^{-1}$ in Theorem 3.3, then we obtain

$$
\begin{aligned}
\left(1+\sec ^{2} \alpha\right) \mathfrak{R}\left(A!_{t} B\right)-\sec ^{2} \alpha \mathfrak{R}\left(A \nabla_{t} B\right) & \leq \mathfrak{R}\left(A \sharp_{t} B\right) \\
& \leq \sec ^{2} \alpha \mathfrak{R}\left(A \nabla_{t} B\right)+\left(1-\cos ^{2} \alpha\right) \mathfrak{R}\left(A!_{t} B\right) .
\end{aligned}
$$

However, we find from the inequality $\cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right) \leq \mathfrak{R}\left(A \nabla_{t} B\right)$ that both inequalities above do not improve the known inequality [46]:

$$
\cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right) \leq \mathfrak{R}\left(A \sharp_{t} B\right) \leq \sec ^{2} \alpha \mathfrak{R}\left(A \nabla_{t} B\right) .
$$

Finally, we give bounds of the weighted logarithmic mean for sectorial matrices $A, B$ using Theorem 3.3. To this end, we review the representing function of the weighted logarithmic mean [38] given by

$$
\ell_{t}(x):=\frac{1-t}{t} \frac{x^{t}-1}{\log x}+\frac{t}{1-t} \frac{x-x^{t}}{\log x}, \quad(x>0,0<t<1) .
$$

For $A, B>0$ and $0<t<1$, the operator version of the weighted logarithmic mean can be defined as

$$
A \ell_{t} B:=\frac{1-t}{t} \int_{0}^{t} A \sharp_{p} B d p+\frac{t}{1-t} \int_{t}^{1} A \sharp_{p} B d p .
$$

Then we have the following corollary.
Corollary 3.1. Let $A, B \in \Pi_{n}^{\alpha}$. Then

$$
\begin{aligned}
\cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right)+\mathfrak{R}\left(A \sharp_{t} B\right)-\sec ^{2} \alpha & \Re\left(A \nabla_{t} B\right) \leq \mathfrak{R}\left(A \ell_{t} B\right) \\
& \leq \sec ^{2} \alpha \mathfrak{R}\left(A \nabla_{t} B\right)+\mathfrak{R}\left(A \sharp_{t} B\right)-\cos ^{2} \alpha \mathfrak{R}\left(A!_{t} B\right) .
\end{aligned}
$$

Proof. We show $\left.\frac{d e_{t}(x)}{d x}\right|_{x \rightarrow 1}=t$. By elementary calculations, we have

$$
\frac{d}{d x}\left(\frac{x^{t}-1}{\log x}\right)=\frac{1-x^{t}+x^{t} \log x^{t}}{x(\log x)^{2}}, \quad \frac{d}{d x}\left(\frac{x-x^{t}}{\log x}\right)=\frac{x^{t}-x+x \log x-x^{t} \log x^{t}}{x(\log x)^{2}} .
$$

Applying L'Hopital's rule, we have
$\lim _{x \rightarrow 1} \frac{1-x^{t}+x^{t} \log x^{t}}{x(\log x)^{2}}=\lim _{x \rightarrow 1} \frac{t x^{t-1} \log x^{t}}{2 \log x+(\log x)^{2}}=\lim _{x \rightarrow 1} \frac{t^{2} x^{t-1}-t(1-t) x^{t-1} \log x^{t}}{2+2 \log x}=\frac{t^{2}}{2}$.
Since we have similarly

$$
\lim _{x \rightarrow 1} \frac{x^{t}-x+x \log x-x^{t} \log x^{t}}{x(\log x)^{2}}=\frac{1-t^{2}}{2}
$$

we have

$$
\left.\frac{\ell_{t}(x)}{d x}\right|_{x \rightarrow 1}=\frac{1-t}{t} \times \frac{t^{2}}{2}+\frac{t}{1-t} \times \frac{1-t^{2}}{2}=t
$$

We also show $\ell_{t}(x) \in \mathfrak{m}$. It is trivial $\lim _{x \rightarrow 1} \ell_{t}(x)=1$. We take a spectral decomposition of the bounded linear operator $A \geq 0$ as $A=\int_{0}^{\infty} \lambda d E_{\lambda}$. For a continuous function $f:(0, \infty) \rightarrow(0, \infty)$, we have $f(A)=\int_{0}^{\infty} f(\lambda) d E_{\lambda}$ by a standard functional calculus. From Fubini's theorem with $f_{1}(x):=\frac{x^{t}-1}{\log x}=\int_{0}^{t} x^{p} d p$, we have for any vector $u \in \mathcal{H}$

$$
\begin{aligned}
\left\langle f_{1}(A) u, u\right\rangle & =\left\langle\int_{0}^{\infty} f_{1}(\lambda) d E_{\lambda} u, u\right\rangle=\left\langle\int_{0}^{\infty} \int_{0}^{t} \lambda^{p} d p d E_{\lambda} u, u\right\rangle \\
& =\left\langle\int_{0}^{t} \int_{0}^{\infty} \lambda^{p} d E_{\lambda} d p u, u\right\rangle=\int_{0}^{t}\left\langle A^{p} u, u\right\rangle d p
\end{aligned}
$$

From $0<t<1$, we have $0<p<1$. Then we have $0 \leq A \leq B \Longrightarrow f_{1}(A) \leq f_{1}(B)$. Similarly we have $0 \leq A \leq B \Longrightarrow f_{2}(A) \leq f_{2}(B)$ for the function $f_{2}(x):=\frac{x-x^{t}}{\log x}=$ $\int_{t}^{1} x^{p} d p$. Therefore $f(x)=\frac{1-t}{t} f_{1}(x)+\frac{t}{1-t} f_{2}(x) \in \mathfrak{m}$ for $0<t<1$. Thus we can apply Theorem 3.3 with $f(x):=\ell_{t}(x)$ and $g(x):=x^{t}$ and then we obtain the desired inequalities.

To our knowledge, the bounds for the weighted logarithmic mean for the positive matrices case and/or scalar case have not been known yet; see [17, 19] for example.

As we have seen, Theorem 3.2 and Theorem 3.3 give some interesting bounds using appropriate functions easily, although their estimations are not so sharp. We gave there the general forms for general functions.

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