

Derivations and Sobolev functions on extended metric-measure spaces

Enrico Pasqualetto and Janne Taipalus

Abstract. We investigate the first-order differential calculus over extended metric-topological measure spaces. The latter are quartets $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$, given by an extended metric space (X, \mathbf{d}) together with a weaker topology τ (satisfying suitable compatibility conditions) and a finite Radon measure \mathbf{m} on (X, τ) . The class of extended metric-topological measure spaces encompasses all metric-measure spaces and many infinite-dimensional metric-measure structures, such as abstract Wiener spaces. In this framework, we study the following classes of objects:

- The Banach algebra $\text{Lip}_b(X, \tau, \mathbf{d})$ of bounded τ -continuous \mathbf{d} -Lipschitz functions on X .
- Several notions of Lipschitz derivations on X , defined in duality with $\text{Lip}_b(X, \tau, \mathbf{d})$.
- The metric Sobolev space $W^{1,p}(\mathbb{X})$, defined in duality with Lipschitz derivations on X .

Inter alia, we generalise both Weaver's and Di Marino's theories of Lipschitz derivations to the extended setting, and we discuss their connections. We also introduce a Sobolev space $W^{1,p}(\mathbb{X})$ via an integration-by-parts formula, along the lines of Di Marino's notion of Sobolev space, and we prove its equivalence with other approaches, studied in the extended setting by Ambrosio, Erbar and Savaré. En route, we obtain some results of independent interest, among which are:

- A Lipschitz-constant-preserving extension result for τ -continuous \mathbf{d} -Lipschitz functions.
- A novel and rather robust strategy for proving the equivalence of Sobolev-type spaces defined via an integration-by-parts formula and those obtained with a relaxation procedure.
- A new description of an isometric predual of the metric Sobolev space $W^{1,p}(\mathbb{X})$.

Derivaatiot ja Sobolev-funktiot laajennetuissa metrisissä mitta-avaruuksissa

Tiivistelmä. Tutkimme ensimmäisen kertaluokan differentiaalilaskentaa laajennetuissa metritopologisissa mitta-avaruuksissa. Jälkimmäiset ovat nelikkoja $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$, jotka muodostuvat laajennetusta metrisestä avaruudesta (X, \mathbf{d}) , jossa on mukana heikompi topologia τ (joka toteuttaa sopivat yhteensopivuusehdot) ja avaruuden (X, τ) äärellinen Radon-mitta \mathbf{m} . Laajennettujen metritopologisten mitta-avaruuksien luokka käsittää kaikki metriset mitta-avaruudet ja monet ääretönulotteiset metriset mitta-rakenteet, kuten abstraktit Wiener-avaruudet. Tässä viitekehityksessä tutkimme seuraavien objektien luokkia:

- Avaruuden X rajoitettujen τ -jatkuvien \mathbf{d} -Lipschitz-funktioiden Banach-algebra $\text{Lip}_b(X, \tau, \mathbf{d})$.
- Avaruuden X lukuisat Lipschitz-derivaatioiden käsitteet, jotka on määritelty duaalisesti avaruuden $\text{Lip}_b(X, \tau, \mathbf{d})$ kanssa.
- Metrinen Sobolev-avaruus $W^{1,p}(\mathbb{X})$, joka on määritelty avaruuden X Lipschitz-derivaatioiden kanssa duaalisesti.

Muun muassa yleistämme Weaverin ja Di Marinon Lipschitz-derivaatioiden teorian laajennettuun ympäristöön ja käsittelemme niiden yhteyksiä. Esittelemme myös osittaisintegroinnin kaavan avulla Sobolev-avaruuden $W^{1,p}(\mathbb{X})$ Di Marinon Sobolev-avaruuden käsitettä mukaillen ja todistamme yhtäpitävyyden muiden lähestymistapojen kanssa, joita Ambrosio, Erbar ja Savaré tutkivat laajennetuissa ympäristöissä. Tämän ohella saamme joitain riippumattomasti kiinnostavia tuloksia, muun muassa:

- Lipschitz-vakion-säilyttävä jatke τ -jatkuville \mathbf{d} -Lipschitz-funktioille.
- Uusi ja melko vahva strategia osittaisintegroinnin kaavan avulla ja relaksaatiomenetelmän avulla määriteltyjen Sobolev-tyyppisten avaruuksien yhtäpitävyyden todistamiseksi.
- Uusi tapa kuvailla metrisen Sobolev-avaruuden $W^{1,p}(\mathbb{X})$ isometristä esiduaalia.

1. Introduction

1.1. General overview. In the last three decades, the analysis in nonsmooth spaces has undergone impressive developments. After the first nonlocal notion of *metric Sobolev space* over a metric-measure space $(X, \mathbf{d}, \mathbf{m})$ had been introduced by Hajlasz in [30], several (essentially equivalent) local notions were studied in the literature:

- A) The space $H^{1,p}(X)$ obtained by approximation, via a *relaxation* procedure. This approach was pioneered by Cheeger [16] and later revisited by Ambrosio, Gigli and Savaré [5, 6].
- B) The space $W^{1,p}(X)$ proposed by Di Marino in [17, 18], based on an integration-by-parts formula involving a suitable class of *Lipschitz derivations* with divergence.
- C) The *Newtonian space* $N^{1,p}(X)$ introduced by Shanmugalingam [47], based on the concept of *upper gradient* by Heinonen and Koskela [33], and on the metric version of Fuglede’s notion of *p-modulus* [21].
- D) The ‘Beppo Levi space’ $B^{1,p}(X)$, where the exceptional curve families for the validity of the upper gradient inequality are selected via *test plans* of curves. The first definition of this type is due to Ambrosio, Gigli and Savaré [5, 6]. The variant of plan of curves we consider in this paper, involving the concept of *barycenter*, was introduced by Ambrosio, Di Marino and Savaré in [3].

We point out that our choices of notation for the various metric Sobolev spaces may depart from the original ones, but they are consistent with the presentation in [7]. Other definitions of metric Sobolev spaces were introduced and studied in the literature, but we do not mention them here as they are not needed for the purposes of this paper. Remarkably, all the above four theories—the two ‘Eulerian approaches’ A), B) and the two ‘Lagrangian approaches’ C), D)—were proven to be fully equivalent on arbitrary *complete* metric-measure spaces [5, 16, 47]. Other related equivalence results were then achieved in [3, 7, 20, 37].

Nevertheless, there are many infinite-dimensional metric-measure structures of interest—where a refined differential calculus is available or feasible—that are not covered by the theory of metric-measure spaces. Due to this reason, Ambrosio, Erbar and Savaré introduced in [4] the language of *extended metric-topological measure spaces*, which we abbreviate to *e.m.t.m. spaces*. The class of e.m.t.m. spaces includes, besides ‘standard’ metric-measure spaces, *abstract Wiener spaces* [12] and *configuration spaces* [1], among others. The main goal of [4] was to understand the connection between gradient contractivity, transport distances and lower Ricci bounds, as well as the interplay between metric and differentiable structures, in the setting of e.m.t.m. spaces. One of the numerous contributions of [4] is the introduction of the notion of Sobolev space $H^{1,p}(X)$ on e.m.t.m. spaces, later investigated further by Savaré in the lecture notes [42]. Therein, the e.m.t.m. versions of the Sobolev spaces $N^{1,p}(X)$ and $B^{1,p}(X)$ were introduced and studied in detail, ultimately obtaining the identification $H^{1,p}(X) = N^{1,p}(X) = B^{1,p}(X)$ on all complete e.m.t.m. spaces. The duality properties of these metric Sobolev spaces were then investigated by Ambrosio and Savaré in [9].

The primary objectives of this paper are to introduce the Sobolev space $W^{1,p}(X)$ via integration-by-parts for e.m.t.m. spaces, to show its equivalence with the other approaches and to explore the benefits it brings to the theory of metric Sobolev spaces. To achieve these goals, we first develop the machinery of Lipschitz derivations

for e.m.t.m. spaces, which in turn requires an in-depth understanding of the algebra of real-valued bounded τ -continuous \mathbf{d} -Lipschitz functions on X .

Before delving into a more detailed description of the contents of this paper, let us expound the advantages of working in the extended setting. Besides its intrinsic interest, the study of e.m.t.m. spaces has significant implications at the level of metric-measure spaces. On e.m.t.m. spaces the roles of the topology and of the distance are ‘decoupled’, and it turned out that for this reason the category of e.m.t.m. spaces is closed under several useful operations under which the category of metric-measure spaces is not closed. Key examples are the *compactification* [42, Section 2.1.7] and the passage to the *length-conformal distance* [42, Section 2.3.2]. Therefore, once an effective calculus on e.m.t.m. spaces is developed, it is possible to reduce some problems on metric-measure spaces to problems on τ -compact length e.m.t.m. spaces (as done, for example, in [42, Section 5.2]). We believe that the full potential of this technique has not been fully explored yet. However, dealing with arbitrary e.m.t.m. spaces poses new challenges, which require new ideas and solutions. In the remaining sections of the Introduction, we shall comment on some of them.

1.2. The algebra of τ -continuous \mathbf{d} -Lipschitz functions. Let (X, τ, \mathbf{d}) be an extended metric-topological space (see Definition 2.8). We consider the algebra of bounded τ -continuous \mathbf{d} -Lipschitz functions on X , denoted by $\text{Lip}_b(X, \tau, \mathbf{d})$. The latter is a Banach algebra with respect to the norm

$$\|f\|_{\text{Lip}_b(X, \tau, \mathbf{d})} := \|f\|_{C_b(X, \tau)} + \text{Lip}(f, \mathbf{d}).$$

While the Banach algebra $\text{Lip}_b(Y, \mathbf{d}_Y)$ on a metric space (Y, \mathbf{d}_Y) is (isometrically isomorphic to) the dual of a Banach space, i.e. of the *Arens–Eells space* $\mathcal{A}(Y)$ of Y [50], the space $\text{Lip}_b(X, \tau, \mathbf{d})$ may not have a predual (as we show in Proposition 2.16), thus it is not endowed with a weak* topology. This fact is relevant when discussing the continuity of derivations, see Section 1.3.

Another issue we need to address in the paper is whether it is possible to extend τ -continuous \mathbf{d} -Lipschitz functions preserving the Lipschitz constant. These kinds of extension results are very important e.g. in some localisation arguments (such as in Proposition 4.15). On metric spaces the McShane–Whitney extension theorem serves the purpose, but on e.m.t. spaces the problem becomes much more delicate, because one has to preserve both τ -continuity and \mathbf{d} -Lipschitzianity when extending a function. In Section 3 we deal with this matter. Leveraging strong extension techniques by Matoušková [39], we obtain the sought-after Lipschitz-constant-preserving extension result for bounded τ -continuous \mathbf{d} -Lipschitz functions (Theorem 3.1), which is sharp (Remark 3.2).

1.3. Metric derivations. In Section 4, we analyse various spaces of derivations on e.m.t.m. spaces. In Definition 4.1 we introduce a rather general (and purely algebraic) notion of derivation, which comprises the different variants we will consider. By a *Lipschitz derivation* on an e.m.t.m. space $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ we mean a linear map $b: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow L^0(\mathbf{m})$ satisfying the *Leibniz rule*:

$$b(fg) = f b(g) + g b(f) \quad \text{for every } f, g \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

Here, $L^0(\mathbf{m})$ denotes the algebra of all real-valued τ -Borel functions on X , up to \mathbf{m} -a.e. equality. Distinguished subclasses of derivations are those having *divergence* (Definition 4.2), that are *local* (Definition 4.3), or that satisfy ‘*weak*-type*’ (*sequential*) *continuity* properties (Definition 4.4). In addition to these, we develop the basic theory of two crucial subfamilies of Lipschitz derivations:

- **WEAVER DERIVATIONS.** In Definition 4.9 we propose a generalisation of Weaver’s concept of ‘bounded measurable vector field’ [50, Definition 10.30 a)] to the extended setting. Consistently e.g. with [44], we adopt the term *Weaver derivation*. An important technical point here is that we ask for the weak*-type *sequential* continuity, not for the weak*-type continuity. The reason is that weakly*-type continuous derivations are trivial on the ‘purely non-d-separable component’ $X \setminus S_{\mathbb{X}}$ of X (as in Lemma 2.9), see Proposition 4.7.
- **DI MARINO DERIVATIONS.** In Definition 4.12 we introduce the natural generalisation of Di Marino’s notion of derivation [18, 17] to e.m.t.m. spaces. More specifically, we consider the space $\text{Der}^q(\mathbb{X})$ of q -integrable derivations, and its subspace $\text{Der}_q^q(\mathbb{X})$ consisting of all those q -integrable derivations having q -integrable divergence, for some given exponent $q \in (1, \infty)$. This axiomatisation is tailored to the notion of metric Sobolev space $W^{1,p}(\mathbb{X})$ (where $p \in (1, \infty)$ is the conjugate exponent of q) that one aims at defining by means of an integration-by-parts formula where $\text{Der}_q^q(\mathbb{X})$ is used as the family of ‘test vector fields’.

Since in this paper we are primarily interested in the Sobolev calculus, we shall focus our attention mostly on Di Marino derivations. Nevertheless, we set up also the basic theory of Weaver derivations and we debate their relation with the Di Marino ones (see Proposition 4.15 or Theorem 4.16, where we borrow some ideas from [7]). We believe that Weaver derivations may find interesting applications even in the analysis on e.m.t.m. spaces, for instance for studying suitable generalisations of metric currents or Alberti representations (cf. with [43, 44, 45]), but addressing these kinds of issues is outside the scope of the present paper.

1.4. Metric Sobolev spaces. In Section 5, we introduce the metric Sobolev space $W^{1,p}(\mathbb{X})$, and we compare it with $H^{1,p}(\mathbb{X})$, $B^{1,p}(\mathbb{X})$ and $N^{1,p}(\mathbb{X})$. Mimicking [18, Definition 1.5], we declare that some $f \in L^p(\mathfrak{m})$ belongs to $W^{1,p}(\mathbb{X})$ if there is a linear operator $L_f: \text{Der}_q^q(\mathbb{X}) \rightarrow L^1(\mathfrak{m})$ satisfying some algebraic and topological conditions, as well as the following integration-by-parts formula:

$$\int L_f(b) \, d\mathfrak{m} = - \int f \, \text{div}(b) \, d\mathfrak{m} \quad \text{for every } b \in \text{Der}_q^q(\mathbb{X});$$

see Definition 5.1. Each $f \in W^{1,p}(\mathbb{X})$ is associated with a distinguished function $|Df| \in L^p(\mathfrak{m})^+$, which has the role of the ‘modulus of the weak differential of f ’.

In Section 5.2, we show that on *any* e.m.t.m. space it holds that

$$H^{1,p}(\mathbb{X}) = W^{1,p}(\mathbb{X}), \quad \text{with } |Df| = |Df|_H \quad \text{for every } f \in W^{1,p}(\mathbb{X});$$

see Theorem 5.4. The proof strategy for the inclusion $H^{1,p}(\mathbb{X}) \subseteq W^{1,p}(\mathbb{X})$ is taken from [18] up to some technical discrepancies, whereas the verification of the converse inclusion relies on a new argument, which was partially inspired by [37]. In a nutshell, we first observe that $H^{1,p}(\mathbb{X})$ induces a *differential* $d: L^p(\mathfrak{m}) \rightarrow L^p(T^*\mathbb{X})$, where $L^p(T^*\mathbb{X})$ is the e.m.t.m. version of Gigli’s notion of *cotangent module* from [23] (Theorem 2.25) and d is an unbounded operator with domain $D(d) = H^{1,p}(\mathbb{X})$, then we prove that $W^{1,p}(\mathbb{X}) \subseteq H^{1,p}(\mathbb{X})$ via a convex duality argument involving the adjoint d^* of d . The latter proof strategy is rather robust and suitable for being adapted to obtain analogous equivalence results for other functional spaces. We also point out that the identification $H^{1,p}(\mathbb{X}) = W^{1,p}(\mathbb{X})$ for possibly non-complete spaces is new and interesting even in the particular case where (X, d) is a metric space and

τ is the topology induced by \mathbf{d} , and it covers e.g. those situations in which X is an open domain in a larger (typically complete) ambient space.

By combining Theorem 5.4 with [42], we obtain that on *complete* e.m.t.m. spaces it holds that

$$W^{1,p}(\mathbb{X}) = B^{1,p}(\mathbb{X}), \quad \text{with } |Df| = |Df|_B \quad \text{for every } f \in W^{1,p}(\mathbb{X});$$

see Corollary 5.6. If in addition (X, τ) is Souslin, then the space $W^{1,p}(\mathbb{X})$ can be identified also with the Newtonian space $N^{1,p}(\mathbb{X})$; see Remark 5.7. Yet, these identities are not always in force without the completeness assumption, cf. with the last paragraph of Section 2.5. However, we show that—on arbitrary e.m.t.m. spaces—each \mathcal{T}_q -test plan π (as in Definition 2.30) induces a derivation $b_\pi \in \text{Der}_q^q(\mathbb{X})$ (see Proposition 5.8), and as a consequence we obtain that the inclusion $W^{1,p}(\mathbb{X}) \subseteq B^{1,p}(\mathbb{X})$ holds and that $|Df|_B \leq |Df|$ for all $f \in W^{1,p}(\mathbb{X})$ (Theorem 5.9).

Finally, in Section 5.4 we present a quite elementary construction of some *isometric predual* of the metric Sobolev space $W^{1,p}(\mathbb{X})$, see Theorem 5.10. The formulation of the Sobolev space in terms of derivations is particularly appropriate for this kind of construction. The existence of an isometric predual of $H^{1,p}(\mathbb{X})$ was already known from [9].

Acknowledgements. The first named author was supported by the Research Council of Finland grant 362898. The second named author was supported by the Research Council of Finland grant 354241 and the Emil Aaltonen Foundation through the research group “Quasiworld network”. We thank Sylvester Eriksson-Bique and Timo Schultz for the several helpful discussions. We also thank the anonymous reviewer for their useful comments, which have led to a significant improvement of the presentation.

List of symbols. Below, we provide a list of non-standard symbols that we use in the paper.

$\text{Osc}_S(f)$	oscillation of f on S ; (2.1)
$\text{Lip}(f, A, \mathbf{d})$	Lipschitz constant of f on A with respect to \mathbf{d} ; (2.2)
$\text{Lip}_b(X, \tau, \mathbf{d})$	space of bounded τ -continuous \mathbf{d} -Lipschitz functions $f: X \rightarrow \mathbb{R}$; (2.3)
$\text{Lip}_{b,1}(X, \tau, \mathbf{d})$	space of all functions $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ that are 1-Lipschitz; (2.4)
$\text{lip}_{\mathbf{d}}(f)$	asymptotic slope of f ; Definition 2.2
$\text{INT}_{\mathcal{M}}: \mathcal{M}^* \rightarrow \mathcal{M}'$	isometric isomorphism between the two notions of dual of \mathcal{M} ; (2.6)
$\mathbb{X}_{\perp} E$	restriction of an e.m.t.m. space \mathbb{X} to the Borel set E ; (2.9)
$S_{\mathbb{X}}$	maximal \mathbf{d} -separable component of an e.m.t.m. space \mathbb{X} ; Lemma 2.9
$(\hat{X}, \hat{\tau}, \hat{\mathbf{d}}, \hat{\mathbf{m}})$	Gelfand compactification of an e.m.t.m. space $(X, \tau, \mathbf{d}, \mathbf{m})$; Theorem 2.12
Γ	Gelfand transform; (2.12)
$\mathbf{d}_{\text{discr}}$	discrete distance; (2.16)
$\text{RA}(X, \mathbf{d})$	space of rectifiable arcs in (X, \mathbf{d}) ; (2.18)

\hat{e}	arc-length evaluation map; (2.20)
$\mathcal{U}_{\tau, \mathbf{d}}$	canonical uniformity of an e.m.t. space (X, τ, \mathbf{d}) ; Definition 2.21
\mathcal{E}_p	Cheeger p -energy functional; Definition 2.23
$H^{1,p}(\mathbb{X})$	Sobolev space via relaxation; Definition 2.23
$ Df _H$	minimal p -relaxed slope of $f \in H^{1,p}(\mathbb{X})$; Section 2.4
$L^p(T^*\mathbb{X})$	p -cotangent module; Theorem 2.25
$L^q(T\mathbb{X})$	q -tangent module; Definition 2.26
$L^q_{\text{Sob}}(T\mathbb{X})$	space of Sobolev derivations of exponent q ; Definition 2.28
h_{π}	q -barycenter of a dynamic plan π ; (2.27)
$\mathcal{T}_q(\mathbb{X})$	space of all \mathcal{T}_q -test plans on an e.m.t.m. space \mathbb{X} ; Definition 2.30
$B^{1,p}(\mathbb{X})$	Sobolev space via \mathcal{T}_q -test plans; Definition 2.33
$ Df _B$	minimal \mathcal{T}_q -weak upper gradient of $f \in B^{1,p}(\mathbb{X})$; Section 2.5
$\text{Der}(\mathbb{X})$	space of (Lipschitz) derivations on an e.m.t.m. space \mathbb{X} ; Definition 4.1
$D(\text{div}; \mathbb{X})$	space of all $b \in \text{Der}(\mathbb{X})$ having divergence $\text{div}(b) \in L^1(\mathfrak{m})$; Definition 4.2
$\mathcal{X}(\mathbb{X})$	space of Weaver derivations on \mathbb{X} ; Definition 4.9
$\text{Der}^0(\mathbb{X})$	space of Di Marino derivations on \mathbb{X} ; Definition 4.12
$\text{Der}^q(\mathbb{X})$	space of all $b \in \text{Der}^0(\mathbb{X})$ that are q -integrable; Definition 4.12
$\text{Der}_r^q(\mathbb{X})$	space of all $b \in \text{Der}^q(\mathbb{X})$ having r -integrable divergence; Definition 4.12
$L^q_{\text{Lip}}(T\mathbb{X})$	Lipschitz q -tangent module; (4.7)
$W^{1,p}(\mathbb{X})$	Sobolev space via Di Marino derivations with divergence; Definition 5.1
$ Df $	minimal p -weak gradient of $f \in W^{1,p}(\mathbb{X})$; Definition 5.1

2. Preliminaries

Let us fix some general terminology and notation, which we will use throughout the whole paper. For any $a, b \in \mathbb{R}$, we write $a \vee b := \max\{a, b\}$ and $a \wedge b := \min\{a, b\}$. Given a set X and a function $f: X \rightarrow \mathbb{R}$, we denote by $\text{Osc}_S(f) \in [0, +\infty]$ the *oscillation* of f on a set $S \subseteq X$, i.e.

$$(2.1) \quad \text{Osc}_S(f) := \sup_S f - \inf_S f.$$

For any Banach space \mathbb{B} , we denote by \mathbb{B}' its dual Banach space. A map $T: \mathbb{B}_1 \rightarrow \mathbb{B}_2$ between two Banach spaces \mathbb{B}_1 and \mathbb{B}_2 is called an *isomorphism* (resp. an *isometric isomorphism*) provided it is a linear homeomorphism (resp. a norm-preserving linear homeomorphism). Accordingly, we say that \mathbb{B}_1 and \mathbb{B}_2 are *isomorphic* (resp. *isometrically isomorphic*) provided there exists an isomorphism (resp. an isometric isomorphism) $T: \mathbb{B}_1 \rightarrow \mathbb{B}_2$. Finally, we say that \mathbb{B}_1 *embeds* (resp. *isometrically*

embeds) into \mathbb{B}_2 provided \mathbb{B}_1 is isomorphic (resp. isometrically isomorphic) to some subspace of \mathbb{B}_2 .

2.1. Topological and metric notions. Let us recall some notions in topology, referring e.g. to the book [35] for a detailed discussion on the topic. Let (X, τ) be a topological space. Then:

- (X, τ) is said to be *completely regular* if for any $x \in X$ and any neighbourhood $U \in \tau$ of x there exists a continuous function $f: X \rightarrow [0, 1]$ such that $f(x) = 1$ and $f|_{X \setminus U} = 0$. Equivalently, (X, τ) is completely regular if τ is induced by a family of semidistances.
- (X, τ) is said to be *normal* if for any pair of disjoint closed sets $A, B \subseteq X$ there exist disjoint open sets $U_A, U_B \in \tau$ such that $A \subseteq U_A$ and $B \subseteq U_B$.
- (X, τ) is said to be a *Tychonoff space* if it is completely regular and Hausdorff. Every locally compact Hausdorff topological space is a Tychonoff space.

Given two topological spaces (X, τ_X) and (Y, τ_Y) , we denote by $C((X, \tau_X); (Y, \tau_Y))$ the space of continuous maps from (X, τ_X) to (Y, τ_Y) ; we drop τ_X or τ_Y from our notation when the chosen topologies are clear from the context. We use the shorthand notation $C(X, \tau) := C((X, \tau); \mathbb{R})$ for any topological space (X, τ) , where the target \mathbb{R} is equipped with the Euclidean topology. Then

$$C_b(X, \tau) := \{f \in C(X, \tau) \mid f \text{ is bounded}\}$$

is a Banach space if endowed with the supremum norm $\|f\|_{C_b(X, \tau)} := \sup_{x \in X} |f(x)|$.

Next, let us recall some metric concepts. By an *extended distance* on a set X we mean a symmetric function $\mathbf{d}: X \times X \rightarrow [0, +\infty]$ that satisfies the triangle inequality and vanishes exactly on the diagonal $\{(x, x) : x \in X\}$. The pair (X, \mathbf{d}) is called an *extended metric space*. As usual, if $\mathbf{d}(x, y) < +\infty$ for every $x, y \in X$, then \mathbf{d} is called a distance and (X, \mathbf{d}) is called a metric space. Given an extended metric space (X, \mathbf{d}) , a center $x \in X$ and a radius $r \in (0, +\infty)$, we denote

$$B_r^{\mathbf{d}}(x) := \{y \in X \mid \mathbf{d}(x, y) < r\}, \quad \bar{B}_r^{\mathbf{d}}(x) := \{y \in X \mid \mathbf{d}(x, y) \leq r\}.$$

A map $\varphi: X \rightarrow Y$ between two extended metric spaces (X, \mathbf{d}_X) and (Y, \mathbf{d}_Y) is said to be Lipschitz (or L -Lipschitz) if for some constant $L \geq 0$ we have that $\mathbf{d}_Y(\varphi(x), \varphi(y)) \leq L \mathbf{d}_X(x, y)$ holds for every $x, y \in X$. We denote by $\text{Lip}_b(X, \mathbf{d})$ the space of all bounded Lipschitz functions from an extended metric space (X, \mathbf{d}) to the real line \mathbb{R} (equipped with the Euclidean distance). Denote

$$(2.2) \quad \text{Lip}(f, A, \mathbf{d}) := \sup \left\{ \frac{|f(x) - f(y)|}{\mathbf{d}(x, y)} \mid x, y \in A, x \neq y \right\}$$

for all $f \in \text{Lip}_b(X, \mathbf{d})$ and $A \subseteq X$. For brevity, we write $\text{Lip}(f, \mathbf{d}) := \text{Lip}(f, X, \mathbf{d})$. It is well known that $\text{Lip}_b(X, \mathbf{d})$ is a Banach space with respect to the norm $\|f\|_{\text{Lip}_b(X, \mathbf{d})} := \text{Lip}(f, \mathbf{d}) + \sup_{x \in X} |f(x)|$.

Now, consider an extended metric space (X, \mathbf{d}) together with a topology τ on X . We define

$$(2.3) \quad \text{Lip}_b(X, \tau, \mathbf{d}) := \text{Lip}_b(X, \mathbf{d}) \cap C(X, \tau).$$

We endow the vector space $\text{Lip}_b(X, \tau, \mathbf{d})$ with the norm

$$\|f\|_{\text{Lip}_b(X, \tau, \mathbf{d})} := \text{Lip}(f, \mathbf{d}) + \|f\|_{C_b(X, \tau)} \quad \text{for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

Remark 2.1. We claim that

$$(\text{Lip}_b(X, \tau, \mathbf{d}), \|\cdot\|_{\text{Lip}_b(X, \tau, \mathbf{d})}) \quad \text{is a Banach algebra.}$$

Indeed, $\|f\|_{\text{Lip}_b(X, \tau, \mathbf{d})} = \|f\|_{\text{Lip}_b(X, \mathbf{d})}$ holds for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$, and every uniform limit of τ -continuous functions is τ -continuous, thus $\text{Lip}_b(X, \tau, \mathbf{d})$ is a closed vector subspace of $\text{Lip}_b(X, \mathbf{d})$. In particular, $\text{Lip}_b(X, \tau, \mathbf{d})$ is a Banach space. Moreover, it can be readily checked that for any given $f, g \in \text{Lip}_b(X, \tau, \mathbf{d})$ we have that $fg \in \text{Lip}_b(X, \tau, \mathbf{d})$, $\|fg\|_{C_b(X, \tau)} \leq \|f\|_{C_b(X, \tau)}\|g\|_{C_b(X, \tau)}$ and $\text{Lip}(fg, \mathbf{d}) \leq \|f\|_{C_b(X, \tau)}\text{Lip}(g, \mathbf{d}) + \|g\|_{C_b(X, \tau)}\text{Lip}(f, \mathbf{d})$, whence it follows that

$$\begin{aligned} \|fg\|_{\text{Lip}_b(X, \tau, \mathbf{d})} &= \text{Lip}(fg, \mathbf{d}) + \|fg\|_{C_b(X, \tau)} \\ &\leq \|f\|_{C_b(X, \tau)}\text{Lip}(g, \mathbf{d}) + \|g\|_{C_b(X, \tau)}\text{Lip}(f, \mathbf{d}) + \|f\|_{C_b(X, \tau)}\|g\|_{C_b(X, \tau)} \\ &\leq (\text{Lip}(f, \mathbf{d}) + \|f\|_{C_b(X, \tau)}) (\text{Lip}(g, \mathbf{d}) + \|g\|_{C_b(X, \tau)}) \\ &= \|f\|_{\text{Lip}_b(X, \tau, \mathbf{d})} \|g\|_{\text{Lip}_b(X, \tau, \mathbf{d})}. \end{aligned}$$

All in all, we have shown that $\text{Lip}_b(X, \tau, \mathbf{d})$ is a Banach algebra, as we claimed. \blacksquare

At times, it is convenient to use the following shorthand notation:

$$(2.4) \quad \text{Lip}_{b,1}(X, \tau, \mathbf{d}) := \{f \in \text{Lip}_b(X, \tau, \mathbf{d}) \mid \text{Lip}(f, \mathbf{d}) \leq 1\}.$$

Any given $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ is associated with a function $\text{lip}_d(f)$ that accounts for the ‘infinitesimal Lipschitz constants’ of f at the different points of X :

Definition 2.2. (Asymptotic slope) Let (X, \mathbf{d}) be an extended metric space and let τ be a topology on X . Let $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ be given. Then we define the function $\text{lip}_d(f): X \rightarrow [0, \text{Lip}(f, \mathbf{d})]$ as

$$\text{lip}_d(f)(x) := \inf \{ \text{Lip}(f, U, \mathbf{d}) \mid x \in U \in \tau \} \quad \text{for every } x \in X.$$

We say that $\text{lip}_d(f)$ is the *asymptotic slope* of f .

The function $\text{lip}_d(f)$ is τ -upper semicontinuous, as it follows from the ensuing remark:

Remark 2.3. Let (X, τ) be a topological space and $S \neq \emptyset$ a subset of τ . Let $\mathcal{F}: S \rightarrow [0, +\infty]$ be any given functional. Define

$$F(x) := \inf \{ \mathcal{F}(U) \mid x \in U \in S \} \quad \text{for every } x \in X.$$

Then $F: X \rightarrow [0, +\infty]$ is a τ -upper semicontinuous function. Indeed, for any $U \in S$ we have that

$$F_U(x) := \begin{cases} \mathcal{F}(U) & \text{for every } x \in U, \\ +\infty & \text{for every } x \in X \setminus U \end{cases}$$

defines a τ -upper semicontinuous function $F_U: X \rightarrow [0, +\infty]$, thus $F = \inf_{U \in S} F_U$ is τ -upper semicontinuous as well. Similarly, we have that $G(x) := \sup \{ \mathcal{F}(U) : x \in U \in S \}$ (with the convention that $\sup(\emptyset) = 0$) defines a τ -lower semicontinuous function $G: X \rightarrow [0, +\infty]$. \blacksquare

2.2. Measure theory. Let (X, Σ, \mathbf{m}) be a measure space. We denote by $L^0(\mathbf{m})$ the algebra of all equivalence classes (up to \mathbf{m} -a.e. equality) of measurable functions $f: X \rightarrow \mathbb{R}$. For any $p \in [1, \infty]$, we denote by $(L^p(\mathbf{m}), \|\cdot\|_{L^p(\mathbf{m})})$ the *Lebesgue space* of exponent p on (X, Σ, \mathbf{m}) . Then $L^p(\mathbf{m})$ is a Banach space (and $L^\infty(\mathbf{m})$ is also a Banach algebra). Moreover, $L^p(\mathbf{m})$ is a Riesz space with respect to the partial order given by the \mathbf{m} -a.e. inequality: given any $f, g \in L^p(\mathbf{m})$, we declare that $f \leq g$ if and only if $f(x) \leq g(x)$ holds for \mathbf{m} -a.e. $x \in X$. Assuming that the measure \mathbf{m} is σ -finite, we also have that $L^p(\mathbf{m})$ is *Dedekind complete*, which means that any family of functions $\{f_i\}_{i \in I} \subseteq L^p(\mathbf{m})$ with an upper bound (i.e. there exists $g \in L^p(\mathbf{m})$ such

that $f_i \leq g$ for all $i \in I$) has a supremum $\bigvee_{i \in I} f_i \in L^p(\mathbf{m})$. The latter is the unique element of $L^p(\mathbf{m})$ such that

- $f_j \leq \bigvee_{i \in I} f_i$ for every $j \in I$,
- if $\tilde{f} \in L^p(\mathbf{m})$ satisfies $f_j \leq \tilde{f}$ for every $j \in I$, then $\bigvee_{i \in I} f_i \leq \tilde{f}$.

In addition, one can find an at most countable subset $C \subseteq I$ such that $\bigvee_{i \in I} f_i = \bigvee_{i \in C} f_i$ (i.e. $L^p(\mathbf{m})$ has the so-called *countable sup property*). Similarly, every set $\{f_i\}_{i \in I} \subseteq L^p(\mathbf{m})$ with a lower bound has an infimum $\bigwedge_{i \in I} f_i \in L^p(\mathbf{m})$ and there exists $\tilde{C} \subseteq I$ at most countable such that $\bigwedge_{i \in I} f_i = \bigwedge_{i \in \tilde{C}} f_i$ (i.e. the countable inf property holds). In particular, essential unions (and essential intersections) exist: given any family $\{E_i\}_{i \in I} \subseteq \Sigma$, we can find a set $E \in \Sigma$ such that

- $\mathbf{m}(E_i \setminus E) = 0$ for every $i \in I$,
- if $F \in \Sigma$ satisfies $\mathbf{m}(E_i \setminus F) = 0$ for every $i \in I$, then $\mathbf{m}(E \setminus F) = 0$.

The set E is \mathbf{m} -a.e. unique, in the sense that $\mathbf{m}(E \Delta \tilde{E}) = 0$ for any other set $\tilde{E} \in \Sigma$ having the same properties. We say that E is the *\mathbf{m} -essential union* of $\{E_i\}_{i \in I}$. It also holds that E can be chosen of the form $\bigcup_{i \in C} E_i$, for some at most countable subset $C \subseteq I$.

Let (X, Σ, \mathbf{m}) be a finite measure space. Following [11, §1.12(iii)], we say that \mathbf{m} is a *separable measure* if there exists a countable family $\mathcal{C} \subseteq \Sigma$ such that for every $E \in \Sigma$ and $\varepsilon > 0$ we can find $F \in \mathcal{C}$ such that $\mathbf{m}(E \Delta F) < \varepsilon$. The following conditions are equivalent:

- \mathbf{m} is a separable measure,
- $L^p(\mathbf{m})$ is separable for some $p \in [1, \infty)$,
- $L^p(\mathbf{m})$ is separable for every $p \in [1, \infty)$.

See for instance [11, §7.14(iv) and Exercise 4.7.63]. In the class of spaces of our interest in this paper, we can encounter examples of spaces whose reference measure is non-separable (cf. with Example 2.18). An advantage of \mathbf{m} being separable is that it is equivalent to the fact that the weak* topology of $L^\infty(\mathbf{m})$ restricted to its closed unit ball is metrisable (see e.g. Lemma 4.11).

Let (X, τ) be a Hausdorff topological space. We denote by $\mathcal{B}(X, \tau)$ its Borel σ -algebra. A finite Borel measure $\mu: \mathcal{B}(X, \tau) \rightarrow [0, +\infty)$ is called a *Radon measure* if it is *inner regular*, i.e.

$$\mu(B) = \sup \{ \mu(K) \mid K \subseteq B, K \text{ is } \tau\text{-compact} \} \quad \text{for every } B \in \mathcal{B}(X, \tau).$$

It follows that μ is also *outer regular*, which means that

$$\mu(B) = \inf \{ \mu(U) \mid U \in \tau, B \subseteq U \} \quad \text{for every } B \in \mathcal{B}(X, \tau).$$

We denote by $\mathcal{M}_+(X)$ or $\mathcal{M}_+(X, \tau)$ the collection of all finite Radon measures on (X, τ) . We refer to the monograph [46] for a thorough account of the theory of Radon measures. Below we collect some more definitions and results that we shall need later in the paper.

Remark 2.4. Radon measures verify the following version of the monotone convergence theorem: if μ is a finite Radon measure on a Hausdorff topological space (X, τ) and $(f_i)_{i \in I}$ is a non-decreasing net of τ -lower semicontinuous functions $f_i: X \rightarrow [0, +\infty)$ satisfying $\sup_{i \in I, x \in X} f_i(x) < +\infty$, then

$$\lim_{i \in I} \int f_i \, d\mu = \int \lim_{i \in I} f_i \, d\mu.$$

Note that $\lim_{i \in I} f_i = \sup_{i \in I} f_i$ is τ -lower semicontinuous, in particular it is Borel measurable and thus the right-hand side of the identity above is meaningful. See e.g. [11, Lemma 7.2.6]. \blacksquare

Let (X, τ_X) and (Y, τ_Y) be Tychonoff spaces. Given a finite Radon measure μ on X , a map $\varphi: X \rightarrow Y$ is said to be *Lusin μ -measurable* if for any $\varepsilon > 0$ there exists a compact set $K_\varepsilon \subseteq X$ such that $\mu(X \setminus K_\varepsilon) \leq \varepsilon$ and $\varphi|_{K_\varepsilon}$ is continuous. Each Lusin μ -measurable map is in particular Borel μ -measurable (i.e. $\varphi^{-1}(B)$ is a μ -measurable subset of X for every Borel set $B \subseteq Y$). Moreover, if $\mu \in \mathcal{M}_+(X)$ is given and $\varphi: X \rightarrow Y$ is Lusin μ -measurable, then we have that

$$(\varphi_\# \mu)(B) := \mu(\varphi^{-1}(B)) \quad \text{for every Borel set } B \subseteq Y$$

defines a Radon measure $\varphi_\# \mu \in \mathcal{M}_+(Y)$, called the *pushforward* of μ under φ . A map $\varphi: X \rightarrow Y$ is said to be *universally Lusin measurable* if it is Lusin μ -measurable for every $\mu \in \mathcal{M}_+(X)$.

Remark 2.5. We point out that the μ -a.e. pointwise limit of a sequence of Lusin μ -measurable functions is Lusin μ -measurable, thus in particular the pointwise limit of a sequence of universally Lusin measurable functions is universally Lusin measurable. Indeed, fix a Tychonoff space (X, τ) and a Radon measure $\mu \in \mathcal{M}_+(X)$. Assume that a sequence $(f_n)_n$ of Lusin μ -measurable functions $f_n: X \rightarrow \mathbb{R}$ and a limit function $f: X \rightarrow \mathbb{R}$ satisfy $f(x) = \lim_n f_n(x) \in \mathbb{R}$ for μ -a.e. $x \in X$. Given any $\varepsilon > 0$ and $n \in \mathbb{N}$, we can find a compact set $K_\varepsilon^n \subseteq X$ such that $\mu(X \setminus K_\varepsilon^n) \leq \varepsilon/2^n$ and $f_n|_{K_\varepsilon^n}$ is continuous. Then $K_\varepsilon := \bigcap_{n \in \mathbb{N}} K_\varepsilon^n$ is a compact set with $\mu(X \setminus K_\varepsilon) \leq \varepsilon$ such that each $f_n|_{K_\varepsilon}$ is continuous. Thanks to Egorov's theorem, we can find a compact set $\tilde{K}_\varepsilon \subseteq K_\varepsilon$ with $\mu(X \setminus \tilde{K}_\varepsilon) \leq 2\varepsilon$ such that $f_n|_{\tilde{K}_\varepsilon} \rightarrow f|_{\tilde{K}_\varepsilon}$ uniformly, so that $f|_{\tilde{K}_\varepsilon}$ is continuous. Hence, f is Lusin μ -measurable.

Furthermore, we point out that any bounded τ -lower semicontinuous function $f: X \rightarrow [0, +\infty)$ defined on a Tychonoff space (X, τ) is universally Lusin measurable. To prove it, fix any Radon measure $\mu \in \mathcal{M}_+(X)$. It follows e.g. from [11, Lemma 7.2.6] that

$$\int f \, d\mu = \sup \left\{ \int g \, d\mu \mid g \in C(X, \tau), g \leq f \right\}.$$

Hence, we can find a non-decreasing sequence of functions $(g_n)_n \subseteq C(X, \tau)$ such that $g_n \leq f$ for every $n \in \mathbb{N}$ and $\lim_n \int g_n \, d\mu = \int f \, d\mu$. By applying the monotone convergence theorem, we deduce that $\lim_n g_n(x) = f(x)$ for μ -a.e. $x \in X$. Since each continuous function is clearly Lusin μ -measurable, by the first claim of this remark we conclude that f is Lusin μ -measurable. \blacksquare

2.2.1. $L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -modules. In this section, we recall some key concepts in the theory of L^p -Banach L^∞ -modules, which are Banach spaces equipped with additional structures (roughly speaking, with a ‘pointwise norm’ and a multiplication by L^∞ -functions). This language has been developed by Gigli in [23], with the goal of providing a functional-analytic framework for a vector calculus in metric-measure spaces. Strictly related notions were previously studied in the literature for different purposes, see e.g. the notion of *random normed module* introduced by Guo [26, 27] and investigated in a long series of works (see [28, 29] and the references therein), or the notion of *random Banach space* introduced by Haydon, Levy and Raynaud [32]. The definitions and results presented below are taken from [22, 23].

For any measure space (X, Σ, \mathbf{m}) , the space $L^\infty(\mathbf{m})$ is a commutative ring (with unity) with respect to the usual pointwise operations. Since the field of real numbers \mathbb{R} can be identified with a subring of $L^\infty(\mathbf{m})$ (via the map sending $\lambda \in \mathbb{R}$ to the function that is \mathbf{m} -a.e. equal to λ), every module over $L^\infty(\mathbf{m})$ is in particular a vector space. Recall also that a homomorphism $T: M \rightarrow N$ of $L^\infty(\mathbf{m})$ -modules is an $L^\infty(\mathbf{m})$ -linear operator, i.e. a map satisfying

$$T(f \cdot v + g \cdot w) = f \cdot T(v) + g \cdot T(w) \quad \text{for every } f, g \in L^\infty(\mathbf{m}) \text{ and } v, w \in M.$$

In particular, each homomorphism of $L^\infty(\mathbf{m})$ -modules is a homomorphism of vector spaces, i.e. a linear operator. Observe that $L^p(\mathbf{m})$ is an $L^\infty(\mathbf{m})$ -module for every $p \in [1, \infty]$.

Definition 2.6. ($L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module) Let (X, Σ, \mathbf{m}) be a σ -finite measure space and let $p \in (1, \infty)$. Then a module \mathcal{M} over $L^\infty(\mathbf{m})$ is said to be an $L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module if it is endowed with a functional $|\cdot|: \mathcal{M} \rightarrow L^p(\mathbf{m})^+$, called a *pointwise norm* on \mathcal{M} , such that:

- i) For any $v \in \mathcal{M}$, it holds that $|v| = 0$ if and only if $v = 0$.
- ii) $|v + w| \leq |v| + |w|$ for every $v, w \in \mathcal{M}$.
- iii) $|f \cdot v| = |f| |v|$ for every $f \in L^\infty(\mathbf{m})$ and $v \in \mathcal{M}$.
- iv) The norm $\|v\|_{\mathcal{M}} := \||v|\|_{L^p(\mathbf{m})}$ on \mathcal{M} is complete.

Every $L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module is in particular a Banach space. A map $\Phi: \mathcal{M} \rightarrow \mathcal{N}$ between $L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -modules \mathcal{M}, \mathcal{N} is said to be an *isomorphism of $L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -modules* if it is an isomorphism of $L^\infty(\mathbf{m})$ -modules satisfying $|\Phi(v)| = |v|$ for all $v \in \mathcal{M}$.

Definition 2.7. (Dual of an $L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module) Let (X, Σ, \mathbf{m}) be a σ -finite measure space. Let $p, q \in (1, \infty)$ be conjugate exponents and let \mathcal{M} be an $L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module. Then we define \mathcal{M}^* as the set of all those homomorphisms $\omega: \mathcal{M} \rightarrow L^1(\mathbf{m})$ of $L^\infty(\mathbf{m})$ -modules for which there exists a function $g \in L^q(\mathbf{m})^+$ such that

$$(2.5) \quad |\omega(v)| \leq g|v| \quad \text{for every } v \in \mathcal{M}.$$

The space \mathcal{M}^* is called the *continuous module dual* of \mathcal{M} .

The space \mathcal{M}^* is a module over $L^\infty(\mathbf{m})$ if endowed with the following pointwise operations:

$$\begin{aligned} (\omega + \eta)(v) &:= \omega(v) + \eta(v) \quad \text{for every } \omega, \eta \in \mathcal{M}^* \text{ and } v \in \mathcal{M}, \\ (f \cdot \omega)(v) &:= f \omega(v) \quad \text{for every } f \in L^\infty(\mathbf{m}), \omega \in \mathcal{M}^* \text{ and } v \in \mathcal{M}. \end{aligned}$$

Moreover, to any element $\omega \in \mathcal{M}^*$ we associate the function $|\omega| \in L^q(\mathbf{m})^+$, which we define as

$$|\omega| := \bigvee \{ \omega(v) \mid v \in \mathcal{M}, |v| \leq 1 \} = \bigwedge \{ g \in L^q(\mathbf{m})^+ \mid g \text{ satisfies (2.5)} \}.$$

It holds that $(\mathcal{M}^*, |\cdot|)$ is an $L^q(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module.

The continuous module dual \mathcal{M}^* of \mathcal{M} is in particular a Banach space, which can be identified with the dual Banach space \mathcal{M}' through the operator $\text{INT}_{\mathcal{M}}: \mathcal{M}^* \rightarrow \mathcal{M}'$, defined as

$$(2.6) \quad \text{INT}_{\mathcal{M}}(\omega)(v) := \int \omega(v) d\mathbf{m} \quad \text{for every } \omega \in \mathcal{M}^* \text{ and } v \in \mathcal{M}.$$

Indeed, the map $\text{INT}_{\mathcal{M}}$ is an isometric isomorphism of Banach spaces (see [23, Proposition 1.2.13]).

2.3. Extended metric-topological measure spaces. In this section, we discuss the notion of *extended metric-topological (measure) space* that was introduced by Ambrosio, Erbar and Savaré in [4, Definitions 4.1 and 4.7] (see also [42, Definition 2.1.3]).

Definition 2.8. (Extended metric-topological measure space) Let (X, \mathbf{d}) be an extended metric space and let τ be a Hausdorff topology on X . Then we say that (X, τ, \mathbf{d}) is an *extended metric-topological space* (or an *e.m.t. space* for short) if the following conditions hold:

- i) The topology τ coincides with the initial topology of $\text{Lip}_b(X, \tau, \mathbf{d})$.
- ii) The extended distance \mathbf{d} can be recovered through the formula

$$(2.7) \quad \mathbf{d}(x, y) = \sup \{ |f(x) - f(y)| \mid f \in \text{Lip}_{b,1}(X, \tau, \mathbf{d}) \} \quad \text{for every } x, y \in X,$$

where $\text{Lip}_{b,1}(X, \tau, \mathbf{d})$ is defined as in (2.4).

When (X, τ, \mathbf{d}) is equipped with a finite Radon measure $\mathbf{m} \in \mathcal{M}_+(X)$, we say that $\mathbb{X} := (X, \tau, \mathbf{d}, \mathbf{m})$ is an *extended metric-topological measure space* (or an *e.m.t.m. space* for short).

In particular, if (X, τ, \mathbf{d}) is an e.m.t. space, then (X, τ) is a Tychonoff space. Given an e.m.t.m. space $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$, we know from [42, Lemma 2.1.27] that

$$(2.8) \quad \text{Lip}_b(X, \tau, \mathbf{d}) \text{ is strongly dense in } L^p(\mathbf{m}), \text{ for every } p \in [1, \infty).$$

Moreover, given any set $E \in \mathcal{B}(X, \tau)$, it can be readily checked that

$$(2.9) \quad \mathbb{X}_\perp E := (E, \tau_E, \mathbf{d}_E, \mathbf{m}_\perp E)$$

is an e.m.t.m. space, where τ_E is the subspace topology on E induced by τ , while $\mathbf{d}_E := \mathbf{d}|_{E \times E}$ and $\mathbf{m}_\perp E$ denotes the Radon measure on E that is obtained from \mathbf{m} by restriction.

Let us now prove some technical results, which will be needed later. First, we show that each e.m.t.m. space can be decomposed (in an \mathbf{m} -a.e. unique manner) into a \mathbf{d} -separable component and a ‘purely non- \mathbf{d} -separable’ one:

Lemma 2.9. (Maximal \mathbf{d} -separable component $S_\mathbb{X}$) *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be a given e.m.t.m. space. Then there exists a \mathbf{d} -separable set $S_\mathbb{X} \in \mathcal{B}(X, \tau)$ such that $\mathbf{m}(E) = 0$ holds for any \mathbf{d} -separable set $E \in \mathcal{B}(X, \tau)$ satisfying $E \subseteq X \setminus S_\mathbb{X}$. Moreover, the set $S_\mathbb{X}$ is unique in the \mathbf{m} -a.e. sense, meaning that $\mathbf{m}(S_\mathbb{X} \Delta \tilde{S}_\mathbb{X}) = 0$ for any other set $\tilde{S}_\mathbb{X} \in \mathcal{B}(X, \tau)$ having the same properties as $S_\mathbb{X}$.*

Proof. Fix any \mathbf{m} -a.e. representative $S_\mathbb{X} \in \mathcal{B}(X, \tau)$ of the \mathbf{m} -essential union of the family of sets

$$\{S \in \mathcal{B}(X, \tau) \mid S \text{ is } \mathbf{d}\text{-separable and } \mathbf{m}(S) > 0\}.$$

Recall that $S_\mathbb{X}$ can be chosen to be of the form $\bigcup_{n \in \mathbb{N}} S_n$, for some sequence $(S_n)_n \subseteq \mathcal{B}(X, \tau)$ such that S_n is \mathbf{d} -separable and $\mathbf{m}(S_n) > 0$ for every $n \in \mathbb{N}$. In particular, the set $S_\mathbb{X}$ is \mathbf{d} -separable. If $E \subseteq X \setminus S_\mathbb{X}$ is τ -Borel and \mathbf{d} -separable, then $\mathbf{m}(E) = 0$ thanks to the definition of \mathbf{m} -essential union. Finally, if $\tilde{S}_\mathbb{X}$ is another set having the same properties as $S_\mathbb{X}$, then the inclusion $\tilde{S}_\mathbb{X} \setminus S_\mathbb{X} \subseteq X \setminus S_\mathbb{X}$ (resp. $S_\mathbb{X} \setminus \tilde{S}_\mathbb{X} \subseteq X \setminus \tilde{S}_\mathbb{X}$) implies that $\mathbf{m}(\tilde{S}_\mathbb{X} \setminus S_\mathbb{X}) = 0$ (resp. $\mathbf{m}(S_\mathbb{X} \setminus \tilde{S}_\mathbb{X}) = 0$), thus $\mathbf{m}(S_\mathbb{X} \Delta \tilde{S}_\mathbb{X}) = 0$. \square

Next, we give sufficient conditions for the separability of the measure \mathbf{m} of an e.m.t.m. space. The proof of the ensuing result is rather standard, but we provide it for the reader’s convenience.

Lemma 2.10. *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Assume either that τ is metrisable on every τ -compact set or that $\mathbf{m}(X \setminus S_{\mathbb{X}}) = 0$. Then it holds that the measure \mathbf{m} is separable.*

Proof. Let us distinguish the two cases. First, assume that τ is metrisable on τ -compact sets. Take an increasing sequence $(K_n)_{n \in \mathbb{N}}$ of τ -compact subsets of X with $\mathbf{m}(X \setminus \bigcup_n K_n) = 0$. For any $n \in \mathbb{N}$, fix a distance \mathbf{d}_n on K_n metrising τ , and a \mathbf{d}_n -dense sequence $(x_j^n)_{j \in \mathbb{N}}$ in K_n . Define

$$\mathcal{C} := \bigcup_{n \in \mathbb{N}} \left\{ \bigcup_{j \in F} \bar{B}_{q_j}^{\mathbf{d}_n}(x_j^n) \mid F \subseteq \mathbb{N} \text{ finite, } (q_j)_{j \in F} \subseteq \mathbb{Q} \cap (0, +\infty) \right\}.$$

Note that \mathcal{C} is a countable family of τ -closed subsets of X , thus $\mathcal{C} \subseteq \mathcal{B}(X, \tau)$. We claim that

$$(2.10) \quad \inf_{C \in \mathcal{C}} \mathbf{m}(E \Delta C) = 0 \quad \text{for every } E \in \mathcal{B}(X, \tau),$$

whence the separability of \mathbf{m} follows. To prove the claim, fix $E \subseteq X$ τ -Borel and $\varepsilon > 0$. We can choose $n \in \mathbb{N}$ so that $\mathbf{m}(E \setminus K_n) \leq \varepsilon$. By the inner regularity of \mathbf{m} , we can find a τ -compact set $K \subseteq E \cap K_n$ such that $\mathbf{m}((E \cap K_n) \setminus K) \leq \varepsilon$. By the outer regularity of \mathbf{m} , we can find $U \in \tau$ such that $K \subseteq U$ and $\mathbf{m}(U \setminus K) \leq \varepsilon$. Due to the compactness of K , there exist $y_1, \dots, y_k \in K$ and $r_1, \dots, r_k > 0$ such that $K \subseteq \bigcup_{i=1}^k \bar{B}_{r_i}^{\mathbf{d}_n}(y_i) \subseteq U \cap K_n$. Moreover, for any $i = 1, \dots, k$ we can find $j_i \in \mathbb{N}$ and $q_i \in \mathbb{Q} \cap (r_i, +\infty)$ such that $\bar{B}_{r_i}^{\mathbf{d}_n}(y_i) \subseteq \bar{B}_{q_i}^{\mathbf{d}_n}(x_{j_i}^n) \subseteq U \cap K_n$. Therefore, we have that $C := \bigcup_{i=1}^k \bar{B}_{q_i}^{\mathbf{d}_n}(x_{j_i}^n) \in \mathcal{C}$ satisfies $K \subseteq C \subseteq U$, whence it follows that $\mathbf{m}(E \Delta C) \leq 3\varepsilon$. This proves (2.10), which gives the statement in the case where τ is metrisable on τ -compact sets.

Let us pass to the second case: assume $\mathbf{m}(X \setminus S_{\mathbb{X}}) = 0$. Fix a \mathbf{d} -dense sequence $(y_k)_{k \in \mathbb{N}}$ in $S_{\mathbb{X}}$. In this case, we define the countable collection \mathcal{C} of τ -closed subsets of X as

$$\mathcal{C} := \left\{ \bigcup_{j \in F} \bar{B}_{q_j}^{\mathbf{d}}(y_j) \mid F \subseteq \mathbb{N} \text{ finite, } (q_j)_{j \in F} \subseteq \mathbb{Q} \cap (0, +\infty) \right\}.$$

We claim that (2.10) holds. To prove it, fix any $E \in \mathcal{B}(X, \tau)$ and $\varepsilon > 0$. By the outer regularity of \mathbf{m} , we can find a τ -open set $U \subseteq X$ such that $E \subseteq U$ and $\mathbf{m}(U \setminus E) \leq \varepsilon$. Since τ is coarser than the topology induced by \mathbf{d} , we have that U is \mathbf{d} -open, thus there exist a subsequence $(y_{k_j})_{j \in \mathbb{N}}$ of $(y_k)_{k \in \mathbb{N}}$ and a sequence of radii $(q_j)_{j \in \mathbb{N}} \subseteq \mathbb{Q} \cap (0, +\infty)$ such that $E \cap S_{\mathbb{X}} \subseteq \bigcup_{j \in \mathbb{N}} \bar{B}_{q_j}^{\mathbf{d}}(y_{k_j}) \subseteq U$. Thanks to the continuity from below of \mathbf{m} , we can thus find $N \in \mathbb{N}$ such that the set $C := \bigcup_{j=1}^N \bar{B}_{q_j}^{\mathbf{d}}(y_{k_j}) \in \mathcal{C}$ satisfies $\mathbf{m}(E \Delta C) \leq 2\varepsilon$. This proves (2.10), thus the statement holds when $\mathbf{m}(X \setminus S_{\mathbb{X}}) = 0$. \square

Observe that the second assumption in Lemma 2.10 is verified, for instance, when (X, \mathbf{d}) is separable. We also point out that the first assumption can be relaxed to: *for some $D \in \mathcal{B}(X, \tau)$ such that \mathbf{m} is concentrated on D , the topology τ is metrisable on every τ -compact subset of D* . A significant example of a non-metrisable topology τ that is metrisable on all τ -compact sets is the weak* topology of the dual \mathbb{B}' of a separable infinite-dimensional Banach space \mathbb{B} .

2.3.1. Compactification of an extended metric-topological space. A very important feature of the category of extended metric-topological spaces is that it is closed under a notion of *compactification*, devised in this framework by Savaré [42,

Section 2.1.7] via the Gelfand theory of Banach algebras. By virtue of the existence of compactifications, one can reduce many proofs to the compact case.

Let us briefly recall the construction of the Gelfand compactification of an e.m.t. space (X, τ, \mathbf{d}) . By a *character* of $\text{Lip}_b(X, \tau, \mathbf{d})$ we mean a non-zero element φ of the dual Banach space of the normed space $(\text{Lip}_b(X, \tau, \mathbf{d}), \|\cdot\|_{C_b(X, \tau)})$ that satisfies

$$(2.11) \quad \varphi(fg) = \varphi(f)\varphi(g) \quad \text{for every } f, g \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

We denote by \hat{X} the set of all characters of $\text{Lip}_b(X, \tau, \mathbf{d})$. We equip \hat{X} with the topology $\hat{\tau}$ obtained by restricting the weak* topology of the dual of $(\text{Lip}_b(X, \tau, \mathbf{d}), \|\cdot\|_{C_b(X, \tau)})$ to \hat{X} . The canonical embedding map $\iota: X \hookrightarrow \hat{X}$ is given by

$$\iota(x)(f) := f(x) \quad \text{for every } x \in X \text{ and } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

Moreover, the *Gelfand transform* $\Gamma: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow C_b(\hat{X}, \hat{\tau})$ is defined as

$$(2.12) \quad \Gamma(f)(\varphi) := \varphi(f) \quad \text{for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}) \text{ and } \varphi \in \hat{X}.$$

Note that $\Gamma(f) \circ \iota = f$ for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$. Finally, we define the extended distance $\hat{\mathbf{d}}$ as

$$\hat{\mathbf{d}}(\varphi, \psi) := \sup \{ |\varphi(f) - \psi(f)| \mid f \in \text{Lip}_{b,1}(X, \tau, \mathbf{d}) \} \quad \text{for every } \varphi, \psi \in \hat{X}.$$

Remark 2.11. We claim that

$$\varphi(\lambda \mathbb{1}_X) = \lambda \quad \text{for every } \varphi \in \hat{X} \text{ and } \lambda \in \mathbb{R}.$$

Indeed, (2.11) and the linearity of φ guarantee that $\varphi(\lambda \mathbb{1}_X)\varphi(\mathbb{1}_X) = \varphi(\lambda \mathbb{1}_X) = \lambda\varphi(\mathbb{1}_X)$, and (2.11) implies also that $\varphi(\mathbb{1}_X) \neq 0$ (otherwise, we would have $\varphi(f) = \varphi(f\mathbb{1}_X) = \varphi(f)\varphi(\mathbb{1}_X) = 0$ for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$, contradicting the fact that $\varphi \neq 0$). It follows that $\varphi(\lambda \mathbb{1}_X) = \lambda$. \blacksquare

The objects \hat{X} , $\hat{\tau}$, ι , Γ and $\hat{\mathbf{d}}$ defined above have the following properties [42, Theorem 2.1.34]:

Theorem 2.12. (Gelfand compactification of an e.m.t. space) *Let (X, τ, \mathbf{d}) be an e.m.t. space. Then $(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ is an e.m.t. space and $(\hat{X}, \hat{\tau})$ is compact. Moreover, the following conditions hold:*

- i) *The map ι is a homeomorphism between (X, τ) and its image $\iota(X)$ in $(\hat{X}, \hat{\tau})$.*
- ii) *The set $\iota(X)$ is a dense subset of $(\hat{X}, \hat{\tau})$.*
- iii) *We have that $\hat{\mathbf{d}}(\iota(x), \iota(y)) = \mathbf{d}(x, y)$ for every $x, y \in X$.*

We say that $(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ is the *compactification* of (X, τ, \mathbf{d}) , with embedding $\iota: X \hookrightarrow \hat{X}$.

If $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ is an e.m.t.m. space and $(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ denotes the compactification of (X, τ, \mathbf{d}) , with embedding $\iota: X \hookrightarrow \hat{X}$, then we define the measure $\hat{\mathbf{m}}$ on \hat{X} as

$$\hat{\mathbf{m}} := \iota_{\#} \mathbf{m} \in \mathcal{M}_+(\hat{X}, \hat{\tau}).$$

The fact that $\hat{\mathbf{m}}$ is a Radon measure follows from the continuity of ι (as all continuous maps are universally Lusin measurable). Given any exponent $p \in [1, \infty]$, we have that $\iota: X \hookrightarrow \hat{X}$ induces via pre-composition a map $\iota^*: L^p(\hat{\mathbf{m}}) \rightarrow L^p(\mathbf{m})$ (sending the $\hat{\mathbf{m}}$ -a.e. equivalence class of a p -integrable Borel function $\hat{f}: \hat{X} \rightarrow \mathbb{R}$ to the \mathbf{m} -a.e. equivalence class of $\hat{f} \circ \iota$), which is an isomorphism of Banach spaces and of Riesz spaces (and also of Banach algebras when $p = \infty$).

Albeit implicitly contained in [42], we isolate the following result for the reader's convenience:

Lemma 2.13. *Let (X, τ, \mathbf{d}) be an e.m.t. space. Let $(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ be its compactification, with embedding $\iota: X \hookrightarrow \hat{X}$. Then the Gelfand transform Γ maps $\text{Lip}_b(X, \tau, \mathbf{d})$ to $\text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$. Moreover, it holds that $\Gamma: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ is an isomorphism of Banach algebras, with inverse given by*

$$(2.13) \quad \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}}) \ni \hat{f} \longmapsto \hat{f} \circ \iota \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

Proof. Fix $f \in \text{Lip}_b(X, \tau, \mathbf{d})$. If $\text{Lip}(f, \mathbf{d}) = 0$, then f is constant, thus $|\Gamma(f)(\varphi) - \Gamma(f)(\psi)| = 0$ for every $\varphi, \psi \in \hat{X}$ by Remark 2.11. If $\text{Lip}(f, \mathbf{d}) > 0$, then $\tilde{f} := \text{Lip}(f, \mathbf{d})^{-1}f \in \text{Lip}_{b,1}(X, \tau, \mathbf{d})$, thus

$$|\Gamma(f)(\varphi) - \Gamma(f)(\psi)| = |\varphi(f) - \psi(f)| = \text{Lip}(f, \mathbf{d})|\varphi(\tilde{f}) - \psi(\tilde{f})| \leq \text{Lip}(f, \mathbf{d})\hat{\mathbf{d}}(\varphi, \psi)$$

for all $\varphi, \psi \in \hat{X}$. All in all, we have that $\Gamma(f) \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ and $\text{Lip}(\Gamma(f), \hat{\mathbf{d}}) \leq \text{Lip}(f, \mathbf{d})$. Also,

$$\begin{aligned} \text{Lip}(\Gamma(f), \hat{\mathbf{d}}) &\geq \text{Lip}(\Gamma(f), \iota(X), \hat{\mathbf{d}}) \\ &= \sup \left\{ \frac{|\Gamma(f)(\iota(x)) - \Gamma(f)(\iota(y))|}{\hat{\mathbf{d}}(\iota(x), \iota(y))} \mid x, y \in X, x \neq y \right\} \\ &= \sup \left\{ \frac{|f(x) - f(y)|}{\mathbf{d}(x, y)} \mid x, y \in X, x \neq y \right\} = \text{Lip}(f, \mathbf{d}), \end{aligned}$$

so that $\text{Lip}(\Gamma(f), \hat{\mathbf{d}}) = \text{Lip}(f, \mathbf{d})$. Moreover, since $\Gamma(f)$ is $\hat{\tau}$ -continuous and $\iota(X)$ is $\hat{\tau}$ -dense in \hat{X} , we have that $\|\Gamma(f)\|_{C_b(\hat{X}, \hat{\tau})} = \sup_{x \in X} |\Gamma(f)(\iota(x))| = \sup_{x \in X} |f(x)| = \|f\|_{C_b(X, \tau)}$. Hence, it holds that $\Gamma(\text{Lip}_b(X, \tau, \mathbf{d})) \subseteq \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ and $\|\Gamma(f)\|_{\text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})} = \|f\|_{\text{Lip}_b(X, \tau, \mathbf{d})}$ for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$.

Now, denote by I the map in (2.13). Clearly, Γ and I are homomorphisms of Banach algebras. As we already pointed out, we have that $(I \circ \Gamma)(f) = \Gamma(f) \circ \iota = f$ for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$, which means that $I \circ \Gamma = \text{id}_{\text{Lip}_b(X, \tau, \mathbf{d})}$. Conversely, for any $\hat{f} \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ we have that

$$(\Gamma \circ I)(\hat{f})(\iota(x)) = \Gamma(\hat{f} \circ \iota)(\iota(x)) = \iota(x)(\hat{f} \circ \iota) = \hat{f}(\iota(x)) \quad \text{for every } x \in X,$$

which gives that $(\Gamma \circ I)(\hat{f})|_{\iota(X)} = \hat{f}|_{\iota(X)}$. Since $(\Gamma \circ I)(\hat{f}), \hat{f}$ are $\hat{\tau}$ -continuous and $\iota(X)$ is $\hat{\tau}$ -dense in \hat{X} , we conclude that $(\Gamma \circ I)(\hat{f}) = \hat{f}$, thus $\Gamma \circ I = \text{id}_{\text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})}$. The proof is complete. \square

Let us also point out that for any given function $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ it holds that

$$(2.14) \quad \text{lip}_{\mathbf{d}}(f)(x) \leq \text{lip}_{\hat{\mathbf{d}}}(\Gamma(f))(\iota(x)) \quad \text{for every } x \in X,$$

but it might happen that the inequality in (2.14) is not an equality. Hence, we have that

$$(2.15) \quad \text{lip}_{\mathbf{d}}(f) \leq \iota^*(\text{lip}_{\hat{\mathbf{d}}}(\Gamma(f))) \quad \text{holds } \mathbf{m}\text{-a.e. on } X, \text{ for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}),$$

but it might happen that the \mathbf{m} -a.e. inequality in (2.15) is not an \mathbf{m} -a.e. equality.

2.3.2. Examples of extended metric-topological spaces. We collect here many examples of e.m.t.(m.) spaces. As observed in [4, Section 13] and [42, Section 2.1.3], the following are e.m.t.m. spaces:

- A metric space (X, \mathbf{d}) together with the topology $\tau_{\mathbf{d}}$ induced by \mathbf{d} and a finite Radon measure $\mathbf{m} \geq 0$ on X . In particular, a complete and separable metric space (X, \mathbf{d}) together with the topology $\tau_{\mathbf{d}}$ and a finite Borel measure $\mathbf{m} \geq 0$ on X (as all finite Borel measures on a complete and separable metric space

are Radon). The latter are often referred to as *metric-measure spaces* in the literature.

- A Banach space \mathbb{B} together with the distance induced by its norm, the weak topology τ_w and a finite Radon measure on (\mathbb{B}, τ_w) .
- The dual \mathbb{B}' of a Banach space \mathbb{B} together with the distance induced by the dual norm, the weak* topology τ_{w^*} and a finite Radon measure on $(\mathbb{B}', \tau_{w^*})$. We point out that if \mathbb{B} is separable, then $(\mathbb{B}', \tau_{w^*})$ is a Lusin space [46, Corollary 1 at p. 115], so that every finite Borel measure on $(\mathbb{B}', \tau_{w^*})$ is Radon.
- An *abstract Wiener space*, i.e. a separable Banach space X together with a (centered, non-degenerate) Gaussian measure γ and the extended distance that is induced by the *Cameron–Martin space* of (X, γ) ; see e.g. [12].
- Other important examples of e.m.t.m. spaces are given by some ‘extended sub-Finsler-type structures’ [42, Example 2.1.3] or the so-called *configuration spaces* [4, Section 13.3].
- Another collection of structures that fall into the class of e.m.t.m. spaces is the one of disjoint unions of e.m.t.m. spaces equipped with ∞ -cross-distances. Namely, given a countable family $\{(X_i, \tau_i, \mathbf{d}_i, \mathbf{m}_i) : i \in I\}$ of e.m.t.m. spaces such that $\sum_{i \in I} \mathbf{m}_i(X_i) < +\infty$, we endow $X := \bigsqcup_{i \in I} X_i$ with the topology $\tau := \{U \subseteq X : U \cap X_i \in \tau_i \text{ for all } i \in I\}$, the finite Radon measure $\mathcal{B}(X, \tau) \ni E \mapsto \mathbf{m}(E) := \sum_{i \in I} \mathbf{m}_i(E \cap X_i)$, and the extended distance

$$\mathbf{d}(x, y) := \begin{cases} \mathbf{d}_i(x, y) & \text{if } x, y \in X_i \text{ for some } i \in I, \\ +\infty & \text{otherwise.} \end{cases}$$

It can be readily checked that the resulting quartet $(X, \tau, \mathbf{d}, \mathbf{m})$ is an e.m.t.m. space.

- Similar objects that can be modelled by the theory of e.m.t.m. spaces are several kinds of structures that are ‘foliated’, such as the parabolic space or measurable laminations. In these examples, a given topological space is partitioned into subspaces, each equipped with its own distance, that are not ‘interconnected’ (which means that the pairwise distance between two different subspaces is declared to be infinite).

On the one hand, the class of e.m.t. spaces in the first bullet point above (i.e. metric spaces equipped with the topology induced by the distance) shows that, in a sense, the theory of e.m.t. spaces is an extension of that of metric spaces. On the other hand, as it is evident from Example 2.14 below (which was pointed out to us by Timo Schultz), the category of e.m.t. spaces encompasses also the one of Tychonoff spaces, but in this paper we will not investigate further in this direction. We point out that it would be interesting to study also the larger class of extended *pseudometric-topological spaces*, which are defined as e.m.t. spaces with the only exception that \mathbf{d} is an extended pseudodistance (i.e. \mathbf{d} is allowed to vanish off the diagonal $\{(x, x) : x \in X\} \subseteq X \times X$), but we do not pursue this goal here. However, we draw attention to the fact that the topology τ of an extended pseudometric-topological space (X, τ, \mathbf{d}) is Hausdorff if and only if \mathbf{d} is an extended distance. Several interesting structures, such as metric quotients endowed with a suitable topology, are examples of extended pseudometric-topological spaces.

Example 2.14. ('Purely-topological' e.m.t. space) Let (X, τ) be a given Tychonoff space. We denote by $\mathbf{d}_{\text{discr}}$ the *discrete distance* on X , i.e. we define

$$(2.16) \quad \mathbf{d}_{\text{discr}}(x, y) := \begin{cases} 1 & \text{for every } x, y \in X \text{ with } x \neq y, \\ 0 & \text{for every } x, y \in X \text{ with } x = y. \end{cases}$$

Then $(X, \tau, \mathbf{d}_{\text{discr}})$ is an e.m.t. space. Indeed, it can be readily checked that the $\mathbf{d}_{\text{discr}}$ -Lipschitz functions $f: X \rightarrow \mathbb{R}$ are exactly the bounded functions and $\text{Lip}(f, \mathbf{d}_{\text{discr}}) = \text{Osc}_X(f)$, in particular

$$\text{Lip}_b(X, \tau, \mathbf{d}_{\text{discr}}) = C_b(X, \tau), \quad \|\cdot\|_{\text{Lip}_b(X, \tau, \mathbf{d}_{\text{discr}})} = \text{Osc}_X(\cdot) + \|\cdot\|_{C_b(X, \tau)}.$$

Therefore, the complete regularity of (X, τ) ensures that the initial topology of $\text{Lip}_b(X, \tau, \mathbf{d}_{\text{discr}})$ coincides with τ (so that Definition 2.8 i) holds), and for any two distinct points $x, y \in X$ we can find (as (X, τ) is completely Hausdorff) a τ -continuous function $f: X \rightarrow [0, 1]$ such that $f(x) = 1$ and $f(y) = 0$, so that $\mathbf{d}_{\text{discr}}(x, y) = 1 = |f(x) - f(y)|$ (whence Definition 2.8 ii) follows). ■

Next, we present explicit constructions of e.m.t.m. spaces that will be useful later in the paper.

Example 2.15. We endow $X := [0, 1]^2 \subseteq \mathbb{R}^2$ with the Euclidean topology τ and the distance

$$\mathbf{d}((x, t), (y, s)) := \max\{\mathbf{d}_{\text{discr}}(x, y), \mathbf{d}_{\text{Eucl}}(t, s)\} \quad \text{for every } (x, t), (y, s) \in X,$$

where $\mathbf{d}_{\text{discr}}$ denotes the discrete distance, while $\mathbf{d}_{\text{Eucl}}(t, s) := |t - s|$ is the Euclidean distance. One can easily check that (X, τ, \mathbf{d}) is an e.m.t. space, and that a given function $f: X \rightarrow \mathbb{R}$ belongs to the space $\text{Lip}_b(X, \tau, \mathbf{d})$ if and only if it is τ -continuous, $f(x, \cdot) \in \text{Lip}_b([0, 1], \mathbf{d}_{\text{Eucl}})$ for every $x \in [0, 1]$ and $\sup_{x \in [0, 1]} \text{Lip}(f(x, \cdot), \mathbf{d}_{\text{Eucl}}) < +\infty$. Moreover, straightforward arguments show that

$$(2.17) \quad \text{Lip}(f, \mathbf{d}) = \text{Osc}_X(f) \vee \sup_{x \in [0, 1]} \text{Lip}(f(x, \cdot), \mathbf{d}_{\text{Eucl}})$$

for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$. ■

Whereas the Banach algebra $\text{Lip}_b(X, \mathbf{d})$ associated to a metric space (X, \mathbf{d}) is (isometrically isomorphic to) a dual Banach space (see [50, Corollary 3.4]), in the more general setting of e.m.t. spaces we can provide examples where $\text{Lip}_b(X, \tau, \mathbf{d})$ is not isometrically isomorphic (and not even just isomorphic) to a dual Banach space, see Proposition 2.16 below. The possible non-existence of a predual of $\text{Lip}_b(X, \tau, \mathbf{d})$ will have an important role in Definition 4.4.

Proposition 2.16. *Let (K, τ) be an infinite compact metrisable topological space. Let $\mathbf{d}_{\text{discr}}$ denote the discrete distance on K . Then $\text{Lip}_b(K, \tau, \mathbf{d}_{\text{discr}})$ is not isomorphic to a dual Banach space.*

Proof. We recall from Example 2.14 that $(K, \tau, \mathbf{d}_{\text{discr}})$ is an extended metric-topological space that satisfies $\mathbf{L} := \text{Lip}_b(K, \tau, \mathbf{d}_{\text{discr}}) = C(K, \tau)$ and

$$\|f\|_{\mathbf{L}} := \|f\|_{\text{Lip}_b(K, \tau, \mathbf{d}_{\text{discr}})} = \text{Osc}_K(f) + \|f\|_{C(K, \tau)}$$

for every $f \in \mathbf{L}$. Note that $\|f\|_{C(K, \tau)} \leq \|f\|_{\mathbf{L}} \leq 3\|f\|_{C(K, \tau)}$ for every $f \in \mathbf{L}$. Since (K, τ) is a compact metrisable topological space, it holds that $C(K, \tau)$ is separable [2, Theorem 4.1.3] and thus \mathbf{L} is separable. Since τ is a Hausdorff topology, by virtue of Remark 2.17 below we can find a sequence $(U_n)_{n \in \mathbb{N}} \subseteq \tau$ of pairwise disjoint sets such that each set U_n contains at least two distinct points x_n and y_n . Since

(K, τ) is completely regular, for any $n \in \mathbb{N}$ we can find a τ -continuous function $f_n: K \rightarrow [-1, 1]$ such that $\{f_n \neq 0\} \subseteq U_n$, $f_n(x_n) = 1$ and $f_n(y_n) = -1$. Letting c_{00} be the vector space of real-valued sequences $a = (a_n)_n$ satisfying $a_n = 0$ for all but finitely many indices $n \in \mathbb{N}$, we define the linear operator $\phi: c_{00} \rightarrow L$ as

$$\phi(a) := \frac{1}{3} \sum_{\substack{n \in \mathbb{N}: \\ a_n \neq 0}} a_n f_n \in L \quad \text{for every } a = (a_n)_n \in c_{00}.$$

Recall that c_{00} is a dense subspace of the Banach space $(c_0, \|\cdot\|_{c_0})$, where c_0 is the space of real-valued sequences $a = (a_n)_n$ with $\lim_n a_n = 0$, and $\|\cdot\|_{c_0}$ is the supremum norm $\|a\|_{c_0} := \sup_n |a_n|$. Given that $\|\phi(a)\|_L = \|a\|_{c_0}$ for every $a \in c_{00}$ by construction, we have that ϕ can be uniquely extended to a linear isometry $\bar{\phi}: c_0 \rightarrow L$. Since c_0 cannot be embedded in a separable dual Banach space (see [2, Theorem 6.3.7] or [10, Theorem 4]), we can finally conclude that L is not isomorphic to a dual Banach space. \square

Remark 2.17. If (X, τ) is an infinite Hausdorff space, then there exists a sequence $(U_n)_{n \in \mathbb{N}}$ of pairwise disjoint non-empty open subsets of X . To prove this claim, we distinguish two cases. If X has infinitely many isolated points, take a sequence $(x_n)_{n \in \mathbb{N}}$ of pairwise distinct isolated points of X , and note that letting $U_n := \{x_n\}$ for every $n \in \mathbb{N}$ does the job. If X has only finitely many isolated points, then the set \tilde{X} of all accumulation points is an open subset of X (by the Hausdorff assumption); since each neighbourhood of an accumulation point is infinite (again, by the Hausdorff assumption), we can construct recursively a sequence $(U_n)_{n \in \mathbb{N}}$ of pairwise disjoint infinite open subsets of \tilde{X} , which are – a fortiori – open subsets of X . The claim is proved. \blacksquare

Example 2.18. (An e.m.t.m. space whose reference measure is non-separable) Let $(X, \tau, \mathbf{d}_{\text{discr}})$ be the product $X := [0, 1]^c$ of the continuum of intervals together with the product topology τ and the discrete distance $\mathbf{d}_{\text{discr}}$. Since (X, τ) is compact and Hausdorff, we know from Example 2.14 that $(X, \tau, \mathbf{d}_{\text{discr}})$ is an e.m.t. space. Moreover, we equip (X, τ) with the probability Radon measure \mathbf{m} obtained as the product of the one-dimensional Lebesgue measures; to be precise, the product measure of the Lebesgue measures is defined on the product σ -algebra $\bigotimes_{t \in c} \mathcal{B}([0, 1])$, but it extends to a Radon measure \mathbf{m} on $\mathcal{B}(X, \tau)$ thanks to [11, Theorem 7.14.3]. However, the measure \mathbf{m} of the e.m.t.m. space $(X, \tau, \mathbf{d}_{\text{discr}}, \mathbf{m})$ is not separable, see [11, Section 7.14(iv)]. \blacksquare

2.3.3. Rectifiable arcs and path integrals. Let (X, τ, \mathbf{d}) be an e.m.t. space. As in [42, Section 2.2.1], we endow the space $C([0, 1]; (X, \tau))$ of all τ -continuous curves $\gamma: [0, 1] \rightarrow X$ with the compact-open topology τ_C and with the extended distance $\mathbf{d}_C: C([0, 1]; (X, \tau)) \times C([0, 1]; (X, \tau)) \rightarrow [0, +\infty]$, which we define as

$$\mathbf{d}_C(\gamma, \sigma) := \sup_{t \in [0, 1]} \mathbf{d}(\gamma_t, \sigma_t) \quad \text{for every } \gamma, \sigma \in C([0, 1]; (X, \tau)).$$

Then $(C([0, 1]; (X, \tau)), \tau_C, \mathbf{d}_C)$ is an extended metric-topological space [42, Proposition 2.2.2]. We recall that a subbasis for the compact-open topology τ_C is given by the family of sets

$$\{S(K, V) \mid K \subseteq [0, 1] \text{ compact, } V \in \tau\},$$

where we denote $S(K, V) := \{\gamma \in C([0, 1]; (X, \tau)) : \gamma(K) \subseteq V\}$.

Following [42, Section 2.2.2], we denote by Σ the set of all continuous, non-decreasing, surjective maps $\phi: [0, 1] \rightarrow [0, 1]$. Let us consider the following equivalence relation on $C([0, 1]; (X, \tau))$: given any $\gamma, \sigma \in C([0, 1]; (X, \tau))$, we declare that $\gamma \sim \sigma$ if and only if there exist $\phi_\gamma, \phi_\sigma \in \Sigma$ such that

$$\gamma \circ \phi_\gamma = \sigma \circ \phi_\sigma.$$

We endow the associated quotient space $A(X, \tau) := C([0, 1]; (X, \tau)) / \sim$ with the quotient topology τ_A induced by τ_C . The elements of $A(X, \tau)$ are called *arcs*. We denote by $[\gamma] \in A(X, \tau)$ the equivalence class of a curve $\gamma \in C([0, 1]; (X, \tau))$. We define the subspace $A(X, d) \subseteq A(X, \tau)$ as

$$A(X, d) := \{[\gamma] \mid \gamma \in C([0, 1]; (X, d))\}.$$

Letting $d_A: A(X, d) \times A(X, d) \rightarrow [0, +\infty]$ be the extended distance on $A(X, d)$ given by

$$d_A(\gamma, \sigma) := \inf \{d_C(\tilde{\gamma}, \tilde{\sigma}) \mid \tilde{\gamma}, \tilde{\sigma} \in C([0, 1]; (X, \tau)), [\tilde{\gamma}] = \gamma, [\tilde{\sigma}] = \sigma\}$$

for every $\gamma, \sigma \in A(X, d)$, we have that $(A(X, d), \tau_A, d_A)$ is an extended metric-topological space [42, Proposition 2.2.6].

Given a curve $\gamma \in C([0, 1]; (X, d))$ and any $t \in [0, 1]$, the *d-variation* of γ on $[0, t]$ is defined as

$$V_\gamma(t) := \sup \left\{ \sum_{i=1}^n d(\gamma_{t_i}, \gamma_{t_{i-1}}) \mid n \in \mathbb{N}, \{t_i\}_{i=0}^n \subseteq [0, 1], t_0 < t_1 < \dots < t_n \right\} \in [0, +\infty].$$

The *d-length* of γ is defined as $\ell(\gamma) := V_\gamma(1) \in [0, +\infty]$. As in [42, Lemma 2.2.8], we set

$$\text{BVC}([0, 1]; (X, d)) := \{\gamma \in C([0, 1]; (X, d)) \mid \ell(\gamma) < +\infty\}.$$

Since ℓ is τ_C -lower semicontinuous, the space $\text{BVC}([0, 1]; (X, d))$ is an F_σ subset of $C([0, 1]; (X, \tau))$. We say that a curve $\gamma \in \text{BVC}([0, 1]; (X, d))$ has *constant d-speed* if $V_\gamma(t) = \ell(\gamma)t$ holds for every $t \in [0, 1]$. For any given $\gamma \in \text{BVC}([0, 1]; (X, d))$, there exists a unique $\ell(\gamma)$ -Lipschitz curve $R_\gamma \in \text{BVC}([0, 1]; (X, d))$ having constant *d-speed* such that

$$\gamma(t) = R_\gamma(\ell(\gamma)^{-1}V_\gamma(t)) \quad \text{for every } t \in [0, 1],$$

with the convention that $\ell(\gamma)^{-1}V_\gamma(t) = 0$ if $\ell(\gamma) = 0$. Then it holds that $[\gamma] = [R_\gamma]$ and we say that R_γ is the *arc-length parameterisation* of γ . The space of *rectifiable arcs* is given by

$$(2.18) \quad \text{RA}(X, d) := \{[\gamma] \mid \gamma \in \text{BVC}([0, 1]; (X, d))\} \subseteq A(X, d).$$

Then $(\text{RA}(X, d), \tau_A, d_A)$ is an extended metric-topological space. Given $\gamma, \sigma \in \text{BVC}([0, 1]; (X, d))$, we have that $[\gamma] = [\sigma]$ if and only if $R_\gamma = R_\sigma$ [42, Lemma 2.2.11(b)], thus we can unambiguously write R_γ for $\gamma \in \text{RA}(X, d)$. Similarly, we can write γ_0 , γ_1 and $\ell(\gamma)$ for $\gamma \in \text{RA}(X, d)$, and

$$(2.19) \quad \text{RA}(X, d) \ni \gamma \mapsto \ell(\gamma) \quad \text{is } \tau_A\text{-lower semicontinuous,}$$

see [42, Lemma 2.2.11(d)]. Given any $\gamma \in \text{RA}(X, d)$ and a Borel function $f: (X, \tau) \rightarrow \mathbb{R}$ such that $f \circ R_\gamma \in L^1(0, 1)$ (or a Borel function $f: X \rightarrow [0, +\infty]$), the *path integral* of f over γ is given by

$$\int_\gamma f := \ell(\gamma) \int_0^1 f(R_\gamma(t)) dt.$$

When f is bounded, $(\text{RA}(X, d), \tau_A) \ni \gamma \mapsto \int_\gamma f \in \mathbb{R}$ is Borel measurable [42, Theorem 2.2.13(e)].

For any $t \in [0, 1]$, the *arc-length evaluation map* $\hat{e}_t: \text{RA}(X, \mathbf{d}) \rightarrow X$ at time t is defined as

$$\hat{e}_t(\gamma) := R_\gamma(t) \quad \text{for every } \gamma \in \text{RA}(X, \mathbf{d}).$$

We also introduce the *arc-length evaluation map* $\hat{e}: \text{RA}(X, \mathbf{d}) \times [0, 1] \rightarrow X$, given by

$$(2.20) \quad \hat{e}(\gamma, t) := \hat{e}_t(\gamma) = R_\gamma(t) \quad \text{for every } \gamma \in \text{RA}(X, \mathbf{d}) \text{ and } t \in [0, 1].$$

Let us now prove some technical results, concerning the measurability properties of \hat{e} and of a map that describes the derivative of a continuous Lipschitz function along rectifiable arcs, which we will use in Section 5.3.

Lemma 2.19. *Let (X, τ, \mathbf{d}) be an e.m.t. space. Then it holds that $\hat{e}: \text{RA}(X, \mathbf{d}) \times [0, 1] \rightarrow X$ is universally Lusin measurable (when $\text{RA}(X, \mathbf{d}) \times [0, 1]$ is equipped with the product topology).*

Proof. First of all, we claim that if $((\gamma^i, t^i))_{i \in I} \subseteq \text{RA}(X, \mathbf{d}) \times [0, 1]$ is a given net converging to $(\gamma, t) \in \text{RA}(X, \mathbf{d}) \times [0, 1]$ such that $\lim_{i \in I} \ell(\gamma^i) = \ell(\gamma)$, then

$$(2.21) \quad \lim_{i \in I} \hat{e}(\gamma^i, t^i) = \hat{e}(\gamma, t).$$

To prove it, fix a neighbourhood $V \in \tau$ of $\hat{e}(\gamma, t)$. By the complete regularity of τ , we can find a neighbourhood $U \in \tau$ of $R_\gamma(t) = \hat{e}(\gamma, t)$ whose τ -closure \bar{U} is contained in V . Since the curve $R_\gamma: [0, 1] \rightarrow X$ is τ -continuous and $\lim_{i \in I} t^i = t$, there exists $i_0 \in I$ such that $R_{\gamma^i}(t^i) \in U$ for every $i \in I$ with $i_0 \preceq i$. Letting K denote the closure of $\{t^i: i \in I, i_0 \preceq i\}$, which is a compact subset of $[0, 1]$, we have that $t \in K$ and $R_{\gamma^i}(s) \in \bar{U} \subseteq V$ for every $s \in K$, thus $S(K, V) \in \tau_C$ is a neighbourhood of R_γ . Since $\lim_{i \in I} R_{\gamma^i} = R_\gamma$ in $(C([0, 1]; (X, \tau)), \tau_C)$ by [42, Theorem 2.2.13(a)], we deduce that there exists $i_1 \in I$ with $i_0 \preceq i_1$ and $R_{\gamma^i} \in S(K, V)$ for every $i \in I$ with $i_1 \preceq i$. It follows that $\hat{e}(\gamma^i, t^i) = R_{\gamma^i}(t^i) \in V$ for every $i \in I$ with $i_1 \preceq i$, which shows that (2.21) holds.

Now let $\mu \in \mathcal{M}_+(\text{RA}(X, \mathbf{d}) \times [0, 1])$ be fixed. By (2.19), the map $\text{RA}(X, \mathbf{d}) \times [0, 1] \ni (\gamma, t) \mapsto \ell(\gamma)$ is lower semicontinuous, thus it is Lusin μ -measurable by Remark 2.5. Hence, for any $\varepsilon > 0$ we can find a compact set $\mathcal{K}_\varepsilon \subseteq \text{RA}(X, \mathbf{d}) \times [0, 1]$ such that $\mathcal{K}_\varepsilon \ni (\gamma, t) \mapsto \ell(\gamma)$ is continuous. The first part of the proof then gives that $\hat{e}|_{\mathcal{K}_\varepsilon}$ is continuous, so that \hat{e} is universally Lusin measurable. \square

Corollary 2.20. *Let (X, τ, \mathbf{d}) be an e.m.t. space. Let $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ be given. We define the function $D_f: \text{RA}(X, \mathbf{d}) \times [0, 1] \rightarrow \mathbb{R}$ as*

$$D_f(\gamma, t) := \limsup_{h \rightarrow 0} \frac{f(R_\gamma(t+h)) - f(R_\gamma(t))}{h} \quad \text{for every } \gamma \in \text{RA}(X, \mathbf{d}) \text{ and } t \in [0, 1].$$

Then D_f is universally Lusin measurable.

Proof. Note that $D_f(\gamma, t) = \lim_{n \in \mathbb{N} \rightarrow \infty} D_f^n(\gamma, t)$ for every $(\gamma, t) \in \text{RA}(X, \mathbf{d}) \times [0, 1]$, where we set

$$D_f^n(\gamma, t) := \sup \left\{ \frac{f(R_\gamma(t+h)) - f(R_\gamma(t))}{h} \mid h \in (\mathbb{Q} \setminus \{0\}) \cap (-1/n, 1/n) \right\}$$

for brevity. Fix $n \in \mathbb{N}$. Let us enumerate the elements of $(\mathbb{Q} \setminus \{0\}) \cap (-1/n, 1/n)$ as $(q_i)_{i \in \mathbb{N}}$. Then

$$D_f^n(\gamma, t) = \lim_{k \rightarrow \infty} \max \left\{ \frac{f(R_\gamma(t+q_i)) - f(R_\gamma(t))}{q_i} \mid i = 1, \dots, k \right\}$$

for all $(\gamma, t) \in \text{RA}(X, \mathbf{d}) \times [0, 1]$. Since the map $\hat{\mathbf{e}}$ is universally Lusin measurable by Lemma 2.19, one can easily deduce that each function $(\gamma, t) \mapsto \max_{i \leq k} (f(R_\gamma(t + q_i)) - f(R_\gamma(t))) / q_i$ is universally Lusin measurable. By taking Remark 2.5 into account, we can finally conclude that D_f is universally Lusin measurable. \square

Given $\gamma \in \text{RA}(X, \mathbf{d})$ and $f \in \text{Lip}_b(X, \tau, \mathbf{d})$, we have that $f \circ R_\gamma: [0, 1] \rightarrow \mathbb{R}$ is a Lipschitz function, thus in particular it is \mathcal{L}^1 -a.e. differentiable. Therefore, it holds that

$$(2.22) \quad D_f(\gamma, t) = (f \circ R_\gamma)'(t) \quad \text{for } \mathcal{L}^1\text{-a.e. } t \in [0, 1].$$

In particular, it holds that

$$(2.23) \quad |D_f(\gamma, t)| \leq \ell(\gamma)(\text{lip}_{\mathbf{d}}(f) \circ R_\gamma)(t) \quad \text{for } \mathcal{L}^1\text{-a.e. } t \in [0, 1].$$

2.3.4. Uniform structure of an extended metric-topological space. We assume the reader is familiar with the basics of the theory of uniform spaces, for which we refer e.g. to [14, 15]. It is well known that every completely regular topology is induced by a uniform structure (in fact, completely regular topological spaces are exactly the uniformisable topological spaces). In the setting of e.m.t. spaces, we make a canonical choice of such a uniform structure:

Definition 2.21. (Canonical uniform structure of an e.m.t. space) Let (X, τ, \mathbf{d}) be an e.m.t. space. Then we define the *canonical uniformity* of (X, τ, \mathbf{d}) as the uniform structure $\mathfrak{U}_{\tau, \mathbf{d}}$ on X that is induced by the family of semidistances $\{\delta_f: f \in \text{Lip}_{b,1}(X, \tau, \mathbf{d})\}$, which are defined as

$$\delta_f(x, y) := |f(x) - f(y)| \quad \text{for every } f \in \text{Lip}_{b,1}(X, \tau, \mathbf{d}) \text{ and } x, y \in X.$$

It can be readily checked that the following properties are verified:

- The topology induced by $\mathfrak{U}_{\tau, \mathbf{d}}$ coincides with τ .
- The topology τ is metrisable if and only if $\mathfrak{U}_{\tau, \mathbf{d}}$ has a countable basis of entourages.

Moreover, we denote by $\mathfrak{B}_{\tau, \mathbf{d}} \subseteq \mathfrak{U}_{\tau, \mathbf{d}}$ the family of all *open symmetric entourages* of $\mathfrak{U}_{\tau, \mathbf{d}}$, i.e.

$$\mathfrak{B}_{\tau, \mathbf{d}} := \{\mathcal{U} \in \mathfrak{U}_{\tau, \mathbf{d}} \cap (\tau \times \tau) \mid (y, x) \in \mathcal{U} \text{ for every } (x, y) \in \mathcal{U}\}.$$

It holds that $\mathfrak{B}_{\tau, \mathbf{d}}$ is a basis of entourages for $\mathfrak{U}_{\tau, \mathbf{d}}$. In the case where τ is metrisable, it is possible to find a countable basis of entourages for $\mathfrak{U}_{\tau, \mathbf{d}}$ consisting of elements of $\mathfrak{B}_{\tau, \mathbf{d}}$.

Remark 2.22. Let $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ and $\mathcal{U} \in \mathfrak{B}_{\tau, \mathbf{d}}$ be given. Then we claim that

$$\text{Lip}(f, \mathcal{U}[\cdot], \mathbf{d}): X \rightarrow [0, \text{Lip}(f, \mathbf{d})] \quad \text{is } \tau\text{-lower semicontinuous,}$$

where $\mathcal{U}[x] := \{y \in X: (x, y) \in \mathcal{U}\}$ for all $x \in X$. Indeed, $\mathcal{U}[y] \cap \mathcal{U}[z] \in \tau$ for every $y, z \in X$ and

$$\text{Lip}(f, \mathcal{U}[x], \mathbf{d}) = \sup \left\{ \frac{|f(y) - f(z)|}{\mathbf{d}(y, z)} \mid y, z \in X, y \neq z, x \in \mathcal{U}[y] \cap \mathcal{U}[z] \right\}$$

for every $x \in X$, so that the function $\text{Lip}(f, \mathcal{U}[\cdot], \mathbf{d})$ is τ -lower semicontinuous thanks to Remark 2.3. \blacksquare

Let us now discuss how the canonical uniform structure behaves under restriction of the e.m.t. space. Let (X, τ, \mathbf{d}) be a given e.m.t. space and fix $E \in \mathcal{B}(X, \tau)$. Consider the restricted e.m.t. space $(E, \tau_E, \mathbf{d}_E)$ (as in (2.9)). Then it holds that

$$(2.24) \quad \mathfrak{U}_{\tau_E, \mathbf{d}_E} = \{\mathcal{U}|_{E \times E} \mid \mathcal{U} \in \mathfrak{U}_{\tau, \mathbf{d}}\}, \quad \mathfrak{B}_{\tau_E, \mathbf{d}_E} = \{\mathcal{U}|_{E \times E} \mid \mathcal{U} \in \mathfrak{B}_{\tau, \mathbf{d}}\}.$$

The first identity follows easily from the definition of canonical uniformity. The second identity follows from $\tau_{E \times E} = \tau_E \times \tau_E$ and from the fact that $\mathcal{U} \cap \mathcal{U}^{-1} \in \mathfrak{B}_{\tau, \mathbf{d}}$ for every $\mathcal{U} \in \mathfrak{U}_{\tau, \mathbf{d}} \cap (\tau \times \tau)$, where we set $\mathcal{U}^{-1} := \{(y, x) : (x, y) \in \mathcal{U}\}$.

2.4. Sobolev spaces $H^{1,p}$ via relaxation. The first notion of Sobolev space over an e.m.t.m. space we consider is the one obtained by *relaxation*, which was introduced in [42, Section 3.1] as a generalisation of [16, 6, 5]. A function $f \in L^p(\mathbf{m})$ is declared to be in the Sobolev space $H^{1,p}(\mathbb{X})$ if it is the $L^p(\mathbf{m})$ -limit of a sequence $(f_n)_n$ of functions in $\text{Lip}_b(X, \tau, \mathbf{d})$ whose asymptotic slopes $(\text{lip}_{\mathbf{d}}(f_n))_n$ form a bounded sequence in $L^p(\mathbf{m})$. Namely, following [42, Definitions 3.1.1 and 3.1.3]:

Definition 2.23 (The Sobolev space $H^{1,p}(\mathbb{X})$). Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $p \in (1, \infty)$. Then we define the *Cheeger p -energy functional* $\mathcal{E}_p: L^p(\mathbf{m}) \rightarrow [0, +\infty]$ of \mathbb{X} as

$$\mathcal{E}_p(f) := \inf \left\{ \liminf_{n \rightarrow \infty} \frac{1}{p} \int \text{lip}_{\mathbf{d}}(f_n)^p \, d\mathbf{m} \mid (f_n)_n \subseteq \text{Lip}_b(X, \tau, \mathbf{d}), f_n \rightarrow f \text{ in } L^p(\mathbf{m}) \right\}$$

for all $f \in L^p(\mathbf{m})$. Then we define the *Sobolev space* $H^{1,p}(\mathbb{X})$ as the finiteness domain of \mathcal{E}_p , i.e.

$$H^{1,p}(\mathbb{X}) := \{f \in L^p(\mathbf{m}) \mid \mathcal{E}_p(f) < +\infty\}.$$

The Cheeger p -energy functional is convex, p -homogeneous and $L^p(\mathbf{m})$ -lower semi-continuous. The vector subspace $H^{1,p}(\mathbb{X})$ of $L^p(\mathbf{m})$ is a Banach space with respect to the Sobolev norm

$$\|f\|_{H^{1,p}(\mathbb{X})} := (\|f\|_{L^p(\mathbf{m})}^p + p \mathcal{E}_p(f))^{1/p} \quad \text{for every } f \in H^{1,p}(\mathbb{X}).$$

Also, \mathcal{E}_p admits an integral representation, in terms of *relaxed slopes* [42, Definition 3.1.5]:

Definition 2.24. (Relaxed slope) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $p \in (1, \infty)$. Let $f \in L^p(\mathbf{m})$ be given. Then we say that a function $G \in L^p(\mathbf{m})^+$ is a *p -relaxed slope* of f if there exist a sequence $(f_n)_n \subseteq \text{Lip}_b(X, \tau, \mathbf{d})$ and a function $\tilde{G} \in L^p(\mathbf{m})^+$ such that the following hold:

- i) $f_n \rightarrow f$ strongly in $L^p(\mathbf{m})$,
- ii) $\text{lip}_{\mathbf{d}}(f_n) \rightharpoonup \tilde{G}$ weakly in $L^p(\mathbf{m})$,
- iii) $\tilde{G} \leq G$ in the \mathbf{m} -a.e. sense.

Below, we collect many properties and calculus rules for p -relaxed slopes (see [42, Section 3.1.1]).

- The set of all p -relaxed slopes of a given $f \in H^{1,p}(\mathbb{X})$ is a closed sublattice of $L^p(\mathbf{m})$. Its (unique) \mathbf{m} -a.e. minimal element is denoted by $|Df|_H \in L^p(\mathbf{m})^+$ and is called the *minimal p -relaxed slope* of f .
- The Cheeger p -energy functional can be represented as

$$\mathcal{E}_p(f) = \frac{1}{p} \int |Df|_H^p \, d\mathbf{m} \quad \text{for every } f \in H^{1,p}(\mathbb{X}).$$

- Given any $f \in H^{1,p}(\mathbb{X})$, there exists a sequence $(f_n)_n \subseteq \text{Lip}_b(X, \tau, \mathbf{d})$ such that $f_n \rightarrow f$ and $\text{lip}_d(f_n) \rightarrow |Df|_H$ strongly in $L^p(\mathbf{m})$.
- $\text{Lip}_b(X, \tau, \mathbf{d}) \subseteq H^{1,p}(\mathbb{X})$, and $|Df|_H \leq \text{lip}_d(f)$ holds \mathbf{m} -a.e. for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$.
- We have that $|D(f+g)|_H \leq |Df|_H + |Dg|_H$ and $|D(\lambda f)|_H = |\lambda| |Df|_H$ hold \mathbf{m} -a.e. for every $f, g \in H^{1,p}(\mathbb{X})$ and $\lambda \in \mathbb{R}$.
- LOCALITY PROPERTY. If $f \in H^{1,p}(\mathbb{X})$ and $N \subseteq \mathbb{R}$ is a Borel set with $\mathcal{L}^1(N) = 0$, then

$$|Df|_H = 0 \quad \text{holds } \mathbf{m}\text{-a.e. on } f^{-1}(N).$$

In particular, $|Df|_H = |Dg|_H$ holds \mathbf{m} -a.e. on $\{f = g\}$ for every $f, g \in H^{1,p}(\mathbb{X})$.

- CHAIN RULE. If $f \in H^{1,p}(\mathbb{X})$ and $\phi \in \text{Lip}_b(\mathbb{R})$, then $\phi \circ f \in H^{1,p}(\mathbb{X})$ and

$$|D(\phi \circ f)|_H \leq |\phi'| \circ f |Df|_H \quad \text{holds } \mathbf{m}\text{-a.e. on } X.$$

- LEIBNIZ RULE. If $f, g \in H^{1,p}(\mathbb{X}) \cap L^\infty(\mathbf{m})$ are given, then $fg \in H^{1,p}(\mathbb{X})$ and

$$|D(fg)|_H \leq |f| |Dg|_H + |g| |Df|_H \quad \text{holds } \mathbf{m}\text{-a.e. on } X.$$

Minimal p -relaxed slopes are induced by a linear *differential* operator $d: H^{1,p}(\mathbb{X}) \rightarrow L^p(T^*\mathbb{X})$, where $L^p(T^*\mathbb{X})$ is a distinguished $L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module, called the *p-cotangent module*:

Theorem 2.25. (Cotangent module) *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $p \in (1, \infty)$. Then there exist an $L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module $L^p(T^*\mathbb{X})$ (called the *p-cotangent module*) and a linear operator $d: H^{1,p}(\mathbb{X}) \rightarrow L^p(T^*\mathbb{X})$ (called the *differential*) such that:*

- $|df| = |Df|_H$ for every $f \in H^{1,p}(\mathbb{X})$.
- The $L^\infty(\mathbf{m})$ -linear span of $\{df: f \in H^{1,p}(\mathbb{X})\}$ is dense in $L^p(T^*\mathbb{X})$.

The pair $(L^p(T^*\mathbb{X}), d)$ is unique up to a unique isomorphism: for any (\mathcal{M}, \tilde{d}) having the same properties, there exists a unique isomorphism of $L^p(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -modules $\Phi: L^p(T^*\mathbb{X}) \rightarrow \mathcal{M}$ such that

$$\begin{array}{ccc} H^{1,p}(\mathbb{X}) & \xrightarrow{d} & L^p(T^*\mathbb{X}) \\ & \searrow \tilde{d} & \downarrow \Phi \\ & & \mathcal{M} \end{array}$$

is a commutative diagram. Moreover, the differential d satisfies the following *Leibniz rule*:

$$(2.25) \quad d(fg) = f \cdot dg + g \cdot df \quad \text{for every } f, g \in H^{1,p}(\mathbb{X}) \cap L^\infty(\mathbf{m}).$$

Proof. This construction is due to Gigli [23]. The existence and uniqueness of $(L^p(T^*\mathbb{X}), d)$ can be proved by repeating verbatim the proof of [23, Section 2.2.1] or [22, Theorem/Definition 2.8] (see also [25, Theorem 4.1.1], or [24, Theorem 3.2] for the case $p \neq 2$). Alternatively, one can apply [38, Theorem 3.19]. The Leibniz rule (2.25) can be proved by arguing as in [23, Corollary 2.2.8] (or as in [22, Proposition 2.12], or as in [25, Theorem 4.1.4], or as in [24, Proposition 3.5]). \square

Following [23, Definition 2.3.1], we then introduce the *q-tangent module* of \mathbb{X} by duality:

Definition 2.26. (Tangent module) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $p, q \in (1, \infty)$ be conjugate exponents. Then we define the q -tangent module $L^q(T\mathbb{X})$ of \mathbb{X} as

$$L^q(T\mathbb{X}) := L^p(T^*\mathbb{X})^*.$$

Recall that $L^q(T\mathbb{X})$, when regarded as a Banach space, can be identified with the dual Banach space $L^p(T^*\mathbb{X})'$ through the isomorphism

$$(2.26) \quad \mathbf{I}_{p,\mathbb{X}} := \text{INT}_{L^p(T^*\mathbb{X})}: L^q(T\mathbb{X}) \rightarrow L^p(T^*\mathbb{X})'$$

defined in (2.6). The following result can be proved by suitably adapting [23, Proposition 1.4.8] (or by applying [38, Proposition 3.20]):

Proposition 2.27. Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $p, q \in (1, \infty)$ be conjugate exponents. Assume that $\varphi: H^{1,p}(\mathbb{X}) \rightarrow L^1(\mathbf{m})$ is a linear map with the following property: there exists a function $G \in L^q(\mathbf{m})^+$ such that $|\varphi(f)| \leq G|Df|_H$ holds for every $f \in H^{1,p}(\mathbb{X})$. Then there exists a unique vector field $v_\varphi \in L^q(T\mathbb{X})$ such that

$$\begin{array}{ccc} H^{1,p}(\mathbb{X}) & \xrightarrow{\varphi} & L^1(\mathbf{m}) \\ \mathbf{d} \downarrow & \nearrow v_\varphi & \\ L^p(T^*\mathbb{X}) & & \end{array}$$

is a commutative diagram. Moreover, it holds that $|v_\varphi| \leq G$.

Exactly as in [23, Section 2.3.1], the tangent module $L^q(T\mathbb{X})$ can be equivalently characterised in terms of a suitable notion of derivation, which we call ‘Sobolev derivation’ (in order to make a distinction with the notion of ‘Lipschitz derivation’, which we will introduce in Section 4). Namely:

Definition 2.28. (Sobolev derivation) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $q \in (1, \infty)$. Then by a *Sobolev derivation* (of exponent q) on \mathbb{X} we mean a linear map $\delta: H^{1,p}(\mathbb{X}) \rightarrow L^1(\mathbf{m})$ such that the following conditions hold:

- i) $\delta(fg) = f\delta(g) + g\delta(f)$ for every $f, g \in H^{1,p}(\mathbb{X}) \cap L^\infty(\mathbf{m})$.
- ii) There exists a function $G \in L^q(\mathbf{m})^+$ such that $|\delta(f)| \leq G|Df|_H$ for every $f \in H^{1,p}(\mathbb{X})$.

We denote by $L_{\text{Sob}}^q(T\mathbb{X})$ the set of all Sobolev derivations of exponent q on \mathbb{X} .

The above definition is adapted from [23, Definition 2.3.2]. To any derivation $\delta \in L_{\text{Sob}}^q(T\mathbb{X})$, we associate the function $|\delta| \in L^q(\mathbf{m})^+$ given by

$$|\delta| := \bigwedge \left\{ G \in L^q(\mathbf{m})^+ \mid |\delta(f)| \leq G|Df|_H \text{ for every } f \in H^{1,p}(\mathbb{X}) \right\}.$$

Note that $|\delta(f)| \leq |\delta||Df|_H$ for all $f \in H^{1,p}(\mathbb{X})$. It is straightforward to check that $(L_{\text{Sob}}^q(T\mathbb{X}), |\cdot|)$ is an $L^q(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module. The latter can be identified with the tangent module $L^q(T\mathbb{X})$, as the next result (which is essentially taken from [23, Theorem 2.3.3]) shows:

Proposition 2.29. (Identification between $L^q(T\mathbb{X})$ and $L_{\text{Sob}}^q(T\mathbb{X})$) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $q \in (1, \infty)$. Then for any $v \in L^q(T\mathbb{X})$ we have that $v \circ \mathbf{d}: H^{1,p}(\mathbb{X}) \rightarrow L^1(\mathbf{m})$ is an element of $L_{\text{Sob}}^q(T\mathbb{X})$. Moreover, the resulting map $\Phi: L^q(T\mathbb{X}) \rightarrow L_{\text{Sob}}^q(T\mathbb{X})$ is an isomorphism of $L^q(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -modules.

Proof. Let $v \in L^q(T\mathbb{X})$ be a given vector field. Then $v \circ d: H^{1,p}(\mathbb{X}) \rightarrow L^1(\mathfrak{m})$ is linear and

$$(v \circ d)(fg) = d(fg)(v) = f dg(v) + g df(v) = f(v \circ d)(g) + g(v \circ d)(f)$$

for every $f, g \in H^{1,p}(\mathbb{X}) \cap L^\infty(\mathfrak{m})$ by (2.25). Moreover, $|(v \circ d)(f)| = |df(v)| \leq |Df|_H |v|$ for every $f \in H^{1,p}(\mathbb{X})$. This gives $v \circ d \in L^q_{\text{Sob}}(T\mathbb{X})$ and $|v \circ d| \leq |v|$. It follows that $\Phi: L^q(T\mathbb{X}) \rightarrow L^q_{\text{Sob}}(T\mathbb{X})$ is a linear map such that $|\Phi(v)| \leq |v|$ for every $v \in L^q(T\mathbb{X})$. Since we have that

$$\Phi(h \cdot v)(f) = ((h \cdot v) \circ d)(f) = df(h \cdot v) = h df(v) = h \Phi(v)(f) = (h \cdot \Phi(v))(f)$$

for every $h \in L^\infty(\mathfrak{m})$ and $f \in H^{1,p}(\mathbb{X})$, we deduce that Φ is $L^\infty(\mathfrak{m})$ -linear. To conclude, it remains to check that for any $\delta \in L^q_{\text{Sob}}(T\mathbb{X})$ there exists $v_\delta \in L^q(T\mathbb{X})$ such that $\Phi(v_\delta) = \delta$ and $|v_\delta| \leq |\delta|$. Since $\delta: H^{1,p}(\mathbb{X}) \rightarrow L^1(\mathfrak{m})$ is linear and $|\delta(f)| \leq |\delta| |Df|_H$ for every $f \in H^{1,p}(\mathbb{X})$, we deduce from Proposition 2.27 that there exists (a unique) $v_\delta \in L^q(T\mathbb{X})$ such that $\delta = v_\delta \circ d = \Phi(v_\delta)$, and it holds that $|v_\delta| \leq |\delta|$. All in all, the statement is achieved. \square

2.5. Sobolev spaces $B^{1,p}$ via test plans. The second notion of Sobolev space over an e.m.t.m. space we consider is the one obtained by investigating the behaviour of functions along suitably chosen curves. The relevant object here is that of a \mathcal{T}_q -test plan (see Definition 2.30 below), which was introduced in [42, Section 4.2] after [3, 5, 6]. A function $f \in L^p(\mathfrak{m})$ is declared to be in the Sobolev space $B^{1,p}(\mathbb{X})$ if it has a p -integrable \mathcal{T}_q -weak upper gradient (where p, q are conjugate exponents), i.e. a function satisfying the *upper gradient* inequality [16, 33, 36] along π -a.e. curve, for every \mathcal{T}_q -test plan π . Our notation ' $B^{1,p}$ ' is different from the one of [42], where ' $W^{1,p}$ ' is used instead. The reason is that in this paper we prefer to denote by $W^{1,p}(\mathbb{X})$ the Sobolev space that we will define through an integration-by-parts formula in Section 5.1, which comes with a notion of 'weak derivative'. In analogy with [7], the notation $B^{1,p}(\mathbb{X})$ is chosen to remind the resemblance to Beppo Levi's approach to weakly differentiable functions.

Let $\mathbb{X} = (X, \tau, d, \mathfrak{m})$ be an e.m.t.m. space. According to [42, Definition 4.2.1], a *dynamic plan* on \mathbb{X} is a Radon measure $\pi \in \mathcal{M}_+(\text{RA}(X, d), \tau_A)$ satisfying

$$\int \ell(\gamma) d\pi(\gamma) < +\infty.$$

The *barycenter* of π is defined as the unique Radon measure $\mu_\pi \in \mathcal{M}_+(X, \tau)$ such that

$$\int f d\mu_\pi = \int \left(\int_\gamma f \right) d\pi(\gamma) \quad \text{for every bounded Borel function } f: (X, \tau) \rightarrow \mathbb{R}.$$

Moreover, we say that π has q -barycenter, for some $q \in (1, \infty)$, if it holds that $\mu_\pi \ll \mathfrak{m}$ and

$$(2.27) \quad h_\pi := \frac{d\mu_\pi}{d\mathfrak{m}} \in L^q(\mathfrak{m})^+.$$

The following definition is taken from [42, Definition 5.1.1]:

Definition 2.30. (\mathcal{T}_q -test plan) Let $\mathbb{X} = (X, \tau, d, \mathfrak{m})$ be an e.m.t.m. space and $q \in (1, \infty)$. Then a dynamic plan π on \mathbb{X} is said to be a \mathcal{T}_q -test plan provided it has q -barycenter and it holds that

$$(\hat{e}_0)_\# \pi, (\hat{e}_1)_\# \pi \ll \mathfrak{m}, \quad \frac{d(\hat{e}_0)_\# \pi}{d\mathfrak{m}}, \frac{d(\hat{e}_1)_\# \pi}{d\mathfrak{m}} \in L^q(\mathfrak{m})^+.$$

We denote by $\mathcal{T}_q(\mathbb{X})$ the set of all \mathcal{T}_q -test plans on \mathbb{X} .

The corresponding notion of weak upper gradient is the following (from [42, Definition 5.1.4]):

Definition 2.31. (\mathcal{T}_q -weak upper gradient) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $q \in (1, \infty)$. Let $f: X \rightarrow \mathbb{R}$ and $G: X \rightarrow [0, +\infty)$ be given τ -Borel functions. Then we say that G is a \mathcal{T}_q -weak upper gradient of f provided for any $\pi \in \mathcal{T}_q(\mathbb{X})$ it holds that

$$(2.28) \quad |f(\gamma_1) - f(\gamma_0)| \leq \int_{\gamma} G < +\infty \quad \text{for } \pi\text{-a.e. } \gamma \in \text{RA}(X, \mathbf{d}).$$

If $f, \tilde{f}: X \rightarrow \mathbb{R}$ are τ -Borel functions satisfying $f = \tilde{f}$ in the \mathbf{m} -a.e. sense, then f and \tilde{f} have the same \mathcal{T}_q -weak upper gradients. Hence, we can unambiguously say that a function $f \in L^1(\mathbf{m})$ has a \mathcal{T}_q -weak upper gradient.

Lemma 2.32. Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $p, q \in (1, \infty)$ be conjugate exponents. Let $f: X \rightarrow \mathbb{R}$ and $G: X \rightarrow [0, +\infty)$ be given τ -Borel functions with $\int G^p \, \mathbf{d}\mathbf{m} < +\infty$. Then the function G is a \mathcal{T}_q -weak upper gradient of f if and only if

$$(2.29) \quad \int f(\gamma_1) - f(\gamma_0) \, \mathbf{d}\pi(\gamma) \leq \int G \, h_{\pi} \, \mathbf{d}\mathbf{m} \quad \text{for every } \pi \in \mathcal{T}_q(\mathbb{X}).$$

Proof. Necessity can be shown by integrating (2.28). For sufficiency, we argue by contradiction: suppose that (2.29) holds, but G is not a \mathcal{T}_q -weak upper gradient of f . Then there exist a \mathcal{T}_q -test plan $\pi \in \mathcal{T}_q(\mathbb{X})$, a Borel set $\Gamma \subseteq \text{RA}(X, \mathbf{d})$ with $\pi(\Gamma) > 0$ and some $\varepsilon > 0$ such that

$$(2.30) \quad |f(\gamma_1) - f(\gamma_0)| \geq \varepsilon + \int_{\gamma} G \quad \text{for every } \gamma \in \Gamma.$$

Denote $\Gamma_+ := \{\gamma \in \Gamma: f(\gamma_1) \geq f(\gamma_0)\}$ and $\Gamma_- := \Gamma \setminus \Gamma_+$. Now let us consider $\pi_+ := \pi|_{\Gamma_+} \in \mathcal{T}_q(\mathbb{X})$ and $\pi_- := \text{Rev}_{\#}(\pi|_{\Gamma_-}) \in \mathcal{T}_q(\mathbb{X})$, where $\text{Rev}: \text{RA}(X, \mathbf{d}) \rightarrow \text{RA}(X, \mathbf{d})$ denotes the map sending a rectifiable arc $[\gamma]$ to the \sim -equivalence class of the curve $[0, 1] \ni t \mapsto \gamma_{1-t} \in X$. We deduce that

$$\begin{aligned} \varepsilon \pi(\Gamma_{\pm}) + \int G \, h_{\pi_{\pm}} \, \mathbf{d}\mathbf{m} &= \int \left(\varepsilon + \int_{\gamma} G \right) \mathbf{d}\pi_{\pm}(\gamma) \\ &\stackrel{(2.30)}{\leq} \int f(\gamma_1) - f(\gamma_0) \, \mathbf{d}\pi_{\pm}(\gamma) \stackrel{(2.29)}{\leq} \int G \, h_{\pi_{\pm}} \, \mathbf{d}\mathbf{m}. \end{aligned}$$

Either $\pi(\Gamma_+) > 0$ or $\pi(\Gamma_-) > 0$, thus the above estimates lead to a contradiction. \square

If $f \in L^1(\mathbf{m})$ has a \mathcal{T}_q -weak upper gradient in $L^p(\mathbf{m})$ (where $p \in (1, \infty)$ denotes the conjugate exponent of q), then there exists a unique function $|Df|_B \in L^p(\mathbf{m})^+$, which we call the *minimal \mathcal{T}_q -weak upper gradient* of f , such that the following hold:

- i) $|Df|_B$ has a representative $G_f: X \rightarrow [0, +\infty)$ that is a \mathcal{T}_q -weak upper gradient of f .
- ii) If G is a \mathcal{T}_q -weak upper gradient of f , then $|Df|_B \leq G$ holds \mathbf{m} -a.e. in X .

See [42, paragraph after Definition 5.1.23]. Consequently, the following definition (which is taken from [42, Definition 5.1.24]) is well posed:

Definition 2.33. (The Sobolev space $B^{1,p}(\mathbb{X})$) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $p, q \in (1, \infty)$ be conjugate exponents. Then we define the

Sobolev space $B^{1,p}(\mathbb{X})$ as the set of all functions $f \in L^p(\mathfrak{m})$ having a \mathcal{T}_q -weak upper gradient in $L^p(\mathfrak{m})$. Moreover, we define

$$\|f\|_{B^{1,p}(\mathbb{X})} := (\|f\|_{L^p(\mathfrak{m})}^p + \| |Df|_B \|_{L^p(\mathfrak{m})}^p)^{1/p} \quad \text{for every } f \in B^{1,p}(\mathbb{X}).$$

It holds that $(B^{1,p}(\mathbb{X}), \|\cdot\|_{B^{1,p}(\mathbb{X})})$ is a Banach space. In the setting of \mathbf{d} -complete e.m.t.m. spaces, the full equivalence of $H^{1,p}$ and $W^{1,p}$ was obtained by Savaré in [42, Theorem 5.2.7] (see Theorem 2.34 below for the precise statement), thus generalising previous results for metric-measure spaces [5, 6, 16, 47]. See also [7, 20, 37] for other related equivalence results.

Theorem 2.34. ($H^{1,p} = B^{1,p}$ on complete e.m.t.m. spaces) *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathfrak{m})$ be an e.m.t.m. space such that (X, \mathbf{d}) is a complete extended metric space. Let $p \in (1, \infty)$ be given. Then*

$$H^{1,p}(\mathbb{X}) = B^{1,p}(\mathbb{X}).$$

Moreover, it holds that $|Df|_B = |Df|_H$ for every $f \in H^{1,p}(\mathbb{X})$.

The completeness assumption in Theorem 2.34 cannot be dropped. For instance, let us consider the space $(-1, 1) \setminus \{0\}$ equipped with the restriction of the Euclidean distance, its induced topology and the restriction of the one-dimensional Lebesgue measure. It can be readily checked that the function $\mathbb{1}_{(0,1)}$ is $B^{1,p}$ -Sobolev with null minimal \mathcal{T}_q -weak upper gradient, but not $H^{1,p}$ -Sobolev.

3. Extensions of τ -continuous \mathbf{d} -Lipschitz functions

A fundamental tool in metric geometry is the *McShane–Whitney extension theorem*, which ensures that every real-valued Lipschitz function defined on some subset of a metric space can be extended to a Lipschitz function on the whole metric space, also preserving the Lipschitz constant. In the setting of extended metric-topological spaces, we rather need an extension theorem for τ -continuous \mathbf{d} -Lipschitz functions for which both the τ -continuity and the \mathbf{d} -Lipschitz conditions are preserved. The McShane–Whitney extension theorem does not accomplish this goal, as we are going to illustrate: it states that if $f: E \rightarrow \mathbb{R}$ is a Lipschitz function with Lipschitz constant L defined on a subset E of some metric space (X, \mathbf{d}) , then by letting

$$(3.1) \quad f^\wedge(x) := \sup_{y \in E} (f(y) - L\mathbf{d}(x, y)), \quad f^\vee(x) := \inf_{y \in E} (f(y) + L\mathbf{d}(x, y))$$

for every $x \in X$ we obtain two Lipschitz functions $f^\wedge, f^\vee: X \rightarrow \mathbb{R}$ with Lipschitz constant L that extend f ; moreover, every Lipschitz extension $\bar{f}: X \rightarrow \mathbb{R}$ of f with Lipschitz constant L satisfies $f^\wedge \leq \bar{f} \leq f^\vee$. However, if in addition X is equipped with a topology τ for which \mathbf{d} is $\tau \times \tau$ -lower semicontinuous, then it is clear that the functions f^\wedge, f^\vee defined in (3.1) are typically not (semi)continuous with respect to τ (unless e.g. τ is exactly the topology induced by \mathbf{d}), since f^\wedge is a supremum of τ -upper semicontinuous functions, whereas f^\vee is an infimum of τ -lower semicontinuous functions.

Conversely, the extension results obtained by Matoušková in [39] are fit for our purposes:

Theorem 3.1. (Extension result) *Let (X, τ, \mathbf{d}) be an e.m.t. space with (X, τ) normal. Assume*

$$(3.2) \quad \bar{B}_r^{\mathbf{d}}(C) \text{ is } \tau\text{-closed, for every } \tau\text{-closed set } C \subseteq X \text{ and } r \in (0, +\infty).$$

Let $C \subseteq X$ be a τ -closed set. Let $f: C \rightarrow \mathbb{R}$ be a bounded τ -continuous \mathbf{d} -Lipschitz function. Then there exists a function $\bar{f} \in \text{Lip}_b(X, \tau, \mathbf{d})$ such that

$$\bar{f}|_C = f, \quad \text{Lip}(\bar{f}, \mathbf{d}) = \text{Lip}(f, C, \mathbf{d}), \quad \inf_C f \leq \bar{f} \leq \sup_C f.$$

Proof. Without loss of generality, we can assume that $\text{Lip}(f, C, \mathbf{d}) > 0$. We define

$$M := \frac{\text{Osc}_C(f)}{\text{Lip}(f, C, \mathbf{d})} > 0$$

and let us consider the truncated distance $\tilde{\mathbf{d}} := \mathbf{d} \wedge M$. Then $\tilde{\mathbf{d}}$ is $(\tau \times \tau)$ -lower semicontinuous, f is $\tilde{\mathbf{d}}$ -Lipschitz and $\text{Lip}(f, C, \tilde{\mathbf{d}}) = \text{Lip}(f, C, \mathbf{d})$. By virtue of [39, Theorem 2.4], we can find a τ -continuous $\tilde{\mathbf{d}}$ -Lipschitz extension $\bar{f}: X \rightarrow \mathbb{R}$ of f such that $\text{Lip}(\bar{f}, \tilde{\mathbf{d}}) = \text{Lip}(f, C, \tilde{\mathbf{d}})$ and $\inf_C f \leq \bar{f} \leq \sup_C f$. Given that $\tilde{\mathbf{d}} \leq \mathbf{d}$, we can thus conclude that $\bar{f} \in \text{Lip}_b(X, \tau, \mathbf{d})$ and $\text{Lip}(\bar{f}, \mathbf{d}) = \text{Lip}(f, C, \mathbf{d})$. \square

Remark 3.2. Let us make some comments on Theorem 3.1:

- i) Every τ -compact e.m.t. space (X, τ, \mathbf{d}) satisfies the assumptions of Theorem 3.1. Indeed, all compact Hausdorff spaces are normal, and (3.2) holds by [39, proof of Corollary 2.5].
- ii) If \mathbb{B} is a Banach space, $\mathbf{d}_{\mathbb{B}'}$ denotes the distance on \mathbb{B}' induced by its norm and τ_{w^*} is the weak* topology of \mathbb{B}' , then $(\mathbb{B}', \tau_{w^*}, \mathbf{d}_{\mathbb{B}'})$ fulfils the assumptions of Theorem 3.1, as it is shown in the proof of [39, Corollary 2.6].
- iii) The requirement (3.2) cannot be dropped. Indeed, if \mathbb{B} is a non-reflexive Banach space, $\mathbf{d}_{\mathbb{B}}$ denotes its induced distance and τ_w is its weak topology, then $(\mathbb{B}, \tau_w, \mathbf{d}_{\mathbb{B}})$ neither fulfils (3.2) nor the conclusions of Theorem 3.1; see the proof of [39, Theorem 3.1]. Note also that if in addition \mathbb{B}' is separable, then (\mathbb{B}, τ_w) is normal (it can be readily checked that it is both regular and Lindelöf, thus it is normal by [35, Lemma at page 113]).
- iv) If (X, τ) is a normal Hausdorff space and $\mathbf{d} := \mathbf{d}_{\text{discr}}$ denotes the discrete distance on X , then Theorem 3.1 for (X, τ, \mathbf{d}) reduces to the *Tietze extension theorem* for bounded functions (note that (3.2) holds in this case, since $\bar{B}_r^{\mathbf{d}}(C) = C$ if $r < 1$, $\bar{B}_r^{\mathbf{d}}(C) = X$ otherwise). In particular, in Theorem 3.1 both the assumptions that τ is normal and that the set C is τ -closed are needed.
- v) If (X, \mathbf{d}) is a metric space and $\tau_{\mathbf{d}}$ denotes the topology induced by \mathbf{d} , then Theorem 3.1 for $(X, \tau_{\mathbf{d}}, \mathbf{d})$ implies the McShane–Whitney extension theorem for bounded functions.
- vi) Differently from the Tietze and the McShane–Whitney extension theorems, in Theorem 3.1 the boundedness assumption on f cannot be dropped; see e.g. [39, Example 3.2]. \blacksquare

In Section 4, the above extension result will be used to study the relation between different notions of Lipschitz derivations. Rather than Theorem 3.1, we will apply a consequence of it:

Corollary 3.3. *Let (X, τ, \mathbf{d}) be an e.m.t. space. Let $K \subseteq X$ be a τ -compact set. Let $f: K \rightarrow \mathbb{R}$ be a bounded τ -continuous \mathbf{d} -Lipschitz function. Then there exists $\bar{f} \in \text{Lip}_b(X, \tau, \mathbf{d})$ such that*

$$\bar{f}|_K = f, \quad \text{Lip}(\bar{f}, \mathbf{d}) = \text{Lip}(f, K, \mathbf{d}), \quad \min_K f \leq \bar{f} \leq \max_K f.$$

Proof. Consider the compactification $(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ of (X, τ, \mathbf{d}) and the canonical embedding $\iota: X \hookrightarrow \hat{X}$. Since ι is continuous, we have that $\iota(K)$ is $\hat{\tau}$ -compact. The function $g: \iota(K) \rightarrow \mathbb{R}$, which we define as $g(y) := f(\iota^{-1}(y))$ for every $y \in \iota(K)$, is $\hat{\tau}$ -continuous and $\hat{\mathbf{d}}$ -Lipschitz. By applying Theorem 3.1 (taking also Remark 3.2 i) into account), we deduce that there exists a function $\bar{g}: \hat{X} \rightarrow \mathbb{R}$ such that $\bar{g}|_{\iota(K)} = g$, $\text{Lip}(\bar{g}, \hat{\mathbf{d}}) = \text{Lip}(g, \iota(K), \hat{\mathbf{d}})$ and $\min_{\iota(K)} g \leq \bar{g} \leq \max_{\iota(K)} g$. Now define $\bar{f}: X \rightarrow \mathbb{R}$ as $\bar{f}(x) := \bar{g}(\iota(x))$ for every $x \in X$. Observe that $\bar{f} \in \text{Lip}_b(X, \tau, \mathbf{d})$, $\bar{f}|_K = f$, $\text{Lip}(\bar{f}, \mathbf{d}) = \text{Lip}(f, K, \mathbf{d})$ and $\min_K f \leq \bar{f} \leq \max_K f$. Therefore, the statement is proved. \square

4. Lipschitz derivations

Let us begin by introducing a rather general notion of *Lipschitz derivation* over an arbitrary e.m.t.m. space. In Sections 4.1 and 4.2, we will then identify and study two special classes of derivations, which extend previous notions by Weaver [49, 50] and Di Marino [18, 17], respectively.

Definition 4.1. (Lipschitz derivation) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Then by a *Lipschitz derivation* on \mathbb{X} we mean a linear operator $b: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow L^0(\mathbf{m})$ such that

$$(4.1) \quad b(fg) = f b(g) + g b(f) \quad \text{for every } f, g \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

We refer to (4.1) as the *Leibniz rule*. We denote by $\text{Der}(\mathbb{X})$ the set of all derivations on \mathbb{X} .

It can be readily checked that the space $\text{Der}(\mathbb{X})$ is a module over $L^0(\mathbf{m})$ if endowed with

$$(b + \tilde{b})(f) := b(f) + \tilde{b}(f) \quad \text{for every } b, \tilde{b} \in \text{Der}(\mathbb{X}) \text{ and } f \in \text{Lip}_b(X, \tau, \mathbf{d}),$$

$$(hb)(f) := h b(f) \quad \text{for every } b \in \text{Der}(\mathbb{X}), h \in L^0(\mathbf{m}) \text{ and } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

In particular, $\text{Der}(\mathbb{X})$ is a vector space (since the field \mathbb{R} can be identified with a subring of $L^0(\mathbf{m})$, via the map that associates to every number $\lambda \in \mathbb{R}$ the function that is \mathbf{m} -a.e. equal to λ).

Definition 4.2. (Divergence of a Lipschitz derivation) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $b \in \text{Der}(\mathbb{X})$. Then we say that b has *divergence* provided it holds that $b(f) \in L^1(\mathbf{m})$ for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ and there exists a function $\text{div}(b) \in L^1(\mathbf{m})$ such that

$$(4.2) \quad \int b(f) d\mathbf{m} = - \int f \text{div}(b) d\mathbf{m} \quad \text{for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

We denote by $D(\text{div}; \mathbb{X})$ the set of all Lipschitz derivations on \mathbb{X} having divergence.

Let us make some comments on Definition 4.2:

- Since $\text{Lip}_b(X, \tau, \mathbf{d})$ is weakly* dense in $L^1(\mathbf{m})$ (as it easily follows from (2.8)), it holds that the divergence $\text{div}(b)$ is uniquely determined by (4.2).
- $D(\text{div}; \mathbb{X})$ is a vector subspace of $\text{Der}(\mathbb{X})$.
- $\text{div}: D(\text{div}; \mathbb{X}) \rightarrow L^1(\mathbf{m})$ is a linear operator.
- The divergence satisfies the *Leibniz rule*, i.e. for every $b \in D(\text{div}; \mathbb{X})$ and $h \in \text{Lip}_b(X, \tau, \mathbf{d})$ it holds that $hb \in D(\text{div}; \mathbb{X})$ and

$$\text{div}(hb) = h \text{div}(b) + b(h).$$

In particular, $D(\operatorname{div}; \mathbb{X})$ is a $\operatorname{Lip}_b(X, \tau, \mathbf{d})$ -submodule of $\operatorname{Der}(\mathbb{X})$.

We shall focus on classes of derivations satisfying additional locality or continuity properties:

Definition 4.3. (Local derivation) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $b \in \operatorname{Der}(\mathbb{X})$ be a given derivation. Then we say that b is *local* if for every function $f \in \operatorname{Lip}_b(X, \tau, \mathbf{d})$ we have that

$$b(f) = 0 \quad \text{holds } \mathbf{m}\text{-a.e. on } \{f = 0\}.$$

Let $E \in \mathcal{B}(X, \tau)$ be such that $\mathbf{m}(E) > 0$. Then every local derivation $b \in \operatorname{Der}(\mathbb{X})$ induces by restriction a local derivation $b|_E \in \operatorname{Der}(\mathbb{X}|_E)$, where $\mathbb{X}|_E$ is as in (2.9), in the following way. Thanks to the inner regularity of \mathbf{m} , we can find a sequence $(K_n)_n$ of pairwise disjoint τ -compact subsets of E such that $\mathbf{m}(E \setminus \bigcup_{n \in \mathbb{N}} K_n) = 0$. For any $f \in \operatorname{Lip}_b(E, \tau_E, \mathbf{d}_E)$ and $n \in \mathbb{N}$, we know from Corollary 3.3 that there exists $\bar{f}_n \in \operatorname{Lip}_b(X, \tau, \mathbf{d})$ such that $\bar{f}_n|_{K_n} = f|_{K_n}$. We then define

$$(4.3) \quad (b|_E)(f) := \sum_{n \in \mathbb{N}} \mathbb{1}_{K_n} b(\bar{f}_n) \in L^0(\mathbf{m}|_E).$$

By using the locality of b , one can readily check that $b|_E$ is well defined and local.

In the definition below, we endow the closed unit ball $\bar{B}_{\operatorname{Lip}_b(X, \tau, \mathbf{d})}$ of $\operatorname{Lip}_b(X, \tau, \mathbf{d})$ with the topology τ_{pt} of *pointwise convergence*, and the space $L^\infty(\mathbf{m})$ with its weak* topology τ_{w^*} .

Definition 4.4. (Weak*-type continuity of derivations) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $b \in \operatorname{Der}(\mathbb{X})$ be a given derivation satisfying $b(f) \in L^\infty(\mathbf{m})$ for every $f \in \operatorname{Lip}_b(X, \tau, \mathbf{d})$. Then:

- i) We say that b is *weakly*-type continuous* provided the map $b|_{\bar{B}_{\operatorname{Lip}_b(X, \tau, \mathbf{d})}}$ is continuous between $(\bar{B}_{\operatorname{Lip}_b(X, \tau, \mathbf{d})}, \tau_{pt})$ and $(L^\infty(\mathbf{m}), \tau_{w^*})$.
- ii) We say that b is *weakly*-type sequentially continuous* provided the map $b|_{\bar{B}_{\operatorname{Lip}_b(X, \tau, \mathbf{d})}}$ is sequentially continuous between $(\bar{B}_{\operatorname{Lip}_b(X, \tau, \mathbf{d})}, \tau_{pt})$ and $(L^\infty(\mathbf{m}), \tau_{w^*})$.

Some comments on the weak*-type continuity and the weak*-type sequential continuity:

- Since derivations are linear, the weak*-type continuity can be equivalently reformulated by asking that *if a bounded net $(f_i)_{i \in I} \subseteq \operatorname{Lip}_b(X, \tau, \mathbf{d})$ and a function $f \in \operatorname{Lip}_b(X, \tau, \mathbf{d})$ satisfy $\lim_{i \in I} f_i(x) = f(x)$ for every $x \in X$, then $\lim_{i \in I} b(f_i) = b(f)$ with respect to the weak* topology of $L^\infty(\mathbf{m})$* . Similarly, the weak*-type sequential continuity is equivalent to asking that *if a bounded sequence $(f_n)_{n \in \mathbb{N}} \subseteq \operatorname{Lip}_b(X, \tau, \mathbf{d})$ and a function $f \in \operatorname{Lip}_b(X, \tau, \mathbf{d})$ satisfy $\lim_n f_n(x) = f(x)$ for every $x \in X$, then $b(f_n) \xrightarrow{*} b(f)$ weakly* in $L^\infty(\mathbf{m})$ as $n \rightarrow \infty$* .
- The terminology ‘weak*-type (sequential) continuity’ is motivated by the fact that it strongly resembles the weak* (sequential) continuity in the Banach algebra $\operatorname{Lip}_b(X, \mathbf{d})$ of bounded Lipschitz functions on a metric space (see [50, Corollary 3.4]), even though in the setting of e.m.t. spaces one has that $\operatorname{Lip}_b(X, \tau, \mathbf{d})$ does not always have a predual (see Proposition 2.16) and thus we cannot talk about an actual weak* topology on it.
- We point out that if a bounded sequence $(f_n)_n \subseteq \operatorname{Lip}_b(X, \tau, \mathbf{d})$ and a function $f: X \rightarrow \mathbb{R}$ satisfy $f_n(x) \rightarrow f(x)$ for every $x \in X$, then f is \mathbf{d} -Lipschitz, but

it can happen that it is not τ -continuous, and thus it does not belong to $\text{Lip}_b(X, \tau, \mathbf{d})$; see Example 4.5 below.

- The weak*-type continuity is stronger than the weak*-type sequential continuity, but they are not equivalent concepts, as we will see in Proposition 4.7 and Remark 5.5.

Example 4.5. When (X, \mathbf{d}) is a metric space, the topology τ_{pt} on $\bar{B}_{\text{Lip}_b(X, \mathbf{d})}$ coincides with the restriction of the weak* topology of $\text{Lip}_b(X, \tau, \mathbf{d})$, thus in particular $(\bar{B}_{\text{Lip}_b(X, \mathbf{d})}, \tau_{pt})$ is a compact Hausdorff topological space. On the contrary, in the more general setting of e.m.t. spaces the Hausdorff topological space $(\bar{B}_{\text{Lip}_b(X, \tau, \mathbf{d})}, \tau_{pt})$ needs not be compact. For example, consider the unit interval $[0, 1]$ together with the Euclidean topology τ and the discrete distance $\mathbf{d}_{\text{discr}}$, which gives a ‘purely-topological’ e.m.t. space as in Example 2.14. Letting $(f_n)_{n \in \mathbb{N}} \subseteq \text{Lip}_b([0, 1], \tau, \mathbf{d}_{\text{discr}})$ be defined as $f_n(t) := (nt) \wedge 1$ for every $n \in \mathbb{N}$ and $t \in [0, 1]$, we have that $\|f_n\|_{\text{Lip}_b([0, 1], \tau, \mathbf{d}_{\text{discr}})} = 2$ for every $n \in \mathbb{N}$ and $\mathbb{1}_{(0, 1]}(t) = \lim_n f_n(t)$ for every $t \in [0, 1]$, but $\mathbb{1}_{(0, 1]} \notin \text{Lip}_b([0, 1], \tau, \mathbf{d}_{\text{discr}})$ (because it is not τ -continuous at 0). In particular, $(\bar{B}_{\text{Lip}_b([0, 1], \tau, \mathbf{d}_{\text{discr}})}, \tau_{pt})$ is not compact. ■

The weak*-type sequential continuity condition implies both locality and strong continuity:

Theorem 4.6. *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $b \in \text{Der}(\mathbb{X})$ be weakly*-type sequentially continuous. Then b is a local derivation. Moreover, the map $b: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow L^\infty(\mathbf{m})$ is a bounded linear operator.*

Proof. The proof of locality is essentially taken from [50, Lemma 10.34]. Fix any $f \in \text{Lip}_b(X, \tau, \mathbf{d})$. For any $n \in \mathbb{N}$, we define the auxiliary functions $\phi_n, \psi_n: \mathbb{R} \rightarrow \mathbb{R}$ as $\phi_n(t) := 1 - e^{-nt^2}$ and $\psi_n(t) := t\phi_n(t)$ for every $t \in \mathbb{R}$. Since $0 \leq \phi_n(t) \leq 1$ and $\phi'_n(t) = 2nte^{-nt^2}$ for all $t \in \mathbb{R}$, we have that ϕ_n is Lipschitz on $f(X)$ and thus $\phi_n \circ f \in \text{Lip}_b(X, \tau, \mathbf{d})$. Moreover, $-|t| \leq \psi_n(t) \leq |t|$ and $0 \leq \psi'_n(t) \leq 1 + 2e^{-3/2}$ for all $t \in \mathbb{R}$, so that $\psi_n \circ f \in \text{Lip}_b(X, \tau, \mathbf{d})$ with $\|\psi_n \circ f\|_{C_b(X, \tau)} \leq \|f\|_{C_b(X, \tau)}$ and $\text{Lip}(\psi_n \circ f, \mathbf{d}) \leq (1 + 2e^{-3/2})\text{Lip}(f, \mathbf{d})$. In particular, the sequence $(\psi_n \circ f)_n$ is norm bounded in $\text{Lip}_b(X, \tau, \mathbf{d})$. Note also that $\lim_n(\psi_n \circ f)(x) = f(x)$ for every $x \in X$, whence it follows that

$$f b(\phi_n \circ f) + (\phi_n \circ f) b(f) = b((\phi_n \circ f)f) = b(\psi_n \circ f) \xrightarrow{*} b(f)$$

weakly* in $L^\infty(\mathbf{m})$ as $n \rightarrow \infty$ by the weak*-type sequential continuity of b . In particular, as $\mathbb{1}_{\{f=0\}}(f b(\phi_n \circ f) + (\phi_n \circ f) b(f)) = 0$ holds \mathbf{m} -a.e. for every $n \in \mathbb{N}$, we conclude that $\mathbb{1}_{\{f=0\}} b(f) = 0$ in the \mathbf{m} -a.e. sense, thus b is local.

Let us now prove that $b: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow L^\infty(\mathbf{m})$ is a bounded linear operator. Given any function $h \in L^1(\mathbf{m})$, we define the linear operator $T_h: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow \mathbb{R}$ as

$$T_h(f) := \int h b(f) \, \mathbf{d}\mathbf{m} \quad \text{for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

If $(f_n)_{n \in \mathbb{N}} \subseteq \text{Lip}_b(X, \tau, \mathbf{d})$ and $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ satisfy $\|f_n - f\|_{\text{Lip}_b(X, \tau, \mathbf{d})} \rightarrow 0$ as $n \rightarrow \infty$, then we have in particular that $\sup_{n \in \mathbb{N}} \|f_n\|_{\text{Lip}_b(X, \tau, \mathbf{d})} < +\infty$ and $f(x) = \lim_n f_n(x)$ for every $x \in X$, so that $b(f_n) \xrightarrow{*} b(f)$ weakly* in $L^\infty(\mathbf{m})$ by the weak*-type sequential continuity of b , and thus accordingly $T_h(f_n) = \int h b(f_n) \, \mathbf{d}\mathbf{m} \rightarrow \int h b(f) \, \mathbf{d}\mathbf{m} = T_h(f)$. This shows that $T_h: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow \mathbb{R}$ is continuous, thus $T_h \in \text{Lip}_b(X, \tau, \mathbf{d})'$. Next,

denote $B := \{h \in L^1(\mathfrak{m}) : \|h\|_{L^1(\mathfrak{m})} \leq 1\}$. Note that

$$\sup_{h \in B} |T_h(f)| \leq \sup_{h \in B} \int |h| |b(f)| \, d\mathfrak{m} \leq \|b(f)\|_{L^\infty(\mathfrak{m})} \quad \text{for every } f \in \text{Lip}_b(X, \tau, \mathfrak{d})$$

by Hölder's inequality. Thanks to the Uniform Boundedness Principle, we then deduce that

$$M := \sup_{h \in B} \|T_h\|_{\text{Lip}_b(X, \tau, \mathfrak{d})'} < +\infty.$$

Therefore, we can conclude that for any $f \in \text{Lip}_b(X, \tau, \mathfrak{d})$ with $\|f\|_{\text{Lip}_b(X, \tau, \mathfrak{d})} \leq 1$ it holds that

$$\|b(f)\|_{L^\infty(\mathfrak{m})} = \sup_{h \in B} \int h b(f) \, d\mathfrak{m} = \sup_{h \in B} T_h(f) \leq \sup_{h \in B} \|T_h\|_{\text{Lip}_b(X, \tau, \mathfrak{d})'} = M,$$

whence it follows that $b: \text{Lip}_b(X, \tau, \mathfrak{d}) \rightarrow L^\infty(\mathfrak{m})$ is a bounded linear operator. \square

The next result clarifies the interplay between weak*-type continuous derivations and the decomposition of an e.m.t.m. space into its maximal \mathfrak{d} -separable and purely non- \mathfrak{d} -separable components. The proof of i) was suggested to us by Sylvester Eriksson-Bique.

Proposition 4.7. *Let $\mathbb{X} = (X, \tau, \mathfrak{d}, \mathfrak{m})$ be an e.m.t.m. space. Let $b \in \text{Der}(\mathbb{X})$ be given. Then:*

- i) *If b is weakly*-type continuous, then $b(f) = 0$ \mathfrak{m} -a.e. on $X \setminus S_{\mathbb{X}}$ for every $f \in \text{Lip}_b(X, \tau, \mathfrak{d})$.*
- ii) *If b is a local derivation and $b \ll S_{\mathbb{X}}$ is weakly*-type sequentially continuous, then $b \ll S_{\mathbb{X}}$ is weakly*-type continuous. In particular, if b is weakly*-type sequentially continuous, then $b \ll S_{\mathbb{X}}$ is weakly*-type continuous.*

Proof. i) Assume that b is weakly*-type continuous. We argue by contradiction: suppose that there exists a function $f \in \text{Lip}_b(X, \tau, \mathfrak{d})$ such that $\mathfrak{m}(\{b(f) \neq 0\} \setminus S_{\mathbb{X}}) > 0$. Up to replacing f with $-f$, we can assume that $\mathfrak{m}(\{b(f) > 0\} \setminus S_{\mathbb{X}}) > 0$, so that there exists a real number $\lambda > 0$ such that $\mathfrak{m}(\{b(f) \geq \lambda\} \setminus S_{\mathbb{X}}) > 0$. Fix any τ -Borel \mathfrak{m} -a.e. representative P of $\{b(f) \geq \lambda\} \setminus S_{\mathbb{X}}$ satisfying $P \subseteq X \setminus S_{\mathbb{X}}$. Next, we define

$$\mathcal{I} := \{(F, G) \mid F \subseteq X \text{ finite}, G \subseteq \text{Lip}_{b,1}(X, \tau, \mathfrak{d}) \text{ finite}\}.$$

For any $(F, G), (\tilde{F}, \tilde{G}) \in \mathcal{I}$, we declare that $(F, G) \preceq (\tilde{F}, \tilde{G})$ if and only if $F \subseteq \tilde{F}$ and $G \subseteq \tilde{G}$. Note that (\mathcal{I}, \preceq) is a directed set. We then define the net $(u_{F,G})_{(F,G) \in \mathcal{I}} \subseteq \text{Lip}_b(X, \tau, \mathfrak{d})$ as

$$u_{F,G}(x) := \min_{p \in F} \max_{g \in G} |g(x) - g(p)| \wedge 1 \quad \text{for every } (F, G) \in \mathcal{I} \text{ and } x \in X.$$

Given any $x \in X$, we have that $u_{F,G}(x) = 0$ holds for every $(F, G) \in \mathcal{I}$ with $(\{x\}, \emptyset) \preceq (F, G)$, thus accordingly $\lim_{(F,G) \in \mathcal{I}} u_{F,G}(x) = 0$ and $\lim_{(F,G) \in \mathcal{I}} (u_{F,G}f)(x) = 0$. Since $\{u_{F,G} : (F, G) \in \mathcal{I}\}$ and $\{u_{F,G}f : (F, G) \in \mathcal{I}\}$ are bounded subsets of $\text{Lip}_b(X, \tau, \mathfrak{d})$, we deduce that

$$\lim_{(F,G) \in \mathcal{I}} u_{F,G} b(f) = \lim_{(F,G) \in \mathcal{I}} (b(u_{F,G}f) - f b(u_{F,G})) = 0 \quad \text{weakly* in } L^\infty(\mathfrak{m}),$$

by the weak*-type continuity of b and the Leibniz rule. Hence, $\lim_{(F,G) \in \mathcal{I}} \int_P u_{F,G} \cdot b(f) \, d\mathfrak{m} = 0$. Since $0 \leq \lambda \int_P u_{F,G} \, d\mathfrak{m} \leq \int_P u_{F,G} b(f) \, d\mathfrak{m}$ for every $(F, G) \in \mathcal{I}$, we get

$\lim_{(F,G) \in \mathcal{I}} \int_P u_{F,G} d\mathbf{m} = 0$. Then we can find a \preceq -increasing sequence $((F_k, G_k))_{k \in \mathbb{N}} \subseteq \mathcal{I}$ such that

$$(4.4) \quad \int_P u_{F,G} d\mathbf{m} \leq \frac{1}{k} \quad \text{for every } k \in \mathbb{N} \text{ and } (F, G) \in \mathcal{I} \text{ with } (F_k, G_k) \preceq (F, G).$$

Given any $k \in \mathbb{N}$, consider the directed set $I_k := \{G \subseteq \text{Lip}_{b,1}(X, \tau, \mathbf{d}) : G_k \subseteq G \text{ with } G \text{ finite}\}$ ordered by inclusion. Being $(u_{F_k, G})_{G \in I_k}$ a non-decreasing net of τ -continuous functions, we have

$$(4.5) \quad \int_P \min_{p \in F_k} \mathbf{d}(x, p) \wedge 1 d\mathbf{m}(x) = \int_P \lim_{G \in I_k} u_{F_k, G} d\mathbf{m} = \lim_{G \in I_k} \int_P u_{F_k, G} d\mathbf{m} \leq \frac{1}{k}$$

for all $k \in \mathbb{N}$ thanks to (2.7), Remark 2.4 and (4.4). Now, observe that $\min_{p \in F_k} \mathbf{d}(x, p) \wedge 1 \searrow \inf_{p \in C} \mathbf{d}(x, p) \wedge 1$ as $k \rightarrow \infty$ for every $x \in X$, where C denotes the countable set $\bigcup_{k \in \mathbb{N}} F_k$. By the dominated convergence theorem, we deduce from (4.5) that $\int_P \inf_{p \in C} \mathbf{d}(x, p) \wedge 1 d\mathbf{m}(x) = 0$, which implies that there exists a set $N \in \mathcal{B}(X, \tau)$ such that $\mathbf{m}(N) = 0$ and $\inf_{p \in C} \mathbf{d}(x, p) \wedge 1 = 0$ for every $x \in P \setminus N$. Therefore, C is \mathbf{d} -dense in $P \setminus N$, in contradiction with the fact that $P \setminus N \subseteq X \setminus S_{\mathbb{X}}$ and $\mathbf{m}(P \setminus N) > 0$.

ii) Assume that b is local and that $b_{\perp} S_{\mathbb{X}}$ is weakly*-type sequentially continuous. Theorem 4.6 ensures that there exists a constant $C > 0$ such that $|(b_{\perp} S_{\mathbb{X}})(f)| \leq C \|f\|_{\text{Lip}_b(S_{\mathbb{X}}, \tau_{S_{\mathbb{X}}}, \mathbf{d}_{S_{\mathbb{X}}})}$ holds $\mathbf{m}_{\perp} S_{\mathbb{X}}$ -a.e. on $S_{\mathbb{X}}$ for every $f \in \text{Lip}_b(S_{\mathbb{X}}, \tau_{S_{\mathbb{X}}}, \mathbf{d}_{S_{\mathbb{X}}})$. For any $R > 0$, we denote

$$A_R := \{f \in \text{Lip}_b(S_{\mathbb{X}}, \tau_{S_{\mathbb{X}}}, \mathbf{d}_{S_{\mathbb{X}}}) \mid \|f\|_{\text{Lip}_b(S_{\mathbb{X}}, \tau_{S_{\mathbb{X}}}, \mathbf{d}_{S_{\mathbb{X}}})} \leq R\},$$

$$B_R := \{h \in L^{\infty}(\mathbf{m}_{\perp} S_{\mathbb{X}}) \mid \|h\|_{L^{\infty}(\mathbf{m}_{\perp} S_{\mathbb{X}})} \leq CR\}.$$

Observe that $b(f) \in B_R$ for every $f \in A_R$. Since $(S_{\mathbb{X}}, \mathbf{d}_{S_{\mathbb{X}}})$ is separable, we know from Lemma 2.10 that $L^1(\mathbf{m}_{\perp} S_{\mathbb{X}})$ is separable, so that the restriction of the weak* topology of $L^{\infty}(\mathbf{m}_{\perp} S_{\mathbb{X}})$ to B_R is metrised by some distance δ_R . Moreover, fixed some countable \mathbf{d} -dense subset $(x_n)_{n \in \mathbb{N}}$ of $S_{\mathbb{X}}$, we define the distance \mathbf{d}^R on A_R as

$$\mathbf{d}^R(f, g) := \sum_{n \in \mathbb{N}} \frac{|f(x_n) - g(x_n)|}{2^n} \quad \text{for every } f, g \in A_R.$$

Using the fact that the set A_R is \mathbf{d} -equi-Lipschitz, it is straightforward to check that \mathbf{d}^R metris the pointwise convergence of functions in A_R . Therefore, for the derivation $b_{\perp} S_{\mathbb{X}}$ the weak*-type continuity is equivalent to the weak*-type sequential continuity, since both conditions are equivalent to the continuity of $b|_{A_R} : (A_R, \mathbf{d}^R) \rightarrow (B_R, \delta_R)$ for every $R > 0$. \square

We highlight the following facts, which are immediate consequences of Proposition 4.7:

Corollary 4.8. *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Then the following properties hold:*

- i) *If $\mathbf{m}(S_{\mathbb{X}}) = 0$, the null derivation is the unique weakly*-type continuous derivation on \mathbb{X} .*
- ii) *If $\mathbf{m}(X \setminus S_{\mathbb{X}}) = 0$, a derivation $b \in \text{Der}(\mathbb{X})$ is weakly*-type continuous if and only if it is weakly*-type sequentially continuous.*

4.1. Weaver derivations. Motivated by Corollary 4.8, we give the following definition:

Definition 4.9. (Weaver derivation) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $b \in \text{Der}(\mathbb{X})$. Then we say that b is a *Weaver derivation* on \mathbb{X} if it is weakly*-type sequentially continuous. We denote by $\mathcal{X}(\mathbb{X})$ the set of all Weaver derivations on \mathbb{X} .

The goal of our axiomatisation above is to extend Weaver’s notion of ‘bounded measurable vector field’ [50, Definition 10.30 a)] to the setting of e.m.t.m. spaces. In fact, in those cases where the set $X \setminus S_{\mathbb{X}}$ is \mathbf{m} -negligible (which cover e.g. all metric-measure spaces), we know from Corollary 4.8 ii) that our notion of Weaver derivation is consistent with [50, Definition 10.30 a)]. Though, many e.m.t.m. spaces of interest (e.g. Example 2.14 or abstract Wiener spaces) are ‘purely non- \mathbf{d} -separable’, meaning that $\mathbf{m}(S_{\mathbb{X}}) = 0$. If this is the case, then no non-null derivation is weakly*-type continuous by Corollary 4.8 i). Due to this reason, in our definition of Weaver derivation we ask for the weak*-type sequential continuity in lieu. As we will see in Example 5.5, abstract Wiener spaces—despite lacking in weak*-type continuous derivations—have plenty of weak*-type sequential ones. The axiomatisation we have chosen is also motivated by Theorem 4.16.

The space $\mathcal{X}(\mathbb{X})$ is an $L^\infty(\mathbf{m})$ -submodule (and, thus, a vector subspace) of $\text{Der}(\mathbb{X})$. To any Weaver derivation $b \in \mathcal{X}(\mathbb{X})$, we associate the function $|b|_W \in L^\infty(\mathbf{m})^+$, which we define as

$$|b|_W := \bigwedge \{g \in L^\infty(\mathbf{m})^+ \mid |b(f)| \leq g\|f\|_{\text{Lip}_b(X, \tau, \mathbf{d})} \text{ } \mathbf{m}\text{-a.e. for every } f \in \text{Lip}_b(X, \tau, \mathbf{d})\}.$$

Note that $|b(f)| \leq |b|_W\|f\|_{\text{Lip}_b(X, \tau, \mathbf{d})}$ holds \mathbf{m} -a.e. on X for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$.

We also point out that all Weaver derivations $b \in \mathcal{X}(\mathbb{X})$ are bounded linear operators (thanks to Theorem 4.6). For ‘bounded measurable vector fields’, this fact was observed in [50, paragraph after Definition 10.30], but in that case a stronger statement actually holds: the image of the closed unit ball of $\text{Lip}_b(X, \mathbf{d})$ under b is a weakly* compact subset of $L^\infty(\mathbf{m})$ (since the closed unit ball is weakly* compact by the Banach–Alaoglu theorem, and b is weakly* continuous). In our setting, we have seen already in Example 4.5 that $(\bar{B}_{\text{Lip}_b(X, \tau, \mathbf{d})}, \tau_{pt})$ is not always compact. The following example shows that for Weaver derivations $b \in \mathcal{X}(\mathbb{X})$ on an e.m.t.m. space \mathbb{X} it is not necessarily true that the image $b(\bar{B}_{\text{Lip}_b(X, \tau, \mathbf{d})}) \subseteq L^\infty(\mathbf{m})$ is a weakly* compact set.

Example 4.10. Let (X, τ, \mathbf{d}) be the e.m.t. space described in Example 2.15. We equip it with the restriction \mathbf{m} of the 2-dimensional Lebesgue measure, so that $\mathbb{X} := (X, \tau, \mathbf{d}, \mathbf{m})$ is an e.m.t.m. space. Given any function $f \in \text{Lip}_b(X, \tau, \mathbf{d})$, we have that $f(x, \cdot) \in \text{Lip}_b([0, 1], \mathbf{d}_{\text{Eucl}})$ for every $x \in [0, 1]$, thus the derivative $f'(x, \cdot)(t) \in \mathbb{R}$ exists for \mathcal{L}^1 -a.e. $t \in [0, 1]$ by Rademacher’s theorem. In particular, thanks to Fubini’s theorem and to (2.17), it makes sense to define $b(f) \in L^\infty(\mathbf{m})$ as

$$b(f)(x, t) := f'(x, \cdot)(t) \quad \text{for } \mathbf{m}\text{-a.e. } (x, t) \in X.$$

It easily follows from the classical calculus rules for the a.e. derivatives of Lipschitz functions from $[0, 1]$ to \mathbb{R} that the resulting operator $b: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow L^\infty(\mathbf{m})$ is a derivation on \mathbb{X} . Moreover, if $(f_n)_{n \in \mathbb{N}} \subseteq \text{Lip}_b(X, \tau, \mathbf{d})$ and $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ are such that $\sup_{n \in \mathbb{N}} \|f_n\|_{\text{Lip}_b(X, \tau, \mathbf{d})} < +\infty$ and $f(x, t) = \lim_n f_n(x, t)$ for every $(x, t) \in X$, then for every $x \in [0, 1]$ the sequence $(f_n(x, \cdot))_n$ is equi-Lipschitz and equibounded, thus $f'_n(x, \cdot) \xrightarrow{*} f'(x, \cdot)$ weakly* in $L^\infty(0, 1)$ (as $f'_n(x, \cdot)$ is the weak derivative of $f_n(x, \cdot)$ by

Rademacher's theorem). Hence, for any $h \in L^1(\mathfrak{m})$ we have that

$$\begin{aligned} \int h b(f_n) d\mathfrak{m} &= \int_0^1 \int_0^1 h(x, t) f'_n(x, \cdot)(t) dt dx \\ &\rightarrow \int_0^1 \int_0^1 h(x, t) f'(x, \cdot)(t) dt dx = \int h b(f) d\mathfrak{m} \end{aligned}$$

as $n \rightarrow \infty$, by Fubini's theorem, the fact that $h(x, \cdot) \in L^1(0, 1)$ for a.e. $x \in [0, 1]$, and the dominated convergence theorem. This proves that b is weakly*-type sequentially continuous, so that $b \in \mathcal{X}(\mathbb{X})$.

Next, we claim that $b(\bar{B}_{\text{Lip}_b(X, \tau, \mathfrak{d})})$ is not a weakly* closed subset of $L^\infty(\mathfrak{m})$, thus in particular it is not a weakly* compact subset of $L^\infty(\mathfrak{m})$. To prove it, we define $(f_n)_{n \in \mathbb{N}} \subseteq \text{Lip}_b(X, \tau, \mathfrak{d})$ as

$$f_n(x, t) := \psi_n(x)t \quad \text{for every } n \in \mathbb{N} \text{ and } (x, t) \in X,$$

where the function $\psi_n: [0, 1] \rightarrow [0, \frac{1}{2}]$ is given by $\psi_n(x) := (\frac{n}{2}(x - \frac{1}{2}) \vee 0) \wedge \frac{1}{2}$ for every $x \in [0, 1]$. As $\|f_n\|_{C_b(X, \tau)} = \text{Osc}_X(f_n) = \frac{1}{2}$ and $\sup_{x \in [0, 1]} \text{Lip}(f_n(x, \cdot), \mathfrak{d}_{\text{Eucl}}) = \frac{1}{2}$, we have $\|f_n\|_{\text{Lip}_b(X, \tau, \mathfrak{d})} = 1$ for every $n \in \mathbb{N}$ thanks to (2.17). Furthermore, for every $n \in \mathbb{N}$ we have that

$$b(f_n)(x, t) = \psi_n(x) \quad \text{for } \mathfrak{m}\text{-a.e. } (x, t) \in X,$$

so accordingly $b(f_n) \xrightarrow{*} \frac{1}{2} \mathbb{1}_{[\frac{1}{2}, 1] \times [0, 1]} =: g$ weakly* in $L^\infty(\mathfrak{m})$ as $n \rightarrow \infty$. To conclude, it remains to show that $g \notin b(\text{Lip}_b(X, \tau, \mathfrak{d}))$, which implies that $b(\bar{B}_{\text{Lip}_b(X, \tau, \mathfrak{d})})$ is not weakly* closed in $L^\infty(\mathfrak{m})$. We argue by contradiction: assume that $g = b(f)$ for some $f \in \text{Lip}_b(X, \tau, \mathfrak{d})$. By Fubini's theorem, we deduce that for a.e. $x \in (0, \frac{1}{2})$ we have $f'(x, \cdot)(t) = 0$ for a.e. $t \in (0, 1)$, and for a.e. $x \in (\frac{1}{2}, 1)$ we have $f'(x, \cdot)(t) = \frac{1}{2}$ for a.e. $t \in (0, 1)$. In particular, we can find sequences $(x_k)_k \subseteq (0, \frac{1}{2})$ and $(y_k)_k \subseteq (\frac{1}{2}, 1)$ such that $|x_k - \frac{1}{2}|, |y_k - \frac{1}{2}| \rightarrow 0$ as $k \rightarrow \infty$, as well as $f'(x_k, \cdot) = 0$ and $f'(y_k, \cdot) = \frac{1}{2}$ a.e. on $(0, 1)$ for every $k \in \mathbb{N}$. Therefore, the fundamental theorem of calculus gives that

$$f(x_k, 1) - f(x_k, 0) = \int_0^1 f'(x_k, \cdot)(t) dt = 0, \quad f(y_k, 1) - f(y_k, 0) = \int_0^1 f'(y_k, \cdot)(t) dt = \frac{1}{2}.$$

By contrast, the τ -continuity of f ensures that $f(x_k, 1) - f(x_k, 0)$ and $f(y_k, 1) - f(y_k, 0)$ converge to the same number $f(\frac{1}{2}, 1) - f(\frac{1}{2}, 0)$ as $k \rightarrow \infty$, thus leading to a contradiction. \blacksquare

Lemma 4.11. *Let $\mathbb{X} = (X, \tau, \mathfrak{d}, \mathfrak{m})$ be an e.m.t.m. space such that \mathfrak{m} is separable. Let $b \in D(\text{div}; \mathbb{X})$ be given. Assume that there exists $C > 0$ such that $|b(f)| \leq C \text{Lip}(f, \mathfrak{d})$ holds \mathfrak{m} -a.e. on X for every $f \in \text{Lip}_b(X, \tau, \mathfrak{d})$. Then b is a Weaver derivation.*

Proof. Let $(f_n)_n \subseteq \text{Lip}_b(X, \tau, \mathfrak{d})$ and $f \in \text{Lip}_b(X, \tau, \mathfrak{d})$ be such that $f_n(x) \rightarrow f(x)$ for every $x \in X$ and $M := \sup_{n \in \mathbb{N}} \|f_n\|_{\text{Lip}_b(X, \tau, \mathfrak{d})} < +\infty$. Since $|b(f_n)| \leq CM$ holds \mathfrak{m} -a.e. for every $n \in \mathbb{N}$, the sequence $(b(f_n))_n$ is bounded in $L^\infty(\mathfrak{m})$. An application of the Banach-Alaoglu theorem, together with the separability of $L^1(\mathfrak{m})$, ensures (up to a non-relabelled subsequence) that $b(f_n) \xrightarrow{*} h$ weakly* in $L^\infty(\mathfrak{m})$ for some

$h \in L^\infty(\mathbf{m})$. Now fix any $g \in \text{Lip}_b(X, \tau, \mathbf{d})$. We have that

$$\begin{aligned} \int gh \, d\mathbf{m} &= \lim_{n \rightarrow \infty} \int g b(f_n) \, d\mathbf{m} = \lim_{n \rightarrow \infty} \int b(f_n g) - f_n b(g) \, d\mathbf{m} \\ &= - \lim_{n \rightarrow \infty} \int f_n (g \operatorname{div}(b) + b(g)) \, d\mathbf{m} = - \int f (g \operatorname{div}(b) + b(g)) \, d\mathbf{m} \\ &= \int b(fg) - f b(g) \, d\mathbf{m} = \int g b(f) \, d\mathbf{m} \end{aligned}$$

by the dominated convergence theorem. As $\text{Lip}_b(X, \tau, \mathbf{d})$ is dense in $L^1(\mathbf{m})$ (see (2.8)), we deduce that $h = b(f)$, so that the original sequence $(f_n)_n$ satisfies $b(f_n) \xrightarrow{*} b(f)$ weakly* in $L^\infty(\mathbf{m})$. This shows that b is weakly*-type sequentially continuous, so that $b \in \mathcal{X}(\mathbb{X})$. \square

4.2. Di Marino derivations. We now introduce another subclass of Lipschitz derivations, which generalises to e.m.t.m. spaces the notions that have been introduced by Di Marino in [17, 18]. After having given the relevant definitions and discussed their main properties, we will investigate (in Theorem 4.16) the relation between our notions of Weaver derivation and of Di Marino derivation.

Definition 4.12. (Di Marino derivation) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Then we say that $b \in \text{Der}(\mathbb{X})$ is a *Di Marino derivation* on \mathbb{X} if there exists $g \in L^0(\mathbf{m})^+$ such that

$$(4.6) \quad |b(f)| \leq g \operatorname{lip}_d(f) \quad \text{holds } \mathbf{m}\text{-a.e. on } X, \text{ for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

We denote by $\text{Der}^0(\mathbb{X})$ the set of all Di Marino derivations on \mathbb{X} . For any $q, r \in [1, \infty]$, we define

$$\begin{aligned} \text{Der}^q(\mathbb{X}) &:= \{b \in \text{Der}^0(\mathbb{X}) \mid (4.6) \text{ holds for some } g \in L^q(\mathbf{m})^+\}, \\ \text{Der}_r^q(\mathbb{X}) &:= \{b \in \text{Der}^q(\mathbb{X}) \cap D(\operatorname{div}; \mathbb{X}) \mid \operatorname{div}(b) \in L^r(\mathbf{m})\}. \end{aligned}$$

The space $\text{Der}^0(\mathbb{X})$ is an $L^0(\mathbf{m})$ -submodule (and, thus, a vector subspace) of $\text{Der}(\mathbb{X})$. Moreover, $\text{Der}^q(\mathbb{X})$ is an $L^\infty(\mathbf{m})$ -submodule of $\text{Der}^0(\mathbb{X})$, and $\text{Der}_q^q(\mathbb{X})$ is a $\text{Lip}_b(X, \tau, \mathbf{d})$ -submodule of $\text{Der}^q(\mathbb{X})$, for every $q \in [1, \infty]$. To any Di Marino derivation $b \in \text{Der}^0(\mathbb{X})$, we associate the function

$$\begin{aligned} |b| &:= \bigwedge \{g \in L^0(\mathbf{m})^+ \mid |b(f)| \leq g \operatorname{lip}_d(f) \text{ } \mathbf{m}\text{-a.e. for every } f \in \text{Lip}_b(X, \tau, \mathbf{d})\} \\ &\in L^0(\mathbf{m})^+. \end{aligned}$$

Since in this paper we are primarily interested in Di Marino derivations (for defining a metric Sobolev space, in Section 5.1), we use the notation $|b|$ (instead e.g. of the more descriptive $|b|_{DM}$). In this regard, it is worth pointing out that if a derivation b is both a Weaver derivation and a Di Marino derivation, it might happen that $|b|_W$ and $|b|$ are different.

Note that $|b(f)| \leq |b| \operatorname{lip}_d(f)$ holds \mathbf{m} -a.e. on X for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$, and that

$$\text{Der}^q(\mathbb{X}) = \{b \in \text{Der}^0(\mathbb{X}) \mid |b| \in L^q(\mathbf{m})\}.$$

One can readily check that $(\text{Der}^q(\mathbb{X}), |\cdot|)$ is an $L^q(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module for any $q \in (1, \infty)$. In particular, $(\text{Der}^q(\mathbb{X}), \|\cdot\|_{\text{Der}^q(\mathbb{X})})$ is a Banach space for every $q \in (1, \infty)$, where we define

$$\|b\|_{\text{Der}^q(\mathbb{X})} := \| |b| \|_{L^q(\mathbf{m})} \quad \text{for every } b \in \text{Der}^q(\mathbb{X}).$$

Furthermore, in analogy with [7, Eq. (4.9)], for any $q \in (1, \infty)$ we define the space $L_{\text{Lip}}^q(T\mathbb{X})$ as

$$(4.7) \quad L_{\text{Lip}}^q(T\mathbb{X}) := \text{cl}_{\text{Der}^q(\mathbb{X})}(\text{Der}_q^q(\mathbb{X})).$$

The notation $L_{\text{Lip}}^q(T\mathbb{X})$, which reminds of the fact that its elements are defined in duality with the space $\text{Lip}_b(X, \tau, \mathbf{d})$, is needed to distinguish it from the ‘Sobolev’ tangent modules $L^q(T\mathbb{X})$ and $L_{\text{Sob}}^q(T\mathbb{X})$ that we introduced in Section 2.4. The relation between $L_{\text{Lip}}^q(T\mathbb{X})$ and $L_{\text{Sob}}^q(T\mathbb{X})$ (in the setting of metric-measure spaces) is studied in the paper [8]. We claim that

$$hb \in L_{\text{Lip}}^q(T\mathbb{X}) \quad \text{for every } h \in L^\infty(\mathbf{m}) \text{ and } b \in L_{\text{Lip}}^q(T\mathbb{X}).$$

To prove it, take a sequence $(b_n)_n \subseteq \text{Der}_q^q(\mathbb{X})$ such that $b_n \rightarrow b$ strongly in $\text{Der}_q^q(\mathbb{X})$, and (using (2.8)) one can find a sequence $(h_n)_n \subseteq \text{Lip}_b(X, \tau, \mathbf{d})$ such that $\sup_{n \in \mathbb{N}} \|h_n\|_{C_b(X, \tau)} \leq \|h\|_{L^\infty(\mathbf{m})}$ and $h(x) = \lim_n h_n(x)$ for \mathbf{m} -a.e. $x \in X$, so that $\text{Der}_q^q(\mathbb{X}) \ni h_n b_n \rightarrow hb$ strongly in $\text{Der}_q^q(\mathbb{X})$ by the dominated convergence theorem, and thus accordingly $hb \in L_{\text{Lip}}^q(T\mathbb{X})$. Since $(\text{Der}_q^q(\mathbb{X}), |\cdot|)$ is an $L^q(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module, we deduce that $L_{\text{Lip}}^q(T\mathbb{X})$ is an $L^q(\mathbf{m})$ -Banach $L^\infty(\mathbf{m})$ -module.

The next result, whose proof is very similar to that of Lemma 4.11, studies the continuity properties of Di Marino derivations with divergence.

Lemma 4.13. *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $q \in [1, \infty)$ and $b \in \text{Der}_q^q(\mathbb{X})$. Then*

$$(4.8) \quad b|_{\bar{B}_{\text{Lip}_b(X, \tau, \mathbf{d})}} : (\bar{B}_{\text{Lip}_b(X, \tau, \mathbf{d})}, \tau_{pt}) \longrightarrow (L^q(\mathbf{m}), \tau_w) \quad \text{is sequentially continuous,}$$

where τ_w denotes the weak topology of $L^q(\mathbf{m})$.

Proof. First, note that $|b(f)| \leq |b| \text{lip}_d(f) \leq \text{Lip}(f, \mathbf{d})|b| \in L^q(\mathbf{m})$ \mathbf{m} -a.e. for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$, thus $b(f) \in L^q(\mathbf{m})$ for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$. Now fix any sequence $(f_n)_n \subseteq \bar{B}_{\text{Lip}_b(X, \tau, \mathbf{d})}$. The above estimate shows that the sequence $(b(f_n))_n$ is dominated in $L^q(\mathbf{m})$, thus the Dunford–Pettis theorem ensures (up to taking a non-relabelled subsequence) that $b(f_n) \rightharpoonup G$ weakly in $L^q(\mathbf{m})$, for some $G \in L^q(\mathbf{m})$. By using also the dominated convergence theorem, we then obtain that

$$\begin{aligned} \int h G \, d\mathbf{m} &= \lim_{n \rightarrow \infty} \int h b(f_n) \, d\mathbf{m} = \lim_{n \rightarrow \infty} \int b(h f_n) - f_n b(h) \, d\mathbf{m} \\ &= - \lim_{n \rightarrow \infty} \int f_n (h \text{div}(b) + b(h)) \, d\mathbf{m} \\ &= - \int f (h \text{div}(b) + b(h)) \, d\mathbf{m} = \int h b(h) \, d\mathbf{m} \end{aligned}$$

for every $h \in \text{Lip}_b(X, \tau, \mathbf{d})$. Letting $p \in (1, \infty)$ be the conjugate exponent of q , we know from (2.8) that $\text{Lip}_b(X, \tau, \mathbf{d})$ is strongly dense (resp. weakly* dense) in $L^p(\mathbf{m})$ if $p < \infty$ (resp. if $p = \infty$), thus we get that $G = b(f)$. Consequently, we have that the original sequence $(f_n)_n$ satisfies $b(f_n) \rightharpoonup b(f)$ weakly in $L^q(\mathbf{m})$. This shows the validity of (4.8). \square

As a consequence, Di Marino derivations with divergence are local:

Corollary 4.14. *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $q \in [1, \infty)$ and $b \in \text{Der}_q^q(\mathbb{X})$ be given. Then b is a local derivation.*

Proof. Fix any $f \in \text{Lip}_b(X, \tau, \mathbf{d})$. For any $n \in \mathbb{N}$, we define the auxiliary function $\phi_n: \mathbb{R} \rightarrow \mathbb{R}$ as

$$\phi_n(t) := \begin{cases} t + \frac{1}{n} & \text{if } t \leq -\frac{1}{n}, \\ 0 & \text{if } -\frac{1}{n} < t < \frac{1}{n}, \\ t - \frac{1}{n} & \text{if } t \geq \frac{1}{n}. \end{cases}$$

Note that $\phi_n \circ f \in \text{Lip}_b(X, \tau, \mathbf{d})$ with $\|\phi_n \circ f\|_{C_b(X, \tau)} \leq \|f\|_{C_b(X, \tau)} + 1$ and $\text{Lip}(\phi_n \circ f, \mathbf{d}) \leq \text{Lip}(f, \mathbf{d})$. It also holds that $(\phi_n \circ f)(x) \rightarrow f(x)$ for every $x \in X$, thus Lemma 4.13 gives that $b(\phi_n \circ f) \rightarrow b(f)$ weakly in $L^q(\mathbf{m})$. Moreover, one can readily check that $\text{lip}_{\mathbf{d}}(\phi_n \circ f) \leq (\text{lip}_{\mathbf{d}_{\text{Eucl}}}(\phi_n) \circ f) \text{lip}_{\mathbf{d}}(f)$, so that the \mathbf{m} -a.e. inequality $|b(\phi_n \circ f)| \leq |b| \text{lip}_{\mathbf{d}}(\phi_n \circ f)$ implies that $b(\phi_n \circ f) = 0$ holds \mathbf{m} -a.e. on the set $\{f = 0\}$ (as $\text{lip}_{\mathbf{d}_{\text{Eucl}}}(\phi_n)(0) = 0$), thus accordingly $b(f) = 0$ holds \mathbf{m} -a.e. on $\{f = 0\}$. \square

Proposition 4.15. *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $b \in \text{Der}(\mathbb{X})$ be a local derivation. Assume that there exists a function $g \in L^0(\mathbf{m})^+$ such that*

$$|b(f)| \leq g \|f\|_{\text{Lip}_b(X, \tau, \mathbf{d})} \quad \text{holds } \mathbf{m}\text{-a.e. on } X, \text{ for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

Let $C \subseteq X$ be a τ -closed set. Then for any entourage $\mathcal{U} \in \mathfrak{B}_{\tau, \mathbf{d}}$ we have that

$$(4.9) \quad |b(f)| \leq g \text{Lip}(f, C \cap \mathcal{U}[\cdot], \mathbf{d}) \quad \text{holds } \mathbf{m}\text{-a.e. on } C, \text{ for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

In particular, if the topology τ is metrisable on C , then (letting $\mathbf{d}_C := \mathbf{d}|_{C \times C}$) we have that

$$(4.10) \quad |b(f)| \leq g \text{lip}_{\mathbf{d}_C}(f|_C) \quad \text{holds } \mathbf{m}\text{-a.e. on } C, \text{ for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

Proof. By definition of uniform structure, we can find $\mathcal{V} \in \mathfrak{U}_{\tau, \mathbf{d}}$ such that $\mathcal{V} \circ \mathcal{V} \subseteq \mathcal{U}$, where we set

$$\mathcal{V} \circ \mathcal{V} := \{(x, z) \in X \times X \mid (x, y), (y, z) \in \mathcal{V} \text{ for some } y \in X\}.$$

Fix any $\varepsilon > 0$ and $f \in \text{Lip}_b(X, \tau, \mathbf{d})$. Since \mathbf{m} is a Radon measure, we can find a sequence $(K_n)_n$ of pairwise disjoint τ -compact subsets of X such that $\text{Osc}_{K_n}(f) \leq \varepsilon$ for every $n \in \mathbb{N}$ and $\mathbf{m}(X \setminus \bigcup_{n \in \mathbb{N}} K_n) = 0$. Now fix $n \in \mathbb{N}$. Given any $x \in K_n \cap C$, we can find a τ -closed τ -neighbourhood F_n^x of x such that $F_n^x \subseteq \mathcal{V}[x]$. Since $K_n \cap C$ is τ -compact, there exist $k(n) \in \mathbb{N}$ and $x_{n,1}, \dots, x_{n,k(n)} \in K_n \cap C$ such that $K_n \cap C \subseteq \bigcup_{i=1}^{k(n)} F_{n,i}$, where we set $F_{n,i} := F_n^{x_{n,i}}$. Denote also $K_{n,i} := K_n \cap C \cap F_{n,i}$ for every $i = 1, \dots, k(n)$. Since $K_{n,i}$ is τ -compact, by applying Corollary 3.3 we obtain a function $\tilde{f}_{n,i} \in \text{Lip}_b(X, \tau, \mathbf{d})$ such that

$$\tilde{f}_{n,i}|_{K_{n,i}} = f|_{K_{n,i}}, \quad \text{Lip}(\tilde{f}_{n,i}, \mathbf{d}) = \text{Lip}(f, K_{n,i}, \mathbf{d}), \quad \text{Osc}_X(\tilde{f}_{n,i}) = \text{Osc}_{K_{n,i}}(f) \leq \varepsilon.$$

Next, we define the function $f_{n,i} \in \text{Lip}_b(X, \tau, \mathbf{d})$ as $f_{n,i} := \tilde{f}_{n,i} - \inf_X \tilde{f}_{n,i}$. Note that

$$\text{Lip}(f_{n,i}, \mathbf{d}) = \text{Lip}(f, K_{n,i}, \mathbf{d}), \quad \|f_{n,i}\|_{C_b(X, \tau)} \leq \varepsilon.$$

Therefore, the locality of b ensures that the following inequalities hold for \mathbf{m} -a.e. point $x \in K_{n,i}$:

$$\begin{aligned} |b(f)|(x) &= |b(\tilde{f}_{n,i})|(x) = |b(f_{n,i})|(x) \leq g(x) \|f_{n,i}\|_{\text{Lip}_b(X, \tau, \mathbf{d})} \leq g(x) (\text{Lip}(f, K_{n,i}, \mathbf{d}) + \varepsilon) \\ &\leq g(x) (\text{Lip}(f, C \cap \mathcal{V}[x_{n,i}], \mathbf{d}) + \varepsilon) \leq g(x) (\text{Lip}(f, C \cap \mathcal{U}[x], \mathbf{d}) + \varepsilon). \end{aligned}$$

By the arbitrariness of $n \in \mathbb{N}$ and $i = 1, \dots, k(n)$, it follows that $|b(f)| \leq g(\text{Lip}(f, C \cap \mathcal{U}[\cdot], \mathbf{d}) + \varepsilon)$ holds \mathbf{m} -a.e. on C . Thanks to the arbitrariness of $\varepsilon > 0$, we thus conclude that (4.9) is verified.

Finally, assume that the restriction τ_C of the topology τ to C is metrisable. Recalling (2.24), we can find a sequence $(\mathcal{U}_n)_{n \in \mathbb{N}} \subseteq \mathfrak{B}_{\tau, \mathbf{d}}$ such that $\{\mathcal{U}_n|_{C \times C} : n \in \mathbb{N}\}$

$\mathbb{N}\} \subseteq \mathfrak{B}_{\tau_C, d_C}$ is a basis of entourages for $\mathfrak{U}_{\tau_C, d_C}$. Given that $(\mathcal{U}_n|_{C \times C})[x] = C \cap \mathcal{U}_n[x]$ and $\text{lip}_{d_C}(f|_C)(x) = \inf_{n \in \mathbb{N}} \text{Lip}(f, C \cap \mathcal{U}_n[x], d)$ hold for every $x \in C$, we have that the inequality in (4.10) follows from (4.9). \square

Theorem 4.16. (Relation between Weaver and Di Marino derivations) *Let $\mathbb{X} = (X, \tau, d, \mathbf{m})$ be an e.m.t.m. space such that \mathbf{m} is separable. Then it holds that*

$$\text{Der}_1^\infty(\mathbb{X}) \subseteq \mathcal{X}(\mathbb{X})$$

and $|b|_W \leq |b|$ holds \mathbf{m} -a.e. on X for every $f \in \text{Der}_1^\infty(\mathbb{X})$. Assuming in addition that τ is metrisable on all τ -compact subsets of X , we also have that

$$\mathcal{X}(\mathbb{X}) \subseteq \text{Der}^\infty(\mathbb{X})$$

and $|b|_W = |b|$ holds \mathbf{m} -a.e. on X for every $b \in \mathcal{X}(\mathbb{X})$.

Proof. Assume \mathbf{m} is separable and fix $b \in \text{Der}_1^\infty(\mathbb{X})$. As $|b(f)| \leq |b| \text{lip}_d(f) \leq \|b\|_{L^\infty(\mathbf{m})} \text{Lip}(f, d)$ holds \mathbf{m} -a.e. on X for every $f \in \text{Lip}_b(X, \tau, d)$, we know from Lemma 4.11 that $b \in \mathcal{X}(\mathbb{X})$. Moreover, the \mathbf{m} -a.e. inequalities $|b(f)| \leq |b| \text{lip}_d(f) \leq \|f\|_{\text{Lip}_b(X, \tau, d)} |b|$ imply that $|b|_W \leq |b|$ \mathbf{m} -a.e. on X .

Now, assume in addition that τ is metrisable on all τ -compact sets and fix any $b \in \mathcal{X}(\mathbb{X})$. As \mathbf{m} is a Radon measure, we find a sequence $(K_n)_n$ of τ -compact sets such that $\mathbf{m}(X \setminus \bigcup_{n \in \mathbb{N}} K_n) = 0$. Since b is local by Theorem 4.6, and τ is metrisable on K_n , we deduce from Proposition 4.15 that

$$|b(f)| \leq |b|_W \text{lip}_{d_{K_n}}(f|_{K_n}) \leq |b|_W \text{lip}_d(f) \quad \text{holds } \mathbf{m}\text{-a.e. on } K_n,$$

for every $f \in \text{Lip}_b(X, \tau, d)$. By the arbitrariness of $n \in \mathbb{N}$, it follows that $|b(f)| \leq |b|_W \text{lip}_d(f)$ holds \mathbf{m} -a.e. on X for every $f \in \text{Lip}_b(X, \tau, d)$. This proves that $b \in \text{Der}^\infty(\mathbb{X})$ and $|b| \leq |b|_W$, thus yielding the statement. \square

We close this section with a result that illustrates the relation between derivations on an e.m.t.m. space and derivations on its compactification. We denote by $\iota^*: \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{d}) \rightarrow \text{Lip}_b(X, \tau, d)$ the inverse of the Gelfand transform $\Gamma: \text{Lip}_b(X, \tau, d) \rightarrow \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{d})$, cf. with Lemma 2.13. With the same symbol ι^* we denote the linear bijection $\iota^*: L^0(\hat{\mathbf{m}}) \rightarrow L^0(\mathbf{m})$ that maps the $\hat{\mathbf{m}}$ -a.e. equivalence class of a Borel function $\hat{f}: \hat{X} \rightarrow \mathbb{R}$ to the \mathbf{m} -a.e. equivalence class of $\hat{f} \circ \iota: X \rightarrow \mathbb{R}$, whereas $\iota_*: L^0(\mathbf{m}) \rightarrow L^0(\hat{\mathbf{m}})$ denotes its inverse.

Proposition 4.17. (Derivations on the compactification) *Let $\mathbb{X} = (X, \tau, d, \mathbf{m})$ be an e.m.t.m. space. Denote by $\hat{\mathbb{X}} = (\hat{X}, \hat{\tau}, \hat{d}, \hat{\mathbf{m}})$ its compactification, with embedding $\iota: X \hookrightarrow \hat{X}$. We define the operator $\iota_*: \text{Der}(\mathbb{X}) \rightarrow \text{Der}(\hat{\mathbb{X}})$ as*

$$(\iota_* b)(\hat{f}) := \iota_*(b(\iota^* \hat{f})) \in L^0(\hat{\mathbf{m}}) \quad \text{for every } b \in \text{Der}(\mathbb{X}) \text{ and } \hat{f} \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{d}).$$

Then ι_* is a linear bijection such that $\iota_*(hb) = (\iota_* h)(\iota_* b)$ for every $b \in \text{Der}(\mathbb{X})$ and $h \in L^0(\mathbf{m})$. Moreover, the following properties are satisfied:

- i) $\iota_*(D(\text{div}; \mathbb{X})) = D(\text{div}; \hat{\mathbb{X}})$ and $\text{div}(\iota_* b) = \iota_*(\text{div}(b))$ for every $b \in D(\text{div}; \mathbb{X})$.
- ii) $\iota_*(\mathcal{X}(\mathbb{X})) \subseteq \mathcal{X}(\hat{\mathbb{X}})$ and $|\iota_* b|_W = \iota_* |b|_W$ for every $b \in \mathcal{X}(\mathbb{X})$.
- iii) Given any derivation $b \in \text{Der}(\mathbb{X})$, we have that b is local if and only if $\iota_* b$ is local.
- iv) $\iota_*(\text{Der}^0(\mathbb{X})) \subseteq \text{Der}^0(\hat{\mathbb{X}})$ and $|\iota_* b| \leq \iota_* |b|$ for every $b \in \text{Der}^0(\mathbb{X})$. In particular, we have that $\iota_*(\text{Der}^q(\mathbb{X})) \subseteq \text{Der}^q(\hat{\mathbb{X}})$ and $\iota_*(\text{Der}_r^q(\mathbb{X})) \subseteq \text{Der}_r^q(\hat{\mathbb{X}})$ for every $q, r \in [1, \infty]$.

- v) Assume in addition that τ is metrisable on all τ -compact subsets of X . Then it holds that $\iota_*(\text{Der}_q^q(\mathbb{X})) = \text{Der}_q^q(\hat{\mathbb{X}})$ for every $q \in [1, \infty]$, and that $|\iota_*b| = \iota_*|b|$ for every $b \in \text{Der}_q^q(\mathbb{X})$.

Proof. Let $b \in \text{Der}(\mathbb{X})$ be given. The map $\iota_*b: \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}}) \rightarrow L^0(\hat{\mathbf{m}})$ is linear (as a composition of linear maps). Moreover, for every $\hat{f}, \hat{g} \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ we have that

$$(\iota_*b)(\hat{f}\hat{g}) = \iota_*(b((\iota^*\hat{f})(\iota^*\hat{g}))) = \iota_*((\iota^*\hat{f})b(\iota^*\hat{g}) + (\iota^*\hat{g})b(\iota^*\hat{f})) = \hat{f}(\iota_*b)(\hat{g}) + \hat{g}(\iota_*b)(\hat{f}),$$

so that ι_*b satisfies the Leibniz rule, thus $\iota_*b \in \text{Der}(\hat{\mathbb{X}})$. The resulting map $\iota_*: \text{Der}(\mathbb{X}) \rightarrow \text{Der}(\hat{\mathbb{X}})$ is clearly linear. Similar arguments show that

$$(\iota^*\hat{b})(f) := \iota^*(\hat{b}(\Gamma(f))) \in L^0(\mathbf{m}) \quad \text{for every } \hat{b} \in \text{Der}(\hat{\mathbb{X}}) \text{ and } f \in \text{Lip}_b(X, \tau, \mathbf{d})$$

defines a linear operator $\iota^*: \text{Der}(\hat{\mathbb{X}}) \rightarrow \text{Der}(\mathbb{X})$ whose inverse is the map $\iota_*: \text{Der}(\mathbb{X}) \rightarrow \text{Der}(\hat{\mathbb{X}})$, thus in particular the latter is a bijection. For any $b \in \text{Der}(\mathbb{X})$ and $h \in L^0(\mathbf{m})$, we also have that

$$(\iota_*(hb))(\hat{f}) = \iota_*(hb(\iota^*\hat{f})) = (\iota_*h)\iota_*(b(\iota^*\hat{f})) = (\iota_*h)(\iota_*b)(\hat{f})$$

for every $\hat{f} \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$, which gives that $\iota_*(hb) = (\iota_*h)(\iota_*b)$. Let us now pass to the verification of i), ii), iii), iv) and v).

i) Let $b \in \text{Der}(\mathbb{X})$ be a given derivation. Note that $b(f) \in L^1(\mathbf{m})$ for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ if and only if $(\iota_*b)(\hat{f}) \in L^1(\hat{\mathbf{m}})$ for every $\hat{f} \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$. Moreover, if $b \in D(\text{div}; \mathbb{X})$, then

$$\int (\iota_*b)(\hat{f}) d\hat{\mathbf{m}} = \int b(\iota^*\hat{f}) d\mathbf{m} = - \int (\iota^*\hat{f}) \text{div}(b) d\mathbf{m} = - \int \hat{f} \iota_*(\text{div}(b)) d\hat{\mathbf{m}}$$

holds for every $\hat{f} \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$, so that $\iota_*b \in D(\text{div}; \hat{\mathbb{X}})$ and $\text{div}(\iota_*b) = \iota_*(\text{div}(b))$. Conversely, if we assume $\iota_*b \in D(\text{div}; \hat{\mathbb{X}})$, then similar computations show that $b \in D(\text{div}; \mathbb{X})$. This proves i).

ii) If $b \in \mathcal{X}(\mathbb{X})$, then $(\iota_*b)(\hat{f}) = \iota_*(b(\iota^*\hat{f})) \in L^\infty(\hat{\mathbf{m}})$ for every $\hat{f} \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$. Moreover, assuming that $(\hat{f}_n)_n \subseteq \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ and $\hat{f} \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ satisfy

$$\sup_{n \in \mathbb{N}} \|\hat{f}_n\|_{\text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})} < +\infty \quad \text{and} \quad \hat{f}(\varphi) = \lim_n \hat{f}_n(\varphi)$$

for every $\varphi \in \hat{X}$, we have $\sup_{n \in \mathbb{N}} \|\iota^*\hat{f}_n\|_{\text{Lip}_b(X, \tau, \mathbf{d})} < +\infty$ by Lemma 2.13 and $(\iota^*\hat{f})(x) = \hat{f}(\iota(x)) = \lim_n \hat{f}_n(\iota(x)) = \lim_n (\iota^*\hat{f}_n)(x)$ for every $x \in X$. Hence, the weak*-type sequential continuity of b ensures that $b(\iota^*\hat{f}_n) \xrightarrow{*} b(\iota^*\hat{f})$ weakly* in $L^\infty(\mathbf{m})$, so that accordingly

$$(\iota_*b)(\hat{f}_n) = \iota_*(b(\iota^*\hat{f}_n)) \xrightarrow{*} \iota_*(b(\iota^*\hat{f})) = (\iota_*b)(\hat{f}) \quad \text{weakly* in } L^\infty(\hat{\mathbf{m}}).$$

This shows that $\iota_*b \in \mathcal{X}(\hat{\mathbb{X}})$. Finally, it follows from the $\hat{\mathbf{m}}$ -a.e. inequalities

$$\begin{aligned} |(\iota_*b)(\hat{f})| &= \iota_*|b(\iota^*\hat{f})| \leq \|\iota^*\hat{f}\|_{\text{Lip}_b(X, \tau, \mathbf{d})} \iota_*|b|_W = \|\hat{f}\|_{\text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})} \iota_*|b|_W, \\ \iota_*|b(f)| &= |(\iota_*b)(\Gamma(f))| \leq \|\Gamma(f)\|_{\text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})} \iota_*|b|_W = \|f\|_{\text{Lip}_b(X, \tau, \mathbf{d})} \iota_*|b|_W, \end{aligned}$$

which hold for all $\hat{f} \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ and $f \in \text{Lip}_b(X, \tau, \mathbf{d})$, that $|\iota_*b|_W = \iota_*|b|_W$. This proves ii).

iii) Note that $\mathbb{1}_{\{\Gamma(f)=0\}} = \iota_* \mathbb{1}_{\{f=0\}}$ holds $\hat{\mathbf{m}}$ -a.e. on \hat{X} for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$. In particular,

$$\mathbb{1}_{\{\Gamma(f)=0\}}(\iota_* b)(\Gamma(f)) = \iota_*(\mathbb{1}_{\{f=0\}}b(f)) \quad \text{holds } \hat{\mathbf{m}}\text{-a.e. on } \hat{X},$$

whence it follows that $(\iota_* b)(\Gamma(f)) = 0$ $\hat{\mathbf{m}}$ -a.e. on $\{\Gamma(f) = 0\}$ if and only if $b(f) = 0$ \mathbf{m} -a.e. on $\{f = 0\}$. As $\Gamma: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$ is bijective, we deduce that b is local if and only if $\iota_* b$ is local.

iv) If $b \in \text{Der}^0(\mathbb{X})$, then by applying (2.15) we obtain the $\hat{\mathbf{m}}$ -a.e. inequalities

$$|(\iota_* b)(\hat{f})| = \iota_* |b(\iota^* \hat{f})| \leq (\iota_* |b|)(\iota_* \text{lip}_{\mathbf{d}}(\iota^* \hat{f})) \leq (\iota_* |b|) \text{lip}_{\hat{\mathbf{d}}}(\hat{f})$$

for every $\hat{f} \in \text{Lip}_b(\hat{X}, \hat{\tau}, \hat{\mathbf{d}})$, whence it follows that $\iota_* b \in \text{Der}^0(\hat{\mathbb{X}})$ and $|\iota_* b| \leq \iota_* |b|$.

v) Fix any $\hat{b} \in \text{Der}_q^q(\hat{\mathbb{X}})$. We know from Corollary 4.14 if $q < \infty$, or from Theorems 4.16 and 4.6 if $q = \infty$, that \hat{b} is a local derivation. For any $f \in \text{Lip}_b(X, \tau, \mathbf{d})$, we have the \mathbf{m} -a.e. inequalities

$$\begin{aligned} |(\iota^* \hat{b})(f)| &= \iota^* |\hat{b}(\Gamma(f))| \leq (\iota^* |\hat{b}|)(\iota^* \text{lip}_{\hat{\mathbf{d}}}(\Gamma(f))) \\ &\leq \text{Lip}(\Gamma(f), \hat{\mathbf{d}})(\iota^* |\hat{b}|) \leq \|f\|_{\text{Lip}_b(X, \tau, \mathbf{d})} \iota^* |\hat{b}|. \end{aligned}$$

Therefore, Proposition 4.15 guarantees that for every τ -compact set $K \subseteq X$ we have that

$$|(\iota^* \hat{b})(f)| \leq (\iota^* |\hat{b}|) \text{lip}_{\mathbf{d}_K}(f|_K) \quad \text{holds } \mathbf{m}\text{-a.e. on } K, \text{ for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

Since the Radon measure \mathbf{m} is concentrated on the union $\bigcup_n K_n$ of countably many τ -compact subsets $(K_n)_{n \in \mathbb{N}}$ of X , we deduce that $|(\iota^* \hat{b})(f)| \leq (\iota^* |\hat{b}|) \text{lip}_{\mathbf{d}}(f)$ \mathbf{m} -a.e. on X , so that $\iota^* \hat{b} \in \text{Der}^q(\mathbb{X})$ and $|\iota^* \hat{b}| \leq \iota^* |\hat{b}|$. Taking also i) and iv) into account, we can finally conclude that v) holds. \square

5. Sobolev spaces via Lipschitz derivations

In this section, we discuss different notions of metric Sobolev spaces in the extended setting. To begin with, we briefly remind already-known results and we outline our new contributions. The mutual connections between the three notions of metric Sobolev space $H^{1,p}(\mathbb{X})$, $B^{1,p}(\mathbb{X})$ and $N^{1,p}(\mathbb{X})$ were studied in [42]. More specifically:

- As we recalled in Theorem 2.34, the equivalence $H^{1,p}(\mathbb{X}) = B^{1,p}(\mathbb{X})$ when $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ is an e.m.t.m. space with (X, \mathbf{d}) complete was achieved in [42, Theorem 5.2.7].
- Assuming in addition that (X, τ) is a Souslin space, it also holds that $B^{1,p}(\mathbb{X}) = N^{1,p}(\mathbb{X})$, as it was proved in [42, Corollary 5.1.26]; cf. with Remark 5.7 below.

In Definition 5.1, we introduce the metric Sobolev space $W^{1,p}(\mathbb{X})$ defined in terms of the Di Marino derivations with divergence that we studied in Section 4.2. For an arbitrary e.m.t.m. space \mathbb{X} —in particular, without any completeness assumption—we obtain the following results:

- In Theorem 5.4, we prove that $H^{1,p}(\mathbb{X}) = W^{1,p}(\mathbb{X})$.
- In Theorem 5.9, we prove that $W^{1,p}(\mathbb{X}) \subseteq B^{1,p}(\mathbb{X})$.

Accordingly, for a \mathbf{d} -complete e.m.t.m. space \mathbb{X} we have that $W^{1,p}(\mathbb{X}) = B^{1,p}(\mathbb{X})$. By contrast, in the non- \mathbf{d} -complete case the inclusion $W^{1,p}(\mathbb{X}) \subseteq B^{1,p}(\mathbb{X})$ can be strict (cf. with the example that is presented at the end of Section 2.5).

5.1. The space $W^{1,p}$. We introduce a new notion of metric Sobolev space $W^{1,p}(\mathbb{X})$ over an e.m.t.m. space \mathbb{X} , defined via an integration-by-parts formula in duality with the space $\text{Der}_q^q(\mathbb{X})$ of Di Marino derivations with divergence. Our definition generalises Di Marino's notion of $W^{1,p}$ space for metric-measure spaces ([18, Definition 1.5], [17, Definition 7.1.4]) to the extended setting.

Definition 5.1. (The Sobolev space $W^{1,p}(\mathbb{X})$) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $p, q \in (1, \infty)$ be conjugate exponents. Then we define the *Sobolev space* $W^{1,p}(\mathbb{X})$ as the set of all functions $f \in L^p(\mathbf{m})$ for which there exists a linear operator $L_f: \text{Der}_q^q(\mathbb{X}) \rightarrow L^1(\mathbf{m})$ such that:

- i) There exists a function $g \in L^q(\mathbf{m})^+$ such that $|L_f(b)| \leq g|b|$ for every $b \in \text{Der}_q^q(\mathbb{X})$.
- ii) $L_f(hb) = h L_f(b)$ for every $h \in \text{Lip}_b(X, \tau, \mathbf{d})$ and $b \in \text{Der}_q^q(\mathbb{X})$.
- iii) The following integration-by-parts formula holds:

$$\int L_f(b) \, d\mathbf{m} = - \int f \, \text{div}(b) \, d\mathbf{m} \quad \text{for every } b \in \text{Der}_q^q(\mathbb{X}).$$

Given any function $f \in W^{1,p}(\mathbb{X})$, we define its *minimal p -weak gradient* $|Df| \in L^p(\mathbf{m})^+$ as

$$|Df| := \bigwedge \{g \in L^p(\mathbf{m})^+ \mid |L_f(b)| \leq g|b| \quad \forall b \in \text{Der}_q^q(\mathbb{X})\} = \bigvee_{b \in \text{Der}_q^q(\mathbb{X})} \mathbb{1}_{\{|b|>0\}} \frac{|L_f(b)|}{|b|}.$$

We use the notation $|Df|$ (instead e.g. of $|Df|_W$) because the space $W^{1,p}(\mathbb{X})$ will be our main object of study in the rest of the paper. Note that $|L_f(b)| \leq |Df||b|$ holds \mathbf{m} -a.e. for every $f \in W^{1,p}(\mathbb{X})$ and $b \in \text{Der}_q^q(\mathbb{X})$. It can also be readily checked that

$$\|f\|_{W^{1,p}(\mathbb{X})} := (\|f\|_{L^p(\mathbf{m})}^p + \| |Df| \|_{L^p(\mathbf{m})}^p)^{1/p} \quad \text{for every } f \in W^{1,p}(\mathbb{X})$$

defines a complete norm on $W^{1,p}(\mathbb{X})$, so that $(W^{1,p}(\mathbb{X}), \|\cdot\|_{W^{1,p}(\mathbb{X})})$ is a Banach space.

Some more comments on the Sobolev space $W^{1,p}(\mathbb{X})$:

- Since $\int h L_f(b) \, d\mathbf{m} = - \int f \, \text{div}(hb) \, d\mathbf{m}$ for every $h \in \text{Lip}_b(X, \tau, \mathbf{d})$, and $\text{Lip}_b(X, \tau, \mathbf{d})$ is weakly* dense in $L^\infty(\mathbf{m})$ by (2.8), the map $L_f: \text{Der}_q^q(\mathbb{X}) \rightarrow L^1(\mathbf{m})$ is uniquely determined.
- It easily follows from the uniqueness of L_f that $W^{1,p}(\mathbb{X}) \ni f \mapsto L_f$ is a linear operator, whose target is the vector space of all linear operators from $\text{Der}_q^q(\mathbb{X})$ to $L^1(\mathbf{m})$.
- $\text{Lip}_b(X, \tau, \mathbf{d}) \subseteq W^{1,p}(\mathbb{X})$ and $L_f(b) = b(f)$ for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ and $b \in \text{Der}_q^q(\mathbb{X})$, thus in particular $|Df| \leq \text{lip}_d(f)$ holds \mathbf{m} -a.e. on X for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$.
- For any $f \in W^{1,p}(\mathbb{X})$, the operator $L_f: \text{Der}_q^q(\mathbb{X}) \rightarrow L^1(\mathbf{m})$ can be uniquely extended to an element $L_f \in L_{\text{Lip}}^q(T\mathbb{X})^*$, whose pointwise norm $|L_f|$ coincides with $|Df|$.

Example 5.2. Let $(X, \tau, \mathbf{d}_{\text{discr}})$ be a ‘purely-topological’ e.m.t. space (as in Example 2.14) together with a finite Radon measure \mathbf{m} , so that $\mathbb{X} := (X, \tau, \mathbf{d}_{\text{discr}}, \mathbf{m})$ is an e.m.t.m. space. For any given function $f \in \text{Lip}_b(X, \tau, \mathbf{d}_{\text{discr}})$, we have that $\text{Lip}(f, U, \mathbf{d}_{\text{discr}}) = \text{Osc}_U(f)$ for every $U \in \tau$, thus the τ -continuity of f implies that $\text{lip}_{\mathbf{d}_{\text{discr}}}(f)(x) = 0$ for all $x \in X$. In particular, $\text{Der}_q^q(\mathbb{X}) = \text{Der}_q(\mathbb{X}) = \{0\}$ for every $q \in [1, \infty]$, whence it follows that $W^{1,p}(\mathbb{X}) = L^p(\mathbf{m})$ for every $p \in (1, \infty)$, with $L_f = 0$ and thus $|Df| = 0$ for every $f \in W^{1,p}(\mathbb{X})$. ■

5.2. The equivalence $H^{1,p} = W^{1,p}$. The goal of this section is to prove that the metric Sobolev spaces $W^{1,p}(\mathbb{X})$ and $H^{1,p}(\mathbb{X})$ coincide on *any* e.m.t.m. space. In the setting of (complete) metric-measure spaces, such equivalence was previously known (see [18, Section 2] or [17, Section 7.2]), but the result seems to be new for non-complete metric-measure spaces; see Theorem 5.4 below. Our proof of the inclusion $H^{1,p}(\mathbb{X}) \subseteq W^{1,p}(\mathbb{X})$ follows along the lines of [18, Section 2.1], whereas our proof of the converse inclusion (inspired by [38, Theorem 3.3]) relies on a new argument using tools in Convex Analysis. The latter is robust enough to be potentially useful in other contexts.

Fix an e.m.t.m. space $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ and $p \in (1, \infty)$. The differential $d: H^{1,p}(\mathbb{X}) \rightarrow L^p(T^*\mathbb{X})$ given by Theorem 2.25 induces an unbounded operator $d: L^p(\mathbf{m}) \rightarrow L^p(T^*\mathbb{X})$ whose domain is $D(d) = H^{1,p}(\mathbb{X})$; see Appendix B. As $\text{Lip}_b(X, \tau, \mathbf{d})$ is contained in $H^{1,p}(\mathbb{X})$, and it is dense in $L^p(\mathbf{m})$ by (2.8), we deduce that d is densely defined, thus its adjoint operator $d^*: L^p(T^*\mathbb{X})' \rightarrow L^q(\mathbf{m})$ is well posed. Letting $I_{p,\mathbb{X}}: L^q(T\mathbb{X}) \rightarrow L^p(T^*\mathbb{X})'$ be as in (2.26), the operator d^* is characterised by

$$(5.1) \quad \int f d^*V \, d\mathbf{m} = \langle V, df \rangle = \int df(I_{p,\mathbb{X}}^{-1}(V)) \, d\mathbf{m}$$

for every $f \in H^{1,p}(\mathbb{X})$ and $V \in D(d^*)$. The next result shows that each element of $D(d^*)$ induces a Di Marino derivation with divergence:

Lemma 5.3. (Derivation induced by a vector field) *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $q \in (1, \infty)$. Fix any $v \in L^q(T\mathbb{X})$. Define the operator $b_v: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow L^1(\mathbf{m})$ as*

$$b_v(f) := df(v) \quad \text{for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}).$$

Then it holds that $b_v \in \text{Der}^q_q(\mathbb{X})$ and $|b_v| \leq |v|$. If in addition $V := I_{p,\mathbb{X}}(v) \in D(d^)$, then*

$$b_v \in \text{Der}^q_q(\mathbb{X}), \quad \text{div}(b_v) = -d^*V.$$

Proof. The map b_v is linear by construction and satisfies the Leibniz rule (4.1) by (2.25), thus it is a Lipschitz derivation. Since $|b_v(f)| \leq |v||Df|_H \leq |v|\text{lip}_d(f)$ holds \mathbf{m} -a.e. on X , we deduce that $b_v \in \text{Der}^q_q(\mathbb{X})$ and $|b_v| \leq |v|$. Now, let us assume that $V := I_{p,\mathbb{X}}(v) \in D(d^*)$. Then (5.1) yields

$$\int b_v(f) \, d\mathbf{m} = \int df(v) \, d\mathbf{m} = \int f d^*V \, d\mathbf{m} \quad \text{for every } f \in \text{Lip}_b(X, \tau, \mathbf{d}),$$

whence it follows that $b_v \in \text{Der}^q_q(\mathbb{X})$ and $\text{div}(b_v) = -d^*V$. Hence, the statement is achieved. \square

We now pass to the equivalence result between $W^{1,p}$ and $H^{1,p}$. We will use ultralimit techniques (see Appendix A) to obtain one of the two inclusions, and tools in Convex Analysis (see Appendix B) to prove the other one.

Theorem 5.4. ($H^{1,p} = W^{1,p}$) *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $p \in (1, \infty)$. Then*

$$H^{1,p}(\mathbb{X}) = W^{1,p}(\mathbb{X})$$

and it holds that $|Df| = |Df|_H$ for every $f \in W^{1,p}(\mathbb{X})$.

Proof. Fix a non-principal ultrafilter ω on \mathbb{N} . Let $f \in H^{1,p}(\mathbb{X})$ be a given function. Take a sequence $(f_n)_n \subseteq \text{Lip}_b(X, \tau, \mathbf{d})$ such that $f_n \rightarrow f$ and $\text{lip}_d(f_n) \rightarrow |Df|_H$ strongly in $L^p(\mathbf{m})$. Up to passing to a non-relabelled subsequence, we can also assume that there exists a function $h \in L^p(\mathbf{m})^+$ such that $\text{lip}_d(f_n) \leq h$ holds \mathbf{m} -a.e. for every

$n \in \mathbb{N}$. In particular, $|b(f_n)| \leq |b|h \in L^1(\mathfrak{m})$ holds for every $b \in \text{Der}_q^q(\mathbb{X})$ and $n \in \mathbb{N}$. Therefore, by virtue of Lemma A.3 the following map is well defined:

$$L_f(b) := \omega\text{-}\lim_n b(f_n) \in L^1(\mathfrak{m}) \quad \text{for every } b \in \text{Der}_q^q(\mathbb{X}),$$

where the ultralimit is intended with respect to the weak topology of $L^1(\mathfrak{m})$. Moreover:

- Fix $\lambda_1, \lambda_2 \in \mathbb{R}$ and $b_1, b_2 \in \text{Der}_q^q(\mathbb{X})$. Since $L^1(\mathfrak{m}) \times L^1(\mathfrak{m}) \ni (g_1, g_2) \mapsto \lambda_1 g_1 + \lambda_2 g_2 \in L^1(\mathfrak{m})$ is continuous if the domain is endowed with the product of the weak topologies and the codomain with the weak topology, by applying Lemma A.1 we obtain that

$$\begin{aligned} L_f(\lambda_1 b_1 + \lambda_2 b_2) &= \omega\text{-}\lim_n (\lambda_1 b_1(f_n) + \lambda_2 b_2(f_n)) \\ &= \lambda_1 (\omega\text{-}\lim_n b_1(f_n)) + \lambda_2 (\omega\text{-}\lim_n b_2(f_n)) = \lambda_1 L_f(b_1) + \lambda_2 L_f(b_2). \end{aligned}$$

This proves that $L_f: \text{Der}_q^q(\mathbb{X}) \rightarrow L^1(\mathfrak{m})$ is a linear operator.

- Fix $b \in \text{Der}_q^q(\mathbb{X})$. Lemma A.3 and the weak continuity of $L^p(\mathfrak{m}) \ni g \mapsto |b|g \in L^1(\mathfrak{m})$ yield

$$|L_f(b)| = |\omega\text{-}\lim_n b(f_n)| \leq \omega\text{-}\lim_n |b(f_n)| \leq \omega\text{-}\lim_n (|b| \text{lip}_d(f_n)) = |b| |Df|_H.$$

- Fix $b \in \text{Der}_q^q(\mathbb{X})$ and $h \in \text{Lip}_b(X, \tau, d)$. Then Lemma A.1 implies that

$$L_f(hb) = \omega\text{-}\lim_n (h b(f_n)) = h(\omega\text{-}\lim_n b(f_n)) = h L_f(b).$$

- Since $L^1(\mathfrak{m}) \ni g \mapsto \int g \, d\mathfrak{m} \in \mathbb{R}$ is weakly continuous and $L^p(\mathfrak{m}) \ni \tilde{f} \mapsto \int \tilde{f} \, \text{div}(b) \, d\mathfrak{m} \in \mathbb{R}$ is strongly continuous for every $b \in \text{Der}_q^q(\mathbb{X})$, by applying Lemma A.1 we obtain that

$$\int L_f(b) \, d\mathfrak{m} = \omega\text{-}\lim_n \int b(f_n) \, d\mathfrak{m} = -\omega\text{-}\lim_n \int f_n \, \text{div}(b) \, d\mathfrak{m} = - \int f \, \text{div}(b) \, d\mathfrak{m}.$$

All in all, we showed that L_f verifies the conditions of Definition 5.1 and that $|L_f(b)| \leq |Df|_H |b|$ holds for every $b \in \text{Der}_q^q(\mathbb{X})$. Consequently, we can conclude that $f \in W^{1,p}(\mathbb{X})$ and $|Df| \leq |Df|_H$.

Conversely, let $f \in W^{1,p}(\mathbb{X})$ be given. Since \mathcal{E}_p is convex and $L^p(\mathfrak{m})$ -lower semi-continuous, we have that $\mathcal{E}_p = \mathcal{E}_p^{**}$ by the Fenchel–Moreau theorem. Note also that $\mathcal{E}_p = \frac{1}{p} \|\cdot\|_{L^p(T^*\mathbb{X})}^p \circ d$. Therefore, by applying Theorem B.1, (B.1), Lemma 5.3 and Young’s inequality, we obtain that

$$\begin{aligned} \mathcal{E}_p(f) &= \mathcal{E}_p^{**}(f) = \sup_{g \in L^q(\mathfrak{m})} \left(\int g f \, d\mathfrak{m} - \mathcal{E}_p^*(g) \right) \\ &= \sup_{g \in L^q(\mathfrak{m})} \left(\int g f \, d\mathfrak{m} - \left(\frac{1}{p} \|\cdot\|_{L^p(T^*\mathbb{X})}^p \circ d \right)^*(g) \right) \\ &= \sup_{g \in L^q(\mathfrak{m})} \left(\int g f \, d\mathfrak{m} - \inf \left\{ \frac{1}{q} \|V\|_{L^p(T^*\mathbb{X})'}^q \mid V \in D(d^*), d^*V = g \right\} \right) \\ &\leq \sup_{g \in L^q(\mathfrak{m})} \left(\int g f \, d\mathfrak{m} - \inf \left\{ \frac{1}{q} \|b\|_{\text{Der}_q^q(\mathbb{X})}^q \mid b \in \text{Der}_q^q(\mathbb{X}), -\text{div}(b) = g \right\} \right) \\ &= \sup_{b \in \text{Der}_q^q(\mathbb{X})} \left(- \int f \, \text{div}(b) \, d\mathfrak{m} - \frac{1}{q} \|b\|_{\text{Der}_q^q(\mathbb{X})}^q \right) = \sup_{b \in \text{Der}_q^q(\mathbb{X})} \int L_f(b) - \frac{1}{q} |b|^q \, d\mathfrak{m} \end{aligned}$$

$$\leq \sup_{b \in \text{Der}_q^q(\mathbb{X})} \int |Df| |b| - \frac{1}{q} |b|^q \, d\mathbf{m} \leq \frac{1}{p} \int |Df|^p \, d\mathbf{m} < +\infty.$$

It follows that $f \in H^{1,p}(\mathbb{X})$ and $\int |Df|_H^p \, d\mathbf{m} = p \mathcal{E}_p(f) \leq \int |Df|^p \, d\mathbf{m}$. Since we also know from the first part of the proof that $|Df| \leq |Df|_H$, we can finally conclude that $W^{1,p}(\mathbb{X}) = H^{1,p}(\mathbb{X})$ and $|Df|_H = |Df|$ for every $f \in W^{1,p}(\mathbb{X})$, thus proving the statement. \square

Example 5.5. (Derivations on abstract Wiener spaces) Let $\mathbb{X}_\gamma := (X, \tau, \mathbf{d}, \gamma)$ be the e.m.t.m. space obtained by equipping an abstract Wiener space (X, γ) with the norm topology τ of X and with the extended distance \mathbf{d} induced by its Cameron–Martin space; see Section 2.3.2. We claim that the space \mathbb{X}_γ is ‘purely non- \mathbf{d} -separable’, meaning that

$$\gamma(S_{\mathbb{X}_\gamma}) = 0.$$

To prove it, we denote by $(H(\gamma), |\cdot|_{H(\gamma)})$ the Cameron–Martin space of (X, γ) . We recall that

$$\mathbf{d}(x, y) = \begin{cases} |x - y|_{H(\gamma)} & \text{if } x, y \in X \text{ and } x - y \in H(\gamma), \\ +\infty & \text{if } x, y \in X \text{ and } x - y \notin H(\gamma), \end{cases}$$

and that $\gamma(x + H(\gamma)) = 0$ for every $x \in X$; see [12]. Hence, if $E \in \mathcal{B}(X, \tau)$ is a given \mathbf{d} -separable subset of X and $(x_n)_n$ is a \mathbf{d} -dense sequence in E , then $E \subseteq \bigcup_{n \in \mathbb{N}} B_1^{\mathbf{d}}(x_n) \subseteq \bigcup_{n \in \mathbb{N}} (x_n + H(\gamma))$ and thus accordingly $\gamma(E) \leq \sum_{n \in \mathbb{N}} \gamma(x_n + H(\gamma)) = 0$, whence it follows that $\gamma(S_{\mathbb{X}_\gamma}) = 0$.

By taking Corollary 4.8 i) into account, we deduce that the unique weakly*-type continuous derivation on \mathbb{X}_γ is the null derivation. Conversely, we know from [42, Example 5.3.14] that $H^{1,p}(\mathbb{X}_\gamma)$ coincides with the usual Sobolev space on \mathbb{X}_γ defined as the completion of *cylindrical functions* [12]. In particular, the identity $W^{1,p}(\mathbb{X}_\gamma) = H^{1,p}(\mathbb{X}_\gamma)$ we proved in Theorem 5.4 guarantees the existence of (many) non-null Di Marino derivations with divergence, and thus (by Lemma 4.11) of non-null weakly*-type sequentially continuous derivations. \blacksquare

5.3. The equivalence $W^{1,p} = B^{1,p}$. In this section, we investigate the relation between the spaces $W^{1,p}(\mathbb{X})$ and $B^{1,p}(\mathbb{X})$. By combining Theorem 5.4 with Theorem 2.34, we see that a sufficient condition for the identity $W^{1,p}(\mathbb{X}) = B^{1,p}(\mathbb{X})$ to hold is the completeness of the extended metric space (X, \mathbf{d}) :

Corollary 5.6. ($W^{1,p} = B^{1,p}$ on complete e.m.t.m. spaces) *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space such that (X, \mathbf{d}) is a complete extended metric space. Let $p \in (1, \infty)$ be given. Then*

$$W^{1,p}(\mathbb{X}) = B^{1,p}(\mathbb{X}).$$

Moreover, it holds that $|Df|_B = |Df|$ for every $f \in W^{1,p}(\mathbb{X})$.

Remark 5.7. (Relation with the Newtonian space $N^{1,p}$) The *Newtonian space* $N^{1,p}(\mathbb{X})$ over an e.m.t.m. space \mathbb{X} has been introduced by Savaré in [42, Definition 5.1.19], thus generalising the notion of Newtonian space for metric-measure spaces introduced by Shanmugalingam in [47]. It follows from Corollary 5.6 and [42, Corollary 5.1.26] that if $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ is an e.m.t.m. space such that (X, \mathbf{d}) is complete and (X, τ) is a *Souslin space* (i.e. the continuous image of a complete separable metric space), then the Sobolev space $W^{1,p}(\mathbb{X})$ is fully consistent with $N^{1,p}(\mathbb{X})$. \blacksquare

On an arbitrary e.m.t.m. space \mathbb{X} , it can happen that the spaces $W^{1,p}(\mathbb{X})$ and $B^{1,p}(\mathbb{X})$ are different, as the example we discussed in the last paragraph of Section 2.5 shows. Nevertheless, we are going to show that every \mathcal{T}_q -test plan π on \mathbb{X} induces a Di Marino derivation with divergence $b_\pi \in \text{Der}_q^q(\mathbb{X})$ (Proposition 5.8), and as a corollary we will prove that $W^{1,p}(\mathbb{X})$ is always contained in $B^{1,p}(\mathbb{X})$ and that $|Df|_B \leq |Df|$ for every $f \in W^{1,p}(\mathbb{X})$ (Theorem 5.9).

For brevity, we denote by \mathcal{L}_1 the restriction of the 1-dimensional Lebesgue measure \mathcal{L}^1 to the unit interval $[0, 1] \subseteq \mathbb{R}$. To any given \mathcal{T}_q -test plan $\pi \in \mathcal{T}_q(\mathbb{X})$, we associate the product measure

$$\hat{\pi} := \pi \otimes \mathcal{L}_1 \in \mathcal{M}_+(\text{RA}(X, d) \times [0, 1]),$$

where the space $\text{RA}(X, d) \times [0, 1]$ is endowed with the product topology.

The next result is inspired by (and generalises) [18, Proposition 2.4] and [7, Proposition 4.10].

Proposition 5.8. (Derivation induced by a \mathcal{T}_q -test plan) *Let $\mathbb{X} = (X, \tau, d, m)$ be an e.m.t.m. space and $q \in (1, \infty)$. Let $\pi \in \mathcal{T}_q(\mathbb{X})$ be given. Then for any $f \in \text{Lip}_b(X, \tau, d)$ we have that*

$$\hat{e}_\#(D_f^+ \hat{\pi}), \hat{e}_\#(D_f^- \hat{\pi}) \ll m, \quad b_\pi(f) := \frac{d\hat{e}_\#(D_f^+ \hat{\pi})}{dm} - \frac{d\hat{e}_\#(D_f^- \hat{\pi})}{dm} \in L^q(m),$$

where \hat{e} denotes the arc-length evaluation map (2.20), while D_f^+ and D_f^- denote the positive and the negative parts, respectively, of the function D_f defined in Lemma 2.20. Moreover, the resulting map $b_\pi: \text{Lip}_b(X, \tau, d) \rightarrow L^q(m)$ belongs to $\text{Der}_q^q(\mathbb{X})$ and it holds that

$$(5.2) \quad |b_\pi| \leq h_\pi, \quad \text{div}(b_\pi) = \frac{d(\hat{e}_0)_\# \pi}{dm} - \frac{d(\hat{e}_1)_\# \pi}{dm}.$$

Proof. First of all, observe that $D_f^\pm \hat{\pi}$ are Radon measures because D_f^\pm is Borel $\hat{\pi}$ -measurable (by Corollary 2.20) and $\hat{\pi}$ is a Radon measure. Since \hat{e} is universally Lusin measurable by Lemma 2.19, we have that $\hat{e}_\#(D_f^\pm \hat{\pi}) \in \mathcal{M}_+(X)$. Given any $f, g \in \text{Lip}_b(X, \tau, d)$ with $g \geq 0$, we can estimate

$$\begin{aligned} \int g d\hat{e}_\#(D_f^\pm \hat{\pi}) &= \int \int_0^1 g(R_\gamma(t)) D_f^\pm(\gamma, t) dt d\pi(\gamma) \\ &\stackrel{(2.23)}{\leq} \int \int_0^1 \ell(\gamma)(g \text{lip}_d(f))(R_\gamma(t)) dt d\pi(\gamma) \\ &= \int \left(\int_\gamma g \text{lip}_d(f) \right) d\pi(\gamma) = \int g \text{lip}_d(f) d\mu_\pi = \int g \text{lip}_d(f) h_\pi dm. \end{aligned}$$

By the arbitrariness of g , we deduce that $\hat{e}_\#(D_f^\pm \hat{\pi}) \ll m$ and that $b_\pi(f) := \frac{d\hat{e}_\#(D_f^+ \hat{\pi})}{dm} - \frac{d\hat{e}_\#(D_f^- \hat{\pi})}{dm}$ satisfies $|b_\pi(f)| \leq 2 \text{lip}_d(f) h_\pi$, so that $b_\pi(f) \in L^q(m)$. By (2.22), for every $f, g \in \text{Lip}_b(X, \tau, d)$, $\alpha, \beta \in \mathbb{R}$ and $\gamma \in \text{RA}(X, d)$ we have that

$$\begin{aligned} D_{\alpha f + \beta g}(\gamma, t) &= \alpha D_f(\gamma, t) + \beta D_g(\gamma, t), \\ D_{fg}(\gamma, t) &= D_f(\gamma, t)g(R_\gamma(t)) + D_g(\gamma, t)f(R_\gamma(t)) \end{aligned}$$

hold for \mathcal{L}_1 -a.e. $t \in [0, 1]$. In particular, $D_{\alpha f + \beta g} = \alpha D_f + \beta D_g$ and $D_{fg} = g \circ \hat{e} D_f + f \circ \hat{e} D_g$ are verified in the $\hat{\pi}$ -a.e. sense. It follows that

$$\begin{aligned} b_{\pi}(\alpha f + \beta g) &= \frac{d\hat{e}_{\#}((\alpha D_f + \beta D_g)\hat{\pi})}{d\mathbf{m}} = \alpha \frac{d\hat{e}_{\#}(D_f\hat{\pi})}{d\mathbf{m}} + \beta \frac{d\hat{e}_{\#}(D_g\hat{\pi})}{d\mathbf{m}} \\ &= \alpha b_{\pi}(f) + \beta b_{\pi}(g), \\ b_{\pi}(fg) &= \frac{d\hat{e}_{\#}((g \circ \hat{e} D_f)\hat{\pi})}{d\mathbf{m}} + \frac{d\hat{e}_{\#}((f \circ \hat{e} D_g)\hat{\pi})}{d\mathbf{m}} \\ &= \frac{d(g \hat{e}_{\#}(D_f\hat{\pi}))}{d\mathbf{m}} + \frac{d(f \hat{e}_{\#}(D_g\hat{\pi}))}{d\mathbf{m}} = b_{\pi}(f)g + b_{\pi}(g)f. \end{aligned}$$

Hence, $b_{\pi}: \text{Lip}_b(X, \tau, \mathbf{d}) \rightarrow L^q(\mathbf{m})$ is a linear operator satisfying the Leibniz rule, thus it is a Lipschitz derivation on \mathbb{X} . Given any $f, g \in \text{Lip}_b(X, \tau, \mathbf{d})$ with $g \geq 0$, we can now estimate

$$\begin{aligned} \left| \int g b_{\pi}(f) d\mathbf{m} \right| &= \left| \iint_0^1 g(R_{\gamma}(t)) D_f(\gamma, t) dt d\pi(\gamma) \right| \\ &\leq \iint_0^1 g(R_{\gamma}(t)) |D_f(\gamma, t)| dt d\pi(\gamma) \\ &\stackrel{(2.23)}{\leq} \iint_0^1 \ell(\gamma)(g \text{lip}_d(f))(R_{\gamma}(t)) dt d\pi(\gamma) = \int g \text{lip}_d(f) h_{\pi} d\mathbf{m}, \end{aligned}$$

so that $|b_{\pi}(f)| \leq \text{lip}_d(f) h_{\pi}$ for every $f \in \text{Lip}_b(X, \tau, \mathbf{d})$. Therefore, $b_{\pi} \in \text{Der}^q(\mathbb{X})$ and $|b_{\pi}| \leq h_{\pi}$. Moreover, for any $f \in \text{Lip}_b(X, \tau, \mathbf{d})$ we can compute

$$\begin{aligned} \int b_{\pi}(f) d\mathbf{m} &= \int D_f d\hat{\pi} \stackrel{(2.22)}{=} \iint_0^1 (f \circ R_{\gamma})'(t) dt d\pi(\gamma) = \int f(\gamma_1) - f(\gamma_0) d\pi(\gamma) \\ &= - \int f \left(\frac{d(\hat{e}_0)_{\#}\pi}{d\mathbf{m}} - \frac{d(\hat{e}_1)_{\#}\pi}{d\mathbf{m}} \right) d\mathbf{m}, \end{aligned}$$

which shows that $b_{\pi} \in \text{Der}_q^q(\mathbb{X})$ and $\text{div}(b_{\pi}) = \frac{d(\hat{e}_0)_{\#}\pi}{d\mathbf{m}} - \frac{d(\hat{e}_1)_{\#}\pi}{d\mathbf{m}}$. The proof is complete. \square

As a consequence of Proposition 5.8, the space $W^{1,p}(\mathbb{X})$ is always contained in $B^{1,p}(\mathbb{X})$:

Theorem 5.9. ($W^{1,p} \subseteq B^{1,p}$) Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space and $p \in (1, \infty)$. Then

$$W^{1,p}(\mathbb{X}) \subseteq B^{1,p}(\mathbb{X}).$$

Moreover, it holds that $|Df|_B \leq |Df|$ for every $f \in W^{1,p}(\mathbb{X})$.

Proof. Let $f \in W^{1,p}(\mathbb{X})$ be given. Fix some τ -Borel representative $G_f: X \rightarrow [0, +\infty)$ of $|Df|$. For any $\pi \in \mathcal{T}_q(\mathbb{X})$ (where $q \in (1, \infty)$ denotes the conjugate exponent of p), the derivation $b_{\pi} \in \text{Der}_q^q(\mathbb{X})$ given by Proposition 5.8 satisfies

$$\begin{aligned} \int f(\gamma_1) - f(\gamma_0) d\pi(\gamma) &\stackrel{(5.2)}{=} - \int f \text{div}(b_{\pi}) d\mathbf{m} = \int L_f(b_{\pi}) d\mathbf{m} \\ &\leq \int |Df| |b_{\pi}| d\mathbf{m} \stackrel{(5.2)}{\leq} \int G_f h_{\pi} d\mathbf{m}. \end{aligned}$$

By virtue of Lemma 2.32, we deduce that G_f is a \mathcal{T}_q -weak upper gradient of f . Therefore, we proved that $f \in B^{1,p}(\mathbb{X})$ and $|Df|_B \leq |Df|$, whence the statement follows. \square

5.4. $W^{1,p}$ as a dual space. In this section, our aim is to provide a new description of some *isometric predual* of the metric Sobolev space, and the formulation of Sobolev space in terms of derivations serves this purpose very well. More precisely, in Theorem 5.10 we give an explicit construction of a Banach space whose dual is isometrically isomorphic to $W^{1,p}(\mathbb{X})$. The existence and the construction of an isometric predual of the space $H^{1,p}(\mathbb{X})$ were previously obtained by Ambrosio and Savaré in [9, Corollary 3.10].

In the proof of Theorem 5.10, we use some facts in Functional Analysis that we collect below:

- If \mathbb{B}, \mathbb{V} are Banach spaces and $q \in (1, \infty)$, the product vector space $\mathbb{B} \times \mathbb{V}$ is a Banach space if endowed with the q -norm

$$\|(v, w)\|_q := (\|v\|_{\mathbb{B}}^q + \|w\|_{\mathbb{V}}^q)^{1/q} \quad \text{for every } (v, w) \in \mathbb{B} \times \mathbb{V}.$$

We write $\mathbb{B} \times_q \mathbb{V}$ to indicate the Banach space $(\mathbb{B} \times \mathbb{V}, \|\cdot\|_q)$.

- If $p, q \in (1, \infty)$ are conjugate exponents, then $(\mathbb{B} \times_q \mathbb{V})'$ and $\mathbb{B}' \times_p \mathbb{V}'$ are isometrically isomorphic. The canonical duality pairing between $\mathbb{B}' \times_p \mathbb{V}'$ and $\mathbb{B} \times_q \mathbb{V}$ is given by

$$\langle (\omega, \eta), (v, w) \rangle = \langle \omega, v \rangle + \langle \eta, w \rangle \quad \text{for every } (\omega, \eta) \in \mathbb{B}' \times \mathbb{V}' \text{ and } (v, w) \in \mathbb{B} \times \mathbb{V}.$$

- The *annihilator* \mathbb{W}^\perp of a closed vector subspace \mathbb{W} of \mathbb{B} is defined as

$$\mathbb{W}^\perp := \{\omega \in \mathbb{B}' \mid \langle \omega, v \rangle = 0 \text{ for every } v \in \mathbb{W}\}.$$

Then \mathbb{W}^\perp is a closed vector subspace of \mathbb{B}' . Moreover, \mathbb{W}^\perp is isometrically isomorphic to the dual $(\mathbb{B}/\mathbb{W})'$ of the quotient Banach space \mathbb{B}/\mathbb{W} .

Theorem 5.10. (A predual of $W^{1,p}$) *Let $\mathbb{X} = (X, \tau, \mathbf{d}, \mathbf{m})$ be an e.m.t.m. space. Let $p, q \in (1, \infty)$ be conjugate exponents. We define the closed vector subspace $\mathbb{B}_{\mathbb{X},q}$ of $L^q(\mathbf{m}) \times_q L_{\text{Lip}}^q(T\mathbb{X})$ as the closure of its vector subspace*

$$\{(g, b) \in L^q(\mathbf{m}) \times \text{Der}_q^q(\mathbb{X}) \mid g = \text{div}(b)\}.$$

Then $W^{1,p}(\mathbb{X})$ is isometrically isomorphic to the dual of the quotient $(L^q(\mathbf{m}) \times_q L_{\text{Lip}}^q(T\mathbb{X}))/\mathbb{B}_{\mathbb{X},q}$.

Proof. For any $f \in W^{1,p}(\mathbb{X})$, we define $\mathfrak{L}_f := \text{INT}_{L_{\text{Lip}}^q(T\mathbb{X})}(L_f) \in L_{\text{Lip}}^q(T\mathbb{X})'$, so that accordingly

$$(5.3) \quad \|\mathfrak{L}_f\|_{L_{\text{Lip}}^q(T\mathbb{X})'} = \|L_f\|_{L_{\text{Lip}}^q(T\mathbb{X})}^* = \|L_f\|_{L^p(\mathbf{m})} = \|Df\|_{L^p(\mathbf{m})}.$$

Clearly, $W^{1,p}(\mathbb{X}) \ni f \mapsto \mathfrak{L}_f \in L_{\text{Lip}}^q(T\mathbb{X})'$ is linear. Define $\phi: W^{1,p}(\mathbb{X}) \rightarrow L^p(\mathbf{m}) \times_p L_{\text{Lip}}^q(T\mathbb{X})'$ as

$$\phi(f) := (f, \mathfrak{L}_f) \in L^p(\mathbf{m}) \times L_{\text{Lip}}^q(T\mathbb{X})' \quad \text{for every } f \in W^{1,p}(\mathbb{X}).$$

It follows from (5.3) and the definition of $\|\cdot\|_{W^{1,p}(\mathbb{X})}$ that ϕ is a linear isometry. We claim that

$$(5.4) \quad \phi(W^{1,p}(\mathbb{X})) = \mathbb{B}_{\mathbb{X},q}^\perp,$$

where we are identifying $\mathbb{B}_{\mathbb{X},q}^\perp \subseteq (L^q(\mathbf{m}) \times_q L_{\text{Lip}}^q(T\mathbb{X}))'$ with a subspace of $L^p(\mathbf{m}) \times_p L_{\text{Lip}}^q(T\mathbb{X})'$. To prove $\phi(W^{1,p}(\mathbb{X})) \subseteq \mathbb{B}_{\mathbb{X},q}^\perp$, it suffices to observe that for any $f \in W^{1,p}(\mathbb{X})$ and $b \in \text{Der}_q^q(\mathbb{X})$ it holds

$$\langle \phi(f), (\text{div}(b), b) \rangle = \langle f, \text{div}(b) \rangle + \mathfrak{L}_f(b) = \int f \text{div}(b) \, d\mathbf{m} + \int L_f(b) \, d\mathbf{m} = 0.$$

We now prove the converse inclusion $\mathbb{B}_{\mathbb{X},q}^\perp \subseteq \phi(W^{1,p}(\mathbb{X}))$. Fix $(f, \mathfrak{L}) \in \mathbb{B}_{\mathbb{X},q}^\perp \subseteq L^p(\mathfrak{m}) \times_p L_{\text{Lip}}^q(T\mathbb{X})'$. Letting $L := \text{INT}_{L_{\text{Lip}}^q(T\mathbb{X})}^{-1}(\mathfrak{L}) \in L_{\text{Lip}}^q(T\mathbb{X})^*$, we have in particular that $L|_{\text{Der}_q^q(\mathbb{X})}: \text{Der}_q^q(\mathbb{X}) \rightarrow L^1(\mathfrak{m})$ is a linear operator satisfying $|L(b)| \leq |L||b|$ for every $b \in \text{Der}_q^q(\mathbb{X})$, for some function $|L| \in L^p(\mathfrak{m})^+$ such that $\|L\|_{L^p(\mathfrak{m})} = \|\mathfrak{L}\|_{L_{\text{Lip}}^q(T\mathbb{X})'}$. Moreover, the $L^\infty(\mathfrak{m})$ -linearity of L implies $L(hb) = hL(b)$ for every $h \in \text{Lip}_b(X, \tau, \mathfrak{d})$ and $b \in \text{Der}_q^q(\mathbb{X})$, and using that $(\text{div}(b), b) \in \mathbb{B}_{\mathbb{X},q}$ we deduce that

$$\int f \text{div}(b) \, d\mathfrak{m} + \int L(b) \, d\mathfrak{m} = \langle f, \text{div}(b) \rangle + \mathfrak{L}(b) = \langle (f, \mathfrak{L}), (\text{div}(b), b) \rangle = 0,$$

so that $\int L(b) \, d\mathfrak{m} = -\int f \text{div}(b) \, d\mathfrak{m}$. All in all, we proved that $f \in W^{1,p}(\mathbb{X})$ and $L_f = L$, which gives $(f, \mathfrak{L}) = (f, \mathfrak{L}_f) = \phi(f) \in \phi(W^{1,p}(\mathbb{X}))$. Consequently, the claimed identity (5.4) is proved. Writing \cong to indicate that two Banach spaces are isometrically isomorphic, we then conclude that

$$W^{1,p}(\mathbb{X}) \cong \phi(W^{1,p}(\mathbb{X})) \cong \mathbb{B}_{\mathbb{X},q}^\perp \cong ((L^q(\mathfrak{m}) \times_q L_{\text{Lip}}^q(T\mathbb{X}))/\mathbb{B}_{\mathbb{X},q})',$$

proving the statement. \square

Appendix A. Ultrafilters and ultralimits

We collect here some definitions and results concerning ultrafilters and ultralimits, which we use in the proof of Theorem 5.4. See e.g. [34] or [19, Chapter 10] for more on these topics.

Let ω be a *filter* on \mathbb{N} , i.e. a collection of subsets of \mathbb{N} that is closed under supersets and finite intersections. Then we say that ω is an *ultrafilter* provided it is a maximal filter with respect to inclusion, or equivalently if for any subset $A \subseteq \mathbb{N}$ we have that either $A \in \omega$ or $\mathbb{N} \setminus A \in \omega$. Moreover, we say that ω is *non-principal* provided it does not contain any finite subset of \mathbb{N} . The existence of non-principal ultrafilters on \mathbb{N} follows e.g. from the so-called *Ultrafilter Lemma* [19, Lemma 10.18], which is (in ZF) strictly weaker than the Axiom of Choice [48, 31]. It holds that an ultrafilter ω on \mathbb{N} is non-principal if and only if it contains the *Fréchet filter* (i.e. the collection of all cofinite subsets of \mathbb{N}).

Let ω be a non-principal ultrafilter on \mathbb{N} , (X, τ) a Hausdorff topological space and $(x_n)_{n \in \mathbb{N}} \subseteq X$ a given sequence. Then we say that an element $\omega\text{-}\lim_n x_n \in X$ is the *ultralimit* of $(x_n)_n$ provided

$$\{n \in \mathbb{N} \mid x_n \in U\} \in \omega \quad \text{for every } U \in \tau \text{ with } \omega\text{-}\lim_n x_n \in U.$$

The Hausdorff assumption on τ ensures that if the ultralimit exists, then it is unique. The existence of the ultralimits of all sequences in (X, τ) is guaranteed when the topology τ is compact.

We now discuss technical results about ultralimits, which we prove for the reader's convenience.

Lemma A.1. *Let ω be a non-principal ultrafilter on \mathbb{N} . Let X_1, \dots, X_k, Y be Hausdorff topological spaces, for some $k \in \mathbb{N}$ with $k \geq 1$. Let $\varphi: X_1 \times \dots \times X_k \rightarrow Y$ be a continuous map, where the domain $X_1 \times \dots \times X_k$ is endowed with the product topology. For any $i = 1, \dots, k$, let $(x_i^n)_{n \in \mathbb{N}} \subseteq X_i$ be a sequence whose ultralimit $x_i := \omega\text{-}\lim_n x_i^n \in X_i$ exists. Then it holds that*

$$(A.1) \quad \exists \omega\text{-}\lim_n \varphi(x_1^n, \dots, x_k^n) = \varphi(x_1, \dots, x_k) \in Y.$$

Proof. Fix a neighbourhood U of $\varphi(x_1, \dots, x_k)$ in Y . Since φ is continuous, $\varphi^{-1}(U)$ is a neighbourhood of (x_1, \dots, x_k) . Thus, for any $i = 1, \dots, k$ there exists a neighbourhood U_i of x_i in X_i such that $U_1 \times \dots \times U_k \subseteq \varphi^{-1}(U)$. Recalling that $x_i = \omega\text{-}\lim_n x_i^n$ for all $i = 1, \dots, k$, we get that

$$\omega \ni \bigcap_{i=1}^k \{n \in \mathbb{N} \mid x_i^n \in U_i\} \subseteq \{n \in \mathbb{N} \mid \varphi(x_1^n, \dots, x_k^n) \in U\}$$

and thus $\{n \in \mathbb{N} \mid \varphi(x_1^n, \dots, x_k^n) \in U\} \in \omega$. Thanks to the arbitrariness of U , (A.1) is proved. \square

Remark A.2. Let (X, Σ, \mathbf{m}) be a finite measure space. Let $h \in L^1(\mathbf{m})^+$ be given. Then

$$(A.2) \quad \mathcal{F}_h := \{f \in L^1(\mathbf{m}) \mid |f| \leq h\} \quad \text{is a weakly compact subset of } L^1(\mathbf{m}).$$

The validity of this property follows from the Dunford–Pettis theorem and the fact that \mathcal{F}_h is a weakly closed subset of $L^1(\mathbf{m})$. \blacksquare

Lemma A.3. Let ω be a non-principal ultrafilter on \mathbb{N} . Let (X, Σ, \mathbf{m}) be a finite measure space. Assume that $(f_n)_n \subseteq L^1(\mathbf{m})$ and $h \in L^1(\mathbf{m})^+$ satisfy $|f_n| \leq h$ for every $n \in \mathbb{N}$. Then the weak ultralimits $f := \omega\text{-}\lim_n f_n \in L^1(\mathbf{m})$ and $\omega\text{-}\lim_n |f_n| \in L^1(\mathbf{m})$ exist. Moreover, it holds that

$$(A.3) \quad |f| \leq \omega\text{-}\lim_n |f_n| \leq h.$$

Proof. The existence of the ultralimits $\omega\text{-}\lim_n f_n$ and $\omega\text{-}\lim_n |f_n|$ in the weak topology of $L^1(\mathbf{m})$ follows from Remark A.2. For any $g \in L^\infty(\mathbf{m})^+$, we consider the functional $\varphi_g: L^1(\mathbf{m}) \rightarrow \mathbb{R}$ given by $\varphi_g(\tilde{f}) := \int \tilde{f}g \, d\mathbf{m}$ for every $\tilde{f} \in L^1(\mathbf{m})$, which is weakly continuous. Hence, Lemma A.1 yields

$$\begin{aligned} \left| \int f g \, d\mathbf{m} \right| &= |\varphi_g(f)| = \left| \omega\text{-}\lim_n \varphi_g(f_n) \right| = \omega\text{-}\lim_n |\varphi_g(f_n)| \\ &\leq \omega\text{-}\lim_n \varphi_g(|f_n|) = \varphi_g(\omega\text{-}\lim_n |f_n|) \end{aligned}$$

and $\int (\omega\text{-}\lim_n |f_n|)g \, d\mathbf{m} = \omega\text{-}\lim_n \varphi_g(|f_n|) \leq \varphi_g(h) = \int h g \, d\mathbf{m}$, whence the claimed inequalities in (A.3) follow thanks to the arbitrariness of $g \in L^\infty(\mathbf{m})^+$. \square

Appendix B. Tools in Convex Analysis

Let \mathbb{B}, \mathbb{V} be Banach spaces. Then by an *unbounded operator* $A: \mathbb{B} \rightarrow \mathbb{V}$ we mean a vector subspace $D(A)$ of \mathbb{B} (called the *domain* of A) together with a linear operator $A: D(A) \rightarrow \mathbb{V}$. When A is *densely defined* (i.e. the set $D(A)$ is dense in \mathbb{B}), it is possible to define its *adjoint operator* $A^*: \mathbb{V}' \rightarrow \mathbb{B}'$, which is characterised by

$$\begin{aligned} D(A^*) &:= \{\eta \in \mathbb{V}' \mid \mathbb{B} \ni v \mapsto \langle \eta, A(v) \rangle \in \mathbb{R} \text{ is continuous}\}, \\ \langle \eta, A(v) \rangle &= \langle A^*(\eta), v \rangle \quad \text{for every } \eta \in D(A^*) \text{ and } v \in D(A). \end{aligned}$$

See e.g. [40, Chapter 5] for more on unbounded operators.

Given any function $f: \mathbb{B} \rightarrow [-\infty, +\infty]$, we denote by $f^*: \mathbb{B}' \rightarrow [-\infty, +\infty]$ its *Fenchel conjugate*, which is defined as

$$f^*(\omega) := \sup \{ \langle \omega, v \rangle - f(v) \mid v \in \mathbb{B} \} \quad \text{for every } \omega \in \mathbb{B}'.$$

Assuming \mathbb{B} is reflexive, we have (unless the function f is identically equal to $+\infty$ or identically equal to $-\infty$) that the *Fenchel biconjugate* $f^{**} := (f^*)^*: \mathbb{B} \rightarrow [-\infty, +\infty]$

coincides with f if and only if f is convex and lower semicontinuous. This follows from the *Fenchel–Moreau theorem*. Furthermore, if $p, q \in (1, \infty)$ are conjugate exponents, then it is straightforward to check that

$$(B.1) \quad \left(\frac{1}{p} \|\cdot\|_{\mathbb{B}}^p \right)^* = \frac{1}{q} \|\cdot\|_{\mathbb{B}'}^q.$$

See e.g. [41] for a thorough discussion on Fenchel conjugates.

In Theorem 5.4 we use the following result, for whose proof we refer to [13, Theorem 5.1].

Theorem B.1. *Let \mathbb{B} and \mathbb{V} be Banach spaces. Let $A: \mathbb{B} \rightarrow \mathbb{V}$ be a densely-defined unbounded operator. Let $\phi: \mathbb{V} \rightarrow \mathbb{R}$ be a convex function that is continuous at some point of $A(D(A))$. Then*

$$(\phi \circ A)^*(\omega) = \inf \{ \phi^*(\eta) \mid \eta \in D(A^*), A^*(\eta) = \omega \} \quad \text{for every } \omega \in \mathbb{B}',$$

where we adopt the convention that $(\phi \circ A)(v) := +\infty$ for every $v \in \mathbb{B} \setminus D(A)$.

References

- [1] ALBEVERIO, S., Y. G. KONDRATIEV, and M. RÖCKNER: Analysis and geometry on configuration spaces. - J. Funct. Anal. 154:2, 1998, 444–500.
- [2] ALBIAC, F., and N. J. KALTON: Topics in Banach space theory. - Springer, New York, 2006.
- [3] AMBROSIO, L., S. DI MARINO, and G. SAVARÉ: On the duality between p -modulus and probability measures. - J. Eur. Math. Soc. (JEMS) 17:8, 2015, 1817–1853.
- [4] AMBROSIO, L., M. ERBAR, and G. SAVARÉ: Optimal transport, Cheeger energies and contractivity of dynamic transport distances in extended spaces. - Nonlinear Anal. 137, 2016, 77–134.
- [5] AMBROSIO, L., N. GIGLI, and G. SAVARÉ: Density of Lipschitz functions and equivalence of weak gradients in metric measure spaces. - Rev. Mat. Iberoam. 29:3, 2013, 969–996.
- [6] AMBROSIO, L., N. GIGLI, and G. SAVARÉ: Calculus and heat flow in metric measure spaces and applications to spaces with Ricci bounds from below. - Invent. Math. 195:2, 2014, 289–391.
- [7] AMBROSIO, L., T. IKONEN, D. LUČIĆ, and E. PASQUALETTO: Metric Sobolev spaces I: equivalence of definitions. - Milan J. Math. 92:2, 2024, 255–347.
- [8] AMBROSIO, L., T. IKONEN, D. LUČIĆ, and E. PASQUALETTO: Metric Sobolev spaces II: dual energies and divergence measures. - ArXiv preprint, arXiv:2510.12424, 2025.
- [9] AMBROSIO, L., and G. SAVARÉ: Duality properties of metric Sobolev spaces and capacity. - Math. Eng. 3:1, 2021, Paper No. 1, 31.
- [10] BESSAGA, C., and A. PEŁCZYŃSKI: On bases and unconditional convergence of series in Banach spaces. - Studia Math. 17:2, 1958, 151–164.
- [11] BOGACHEV, V. I.: Measure theory. Vol. I, II. - Springer-Verlag, Berlin, 2007.
- [12] BOGACHEV, V. I.: Gaussian measures. - Math. Surveys Monogr. 62, Amer. Math. Soc., 2015.
- [13] BOUCHITTÉ, G., G. BUTTAZZO, and P. SEPPECHER: Energies with respect to a measure and applications to low dimensional structures. - Calc. Var. Partial Differential Equations 5, 1997, 37–54.
- [14] BOURBAKI, N.: General topology. Part 1. - Hermann, Paris, 1966.
- [15] BOURBAKI, N.: General topology. Part 2. - Hermann, Paris, 1966.
- [16] CHEEGER, J.: Differentiability of Lipschitz functions on metric measure spaces. - Geom. Funct. Anal. 9:3, 1999, 428–517.
- [17] DI MARINO, S.: Recent advances on BV and Sobolev spaces in metric measure spaces. - PhD thesis, Scuola Normale Superiore (Pisa), 2014.

- [18] DI MARINO, S.: Sobolev and BV spaces on metric measure spaces via derivations and integration by parts. - ArXiv preprint, arXiv:1409.5620, 2014.
- [19] DRUȚU, C., and M. KAPOVICH: Geometric group theory. - Colloquium Publications 63, Amer. Math. Soc., 2018.
- [20] ERIKSSON-BIQUE, S.: Density of Lipschitz functions in energy. - Calc. Var. Partial Differential Equations 62:2, 2023, Paper No. 60.
- [21] FUGLEDE, B.: Extremal length and functional completion. - Acta Math. 98, 1957, 171–219.
- [22] GIGLI, N.: Lecture notes on differential calculus on RCD spaces. - Publ. RIMS Kyoto Univ. 54, 2018.
- [23] GIGLI, N.: Nonsmooth differential geometry - an approach tailored for spaces with Ricci curvature bounded from below. - Mem. Amer. Math. Soc. 251:1196, 2018.
- [24] GIGLI, N., and E. PASQUALETTO: Differential structure associated to axiomatic Sobolev spaces. - Expo. Math. 38:4, 2020, 480–495.
- [25] GIGLI, N., and E. PASQUALETTO: Lectures on nonsmooth differential geometry. - SISSA Springer Series 2, 2020.
- [26] GUO, T. X.: The theory of probabilistic metric spaces with applications to random functional analysis. - Master's thesis, Xi'an Jiaotong University (China), 1989.
- [27] GUO, T. X.: Random metric theory and its applications. - PhD thesis, Xi'an Jiaotong University (China), 1992.
- [28] GUO, T. X.: Recent progress in random metric theory and its applications to conditional risk measures. - Sci. China Math. 54, 2011, 633–660.
- [29] GUO, T. X., X. MU, and Q. TU: Relations among the notions of various kinds of stability and applications. - Banach J. Math. Anal. 18, 2024.
- [30] HAJLASZ, P.: Sobolev spaces on an arbitrary metric space. - Potential Anal. 5, 1996, 403–415.
- [31] HALPERN, J.: The independence of the axiom of choice from the Boolean prime ideal theorem. - Fund. Math. 55, 1964, 57–66.
- [32] HAYDON, R., M. LEVY, and Y. RAYNAUD: Randomly normed spaces. - Travaux en Cours 41, Hermann, Paris, 1991.
- [33] HEINONEN, J., and P. KOSKELA: Quasiconformal maps in metric spaces with controlled geometry. - Acta Math. 181:1, 1998, 1–61.
- [34] JECH, T.: Set theory. - Academic Press, 1978.
- [35] KELLEY, J. L.: General topology. - Grad. Texts in Math. 27, Springer New York, 1st edition, 1975.
- [36] KOSKELA, P., and P. MACMANUS: Quasiconformal mappings and Sobolev spaces. - Studia Math. 131:1, 1998, 1–17.
- [37] LUČIĆ, D., and E. PASQUALETTO: Yet another proof of the density in energy of Lipschitz functions. - Manuscripta Math. 175, 2024, 421–438.
- [38] LUČIĆ, D., and E. PASQUALETTO: An axiomatic theory of normed modules via Riesz spaces. - Q. J. Math. 75, 2024, 1429–1479.
- [39] MATOUŠKOVÁ, E.: Extensions of continuous and Lipschitz functions. - Canad. Math. Bull. 43:2, 2000, 208–217.
- [40] PEDERSEN, G. K.: Analysis now. - Grad. Texts in Math. 118, Springer-Verlag, 1989.
- [41] ROCKAFELLAR, R. T.: Conjugate duality and optimization. - Society for Industrial and Applied Mathematics, Philadelphia, 1974.
- [42] SAVARÉ, G.: Sobolev spaces in extended metric-measure spaces. - In: New trends on analysis and geometry in metric spaces, Lecture Notes in Math. 2296, Springer, Cham, 2022, 117–276.

- [43] SCHIOPPA, A.: On the relationship between derivations and measurable differentiable structures. - *Ann. Acad. Sci. Fenn. Math.* 39, 2014, 275–304.
- [44] SCHIOPPA, A.: Derivations and Alberti representations. - *Adv. Math.* 293, 2016, 436–528, 2016.
- [45] SCHIOPPA, A.: Metric currents and Alberti representations. - *J. Funct. Anal.* 271:11, 2016, 3007–3081.
- [46] SCHWARTZ, L.: Radon measures on arbitrary topological spaces and cylindrical measures. - *Studies in Mathematics*, Tata Institute of Fundamental Research, 1973.
- [47] SHANMUGALINGAM, N.: Newtonian spaces: an extension of Sobolev spaces to metric measure spaces. - *Rev. Mat. Iberoam.* 16:2, 2000, 243–279.
- [48] TARSKI, A.: Une contribution à la théorie de la mesure. - *Fund. Math.* 15, 1930, 42–50.
- [49] WEAVER, N.: Lipschitz algebras and derivations. II. Exterior differentiation. - *J. Funct. Anal.* 178:1, 2000, 64–112.
- [50] WEAVER, N.: Lipschitz algebras. - World Scientific, 2nd edition, 2018.

Received 14 July 2025 • Revision received 12 January 2026 • Accepted 13 January 2026

Published online 28 January 2026

Enrico Pasqualetto
University of Jyväskylä
Department of Mathematics and Statistics
P.O. Box 35 (MaD)
FI-40014 University of Jyväskylä
enrico.e.pasqualetto@jyu.fi

Janne Taipalus
University of Jyväskylä
Department of Mathematics and Statistics
P.O. Box 35 (MaD)
FI-40014 University of Jyväskylä
janne.m.m.taipalus@jyu.fi